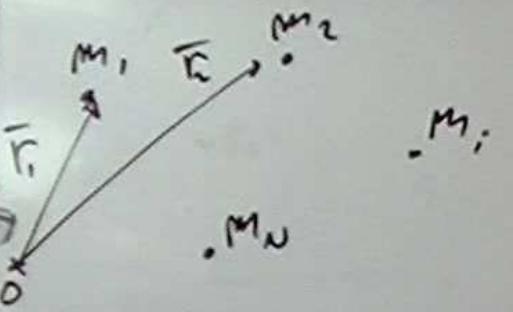
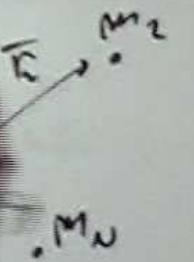


PROBLEMA DE N CUERPOS

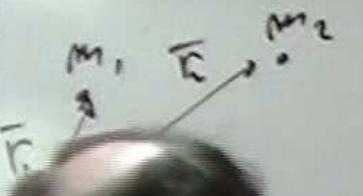
$$m_1 \ddot{\vec{r}}_1 = - \vec{F}$$

PROBLEMA DE N CUERPOS

$$\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

$$\vec{F}_i = -G^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3}$$



PROBLEMA DE N CUERPOS m_i

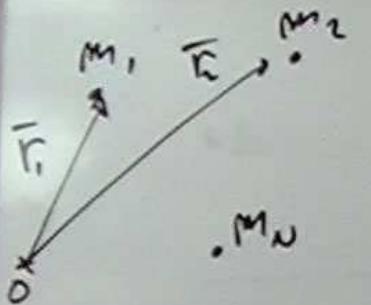
$$\bar{r}_{ij} = \bar{r}_i - \bar{r}_j$$

$$-k^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\bar{r}_i - \bar{r}_j)}{r_{ij}^3} \Rightarrow 3N \text{ Eqs. 2c}$$





PROBLEMA DE N CUERPOS



$$\vec{r}_j = \vec{r}_i - \vec{r}_j$$

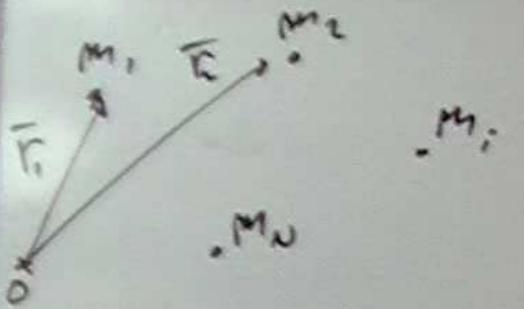
$$m_i \ddot{\vec{r}}_i = -G^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_i^3} \Rightarrow 3N \text{ Eqs. 2c}$$

$$\left. \begin{aligned} \dot{\vec{r}}_i &= \vec{v}_i \\ \dot{\vec{v}}_i &= f_i(\vec{r}_1, \dots, \vec{r}_N) \end{aligned} \right\} 6N \text{ ec.}$$

$$\ddot{\vec{x}} = F(\vec{x})$$



PROBLEMA DE N CUERPOS



$$\vec{r}_{\bar{j}} = \vec{r}_i - \vec{r}_{\bar{j}}$$

$$m_i \ddot{\vec{r}}_i = -G^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3} \Rightarrow 3N \text{ Eqs. 2c}$$

$$\left. \begin{aligned} \dot{\vec{r}}_i &= \vec{v}_i \\ \dot{\vec{v}}_i &= f_i(\vec{r}_1, \dots, \vec{r}_N) \\ \dot{\vec{x}} &= F(\vec{x}) \end{aligned} \right\} 6N \text{ ec.}$$

$$\vec{x} = (x_1, \dots, x_{6N})$$

$$\left\{ \begin{array}{ll} x_i = \text{Posición} & i \leq 3N \\ x_i = \text{Velocid} & i > 3N \end{array} \right.$$

PROBLEMA DE N CUERPOS m_i

$$\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

$$-k^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3} \Rightarrow 3N \text{ Eqs. } 2c$$

} 6N ec.

\vec{r}_1

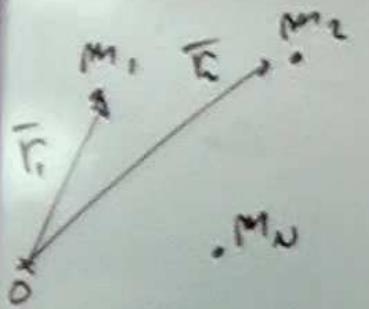
\vec{x}

$$\vec{x} = (x_1, \dots, x_{6N})$$

$$\begin{cases} x_i = \text{Posición} & i \leq 3N \\ x_i = \text{Velocid} & i > 3N \end{cases}$$

$$I_1(x_1, \dots, x_{6N}) = CTG \rightarrow x_{6N} = f(x_1, \dots, x_{6N-1})$$

PROBLEMA DE

 m_i m_N

$$\vec{r}_j = \vec{r}_i - \vec{r}_j$$

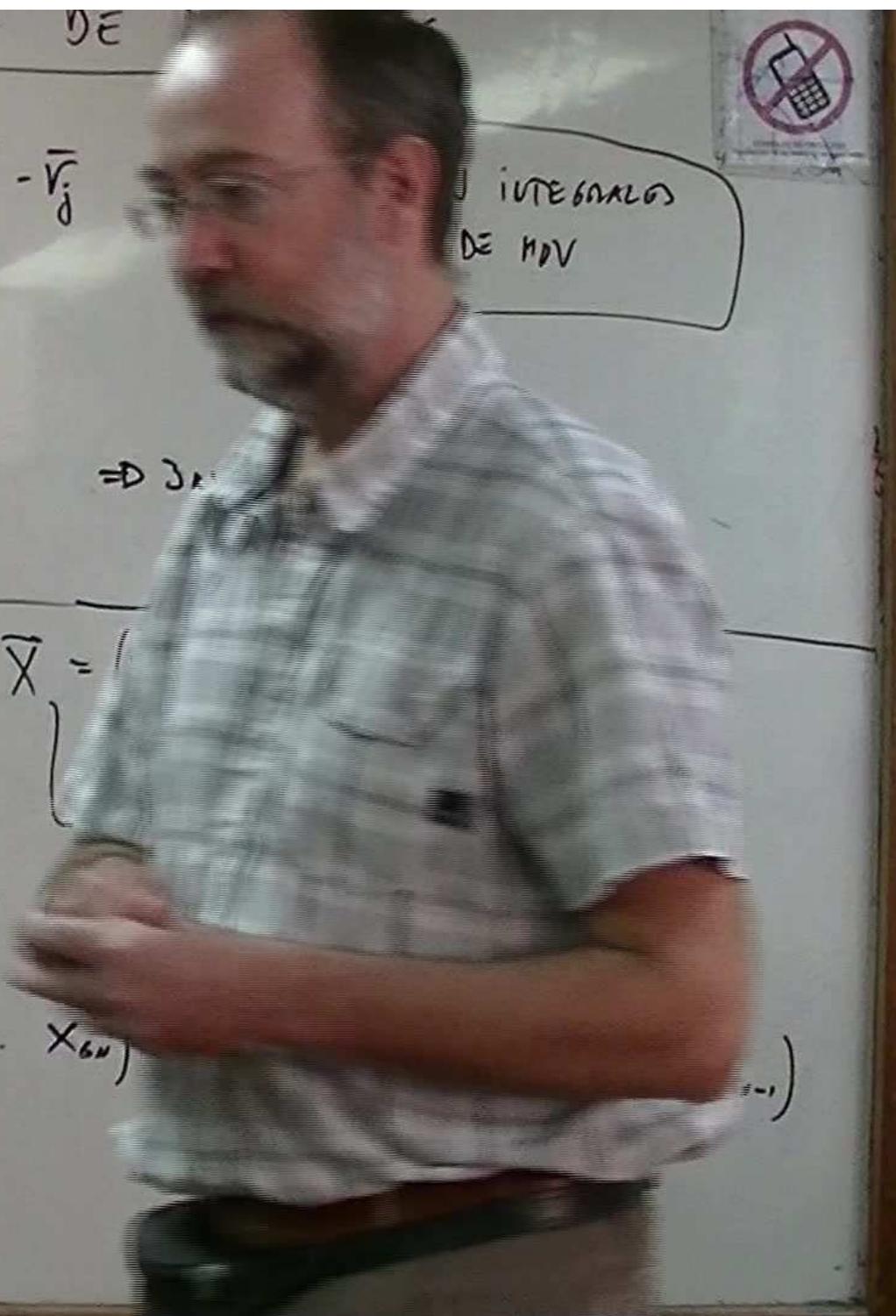
$$m_i \ddot{\vec{r}}_i = -\hbar^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3}$$

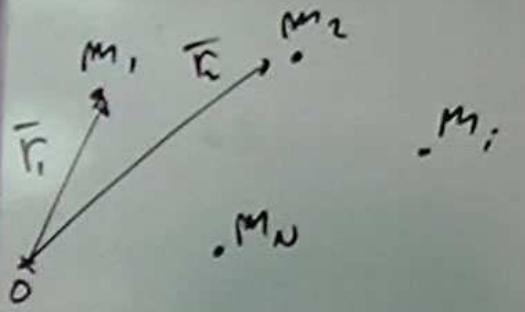
 $\forall i = 1, N$ $\Rightarrow 3N$

$$\left. \begin{aligned} \dot{\vec{r}}_i &= \vec{v}_i \\ \dot{\vec{v}}_i &= f_i(\vec{r}_1, \dots, \vec{r}_N) \end{aligned} \right\} 6N \text{ ec.}$$

$$\dot{\vec{x}} = F(\vec{x})$$

$$I_1(x_1, \dots, x_{6N})$$

INTEGRALS
DE MOL

PROBLEMA DE N CUERPOS

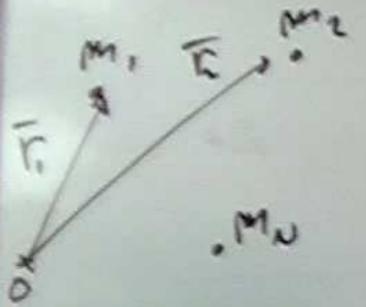
$$m_i \ddot{\vec{r}}_i = -\hbar^2 \sum_{j=1}^N m_i m_j$$

$\forall i = 1, N$

$\Rightarrow 3N \text{ Eqs. de}$

6N integrales
de MV



PROBLEMA DE N CUERPOS

$m_i \vec{r}_i$

$$m_i \ddot{\vec{r}}_i = -\frac{k^2}{r_{ij}^3} \left(\vec{r}_j \right)$$

$\sum_{i=1, N}$

$$\ddot{\vec{r}} = \vec{r}_i - \vec{r}_j$$

6N integrales
de mov

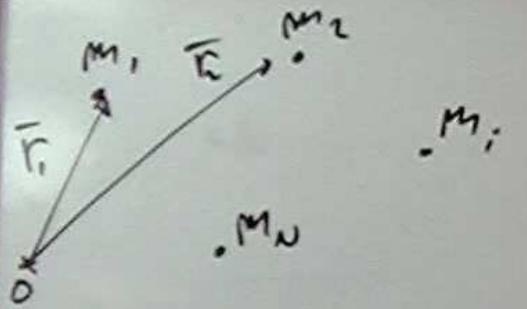
$\Rightarrow 3N$ Ecs. 2c

$$I_i = \text{ctes}$$

$$V_i = \text{ctes}$$

Acciones

T. Gallardo

PROBLEMA DE N CUERPOS

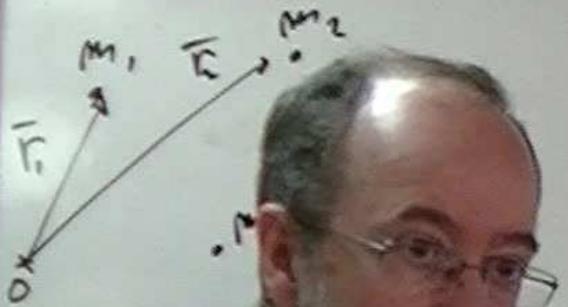
$$\bar{r}_{ij} = \bar{r}_i - \bar{r}_j$$

6N integrales
de Mv

$$m_i \ddot{\bar{r}}_i = -\hbar^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\bar{r}_i - \bar{r}_j)}{r_{ij}^3}$$

$\forall i = 1, N$

$$\sum_{i=1}^N m_i \ddot{\bar{r}}_i =$$

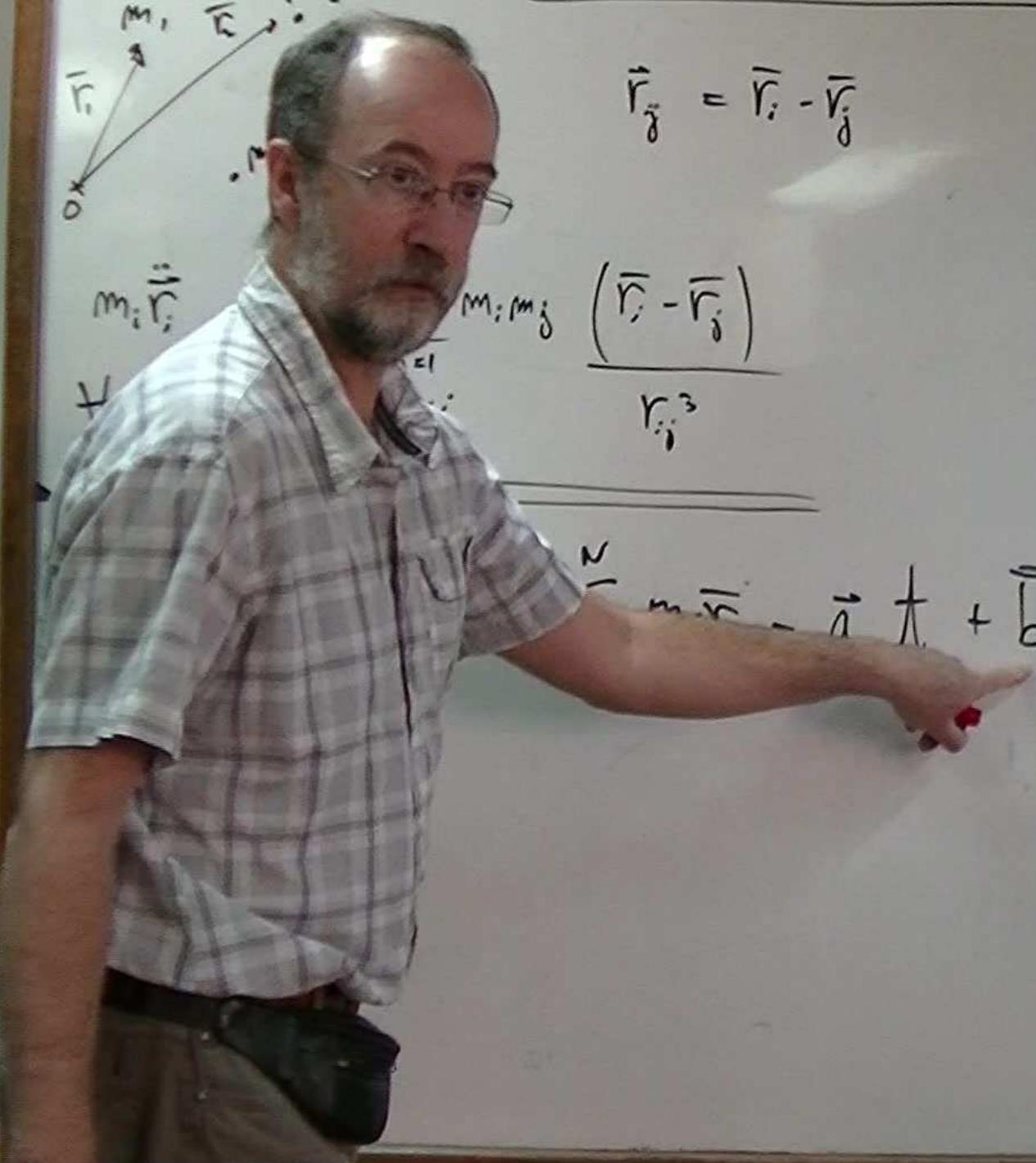
PROBLEMA DE N CUERPOS

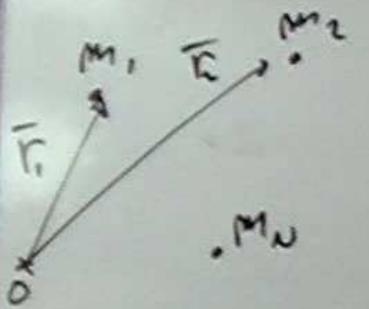
$$\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

$$\frac{m_i m_j}{r_{ij}^3} \left(\vec{r}_i - \vec{r}_j \right)$$

6N integrales
de mov

$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = \vec{F}_{ext} + \vec{b}$$



PROBLEMA DE N CUERPOS m_i \vec{r}_i m_j \vec{r}_j m_{ij}

$$\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

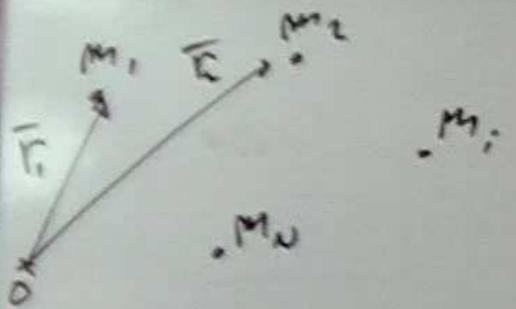
6N integrales
de mov

$$m_i \ddot{\vec{r}}_i = -G^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3}$$

 $\forall i = 1, N$

$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = 0 \Rightarrow \sum_{i=1}^N m_i \vec{r}_i = \vec{a} \cdot \vec{t} + \vec{b} \rightarrow 6 \text{ cons}$$

PROBLEMA DE N CUERPOS



$$\vec{r}_{ij} = \vec{r}_i - \vec{r}_j$$

6N integrales
de mov

$$m_i \ddot{\vec{r}}_i = -\hbar^2 \sum_{\substack{j=1 \\ j \neq i}}^N m_i m_j \frac{(\vec{r}_i - \vec{r}_j)}{r_{ij}^3}$$

$\forall i = 1, N$

$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = 0 \Rightarrow \sum_{i=1}^N m_i \vec{r}_i = \vec{a} \cdot t + \vec{b} \rightarrow 6 \text{ cons}$$

$$m_i \ddot{\vec{r}}_i \wedge \vec{r}_i = \hbar^2 m_i \sum_{\substack{j=1 \\ j \neq i}}^N m_j \vec{r}_i \wedge \vec{r}_j$$

$$\sum_{i=1}^N \boxed{m_i \ddot{\vec{r}}_i \wedge \vec{r}_i} =$$

$$\Rightarrow \sum_{i=1}^n m_i \vec{r}_i \wedge \dot{\vec{r}}_i = \vec{L}_{\text{CG}} \rightarrow 3 \text{ crs}$$



$$\sum_{i=1}^n m_i \ddot{\vec{r}}_i = 0 \Rightarrow \sum_{i=1}^n m_i \vec{r}_i = \vec{a} \cdot t + \vec{b} \rightarrow 6 \text{ crs}$$

$$[m_i \vec{r}_i \wedge \ddot{\vec{r}}_i] = h^2 m_i \sum_{j \neq i} m_j \vec{r}_i \wedge \frac{\vec{r}_j}{r_{ij}^3}$$

$$\sum_{i=1}^n M_i = 0$$

INTEGR.

$$\Rightarrow \sum_{i=1}^N m_i \vec{r}_i \wedge \dot{\vec{r}}_i = \vec{L}_{\text{CRS}} \quad \rightarrow 3 \text{ CRs}$$

PLANO INVARIABLE

$$\Omega = 107^\circ$$

$$i = 1^\circ$$

$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = 0 \Rightarrow \sum_{i=1}^N m_i \vec{r}_i = \vec{a} \cdot t + \vec{b} \rightarrow 6$$

$$[m_i \vec{r}_i \wedge \dot{\vec{r}}_i] = h^2 m_i \sum_{j \neq i} m_j \frac{\vec{r}_i \wedge \vec{r}_j}{r_{ij}^3}$$

$$\sum_{i=1}^N [] = 0 \quad \rightarrow \text{INTEGR.}$$



$$U = k \sum_{i < j} \sum_{j=1}^N m_i m_j$$



$$U = h^2 \sum_{i < j} \sum_{j=1}^N \frac{m_j m_i}{r_{ij}} = \frac{1}{2} h^2 \sum_{i=1}^N \sum_{j > i} \frac{m_i m_j}{r_{ij}}$$

$$\nabla U = \left(\frac{\partial U}{\partial x_i}, \frac{\partial U}{\partial y_i}, \frac{\partial U}{\partial z_i} \right)$$

$$\frac{\partial U}{\partial r_i} = h^2 m_i$$



$$U = h^2 \sum_{i < j} \sum_{j=1}^n \frac{m_j m_i}{r_{ij}} = \frac{1}{2} h^2 \sum_{i=1}^n \sum_{j > i} \frac{m_j m_i}{r_{ij}}$$

$$\nabla U = \left(\frac{\partial U}{\partial x_i}, \frac{\partial U}{\partial y_i}, \frac{\partial U}{\partial z_i} \right)$$

$$\frac{\partial U}{\partial x_i} = h^2 m_i \sum_{j=1}^n m_j \frac{\partial \left(\frac{1}{r_{ij}} \right)}{\partial x_i} = -1 \cdot r_{ij}^{-2} \cdot (-x_i)^2 + ()^2 + ()^2$$

$$(x_j - x_i)$$

$$U = k^2 \sum_{i < j} \sum_{j=1}^N \frac{m_j m_i}{r_{ij}} = \frac{1}{2} k^2 \sum_{i=1}^N \sum_{j > i} \frac{m_i m_j}{r_{ij}}$$

$$\nabla U = \left(\frac{\partial U}{\partial x_i}, \frac{\partial U}{\partial y_i}, \frac{\partial U}{\partial z_i} \right)$$

$$\frac{\partial U}{\partial x_i} = k^2 m_i \sum_{j=1}^N m_j \frac{\partial \left(\frac{1}{r_{ij}} \right)}{\partial x_i}$$

$$= -k^2 m_i \sum_{j=1}^N m_j \cdot \frac{1}{r_{ij}^2} \cdot \frac{(x_i - x_j)}{r_{ij}}$$

$$r_{ij}^2 = (x_i - x_j)^2 + ()^2 + ()^2$$

$$2 \frac{\partial r_{ij}}{\partial x_i} \cdot \frac{\partial r_{ij}}{\partial x_i} = 2 (x_j - x_i) \cdot (-1) \\ = 2(x_i - x_j)$$

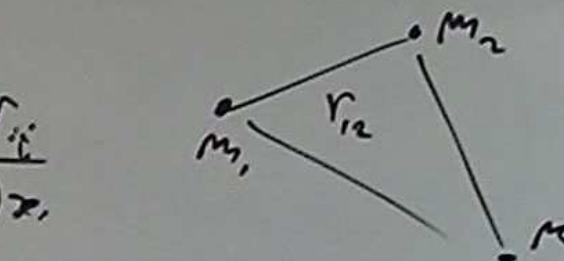
$$U = k \sum_{i < j} \sum_{j=1}^N \frac{m_j m_i}{r_{ij}} = \frac{1}{2} k \sum_{i=1}^N \sum_{j > i} \frac{m_j m_i}{r_{ij}}$$

$$\nabla_i U = \left(\frac{\partial U}{\partial x_i}, \frac{\partial U}{\partial y_i}, \frac{\partial U}{\partial z_i} \right)$$

$$\frac{\partial U}{\partial x_i} = k m_i \sum_{j=1}^N m_j \frac{\partial \left(\frac{1}{r_{ij}} \right)}{\partial x_i}$$

$$= -k m_i \sum_{j=1}^N m_j \cdot \frac{1}{r_{ij}^2} \cdot \frac{(x_i - x_j)}{r_{ij}}$$

$$POT = -U$$



$$r_{ij}^2 = (x_i - x_j)^2 + ()^2 + ()^2$$

$$\frac{\partial r_{ij}}{\partial x_i} \cdot \frac{\partial r_{ij}}{\partial x_i} = 2(x_j - x_i) \cdot (-1) \\ = 2(x_i - x_j)$$

$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = \sum_{i=1}^N \vec{F}_i \cdot \nabla_i U$$

$\Rightarrow \sum_{i=1}^N$

$$G = -k \sum_{j=1}^N m_j \cdot \frac{1}{r_{ij}^2} \cdot \frac{(x_i - x_j)}{r_{ij}}$$

$m_i \ddot{\vec{r}}_i = \nabla_i U$

$\therefore \vec{r}_i$

$E_{\text{POT}} = -U$



$$\sum_{i=1}^N m_i \ddot{\vec{r}}_i = \sum_{i=1}^N \vec{F}_i \cdot \nabla_i U$$

$$\left(\dot{x}_i \frac{\partial U}{\partial x_i} + \dot{y}_i \frac{\partial U}{\partial y_i} + \dots \right) = \frac{dU}{dt}$$

$$\cdot \frac{(x_i - x_j)}{r_{ij}}$$

$$-POT = -U$$



$$\sum_{i=1}^N m_i \dot{\vec{r}}_i \cdot \ddot{\vec{r}}_i = \sum_{i=1}^N \vec{r}_i \cdot \nabla_i U$$

INTEGRAR

$$\Rightarrow \sum_{i=1}^N m_i \frac{\dot{\vec{r}}_i^2}{2}$$

$$\sum_{i=1}^N \left(\dot{x}_i \frac{\partial U}{\partial x_i} + \dot{y}_i \frac{\partial U}{\partial y_i} + \dots \right) = \frac{dU}{dt}$$

$$T - U = c_{re} = E_{\text{POT}}$$

INTEGRAR $\Rightarrow U + c_{re}$

$$U = -k \sum_{j=1}^N m_j \cdot \frac{1}{r_{ij}} \cdot \frac{(x_i - x_j)}{r_{ij}}$$

$$m_i \ddot{\vec{r}}_i = \nabla_i U$$

$\downarrow \cdot \dot{\vec{r}}_i$

$$E_{\text{POT}} = -U$$



Contra el uso del teléfono móvil
en las aulas

Excepción de los móviles

que se usen para la enseñanza

o investigación

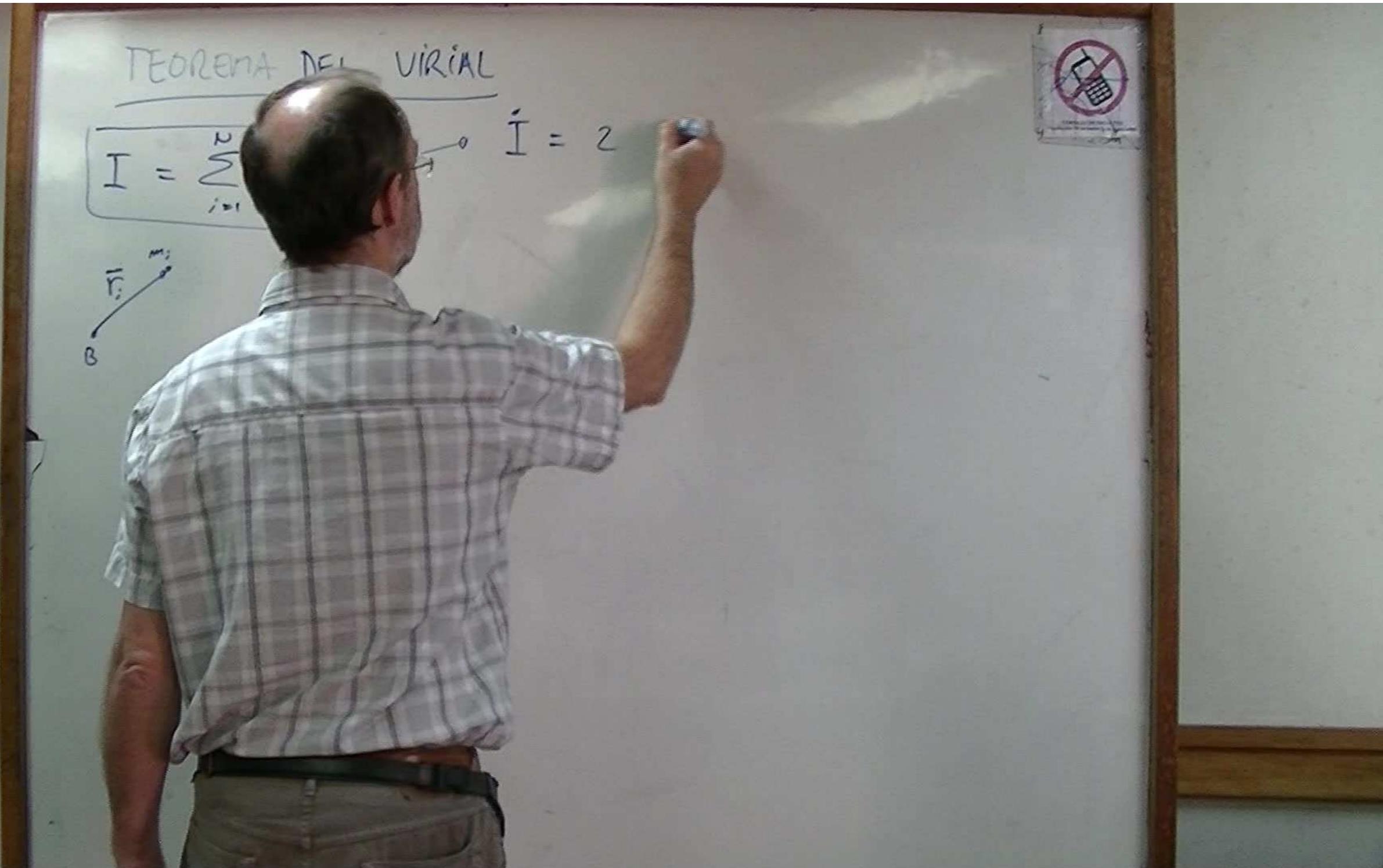
de acuerdo con la normativa

de cada centro

o universidad

que lo establezca

o no



LEY DEL VIRIAL

$$\sum_{i=1}^N m_i \dot{r}_i^2$$

$$\ddot{\mathbf{I}} = 2 \sum_{i=1}^N m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i$$

$$\ddot{\mathbf{I}} = 2 \sum_{i=1}^N m_i (\dot{\mathbf{r}}_i \cdot \dot{\mathbf{r}}_i + \ddot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i)$$

$$= \left(2 \sum_{i=1}^N m_i \dot{r}_i^2 \right)$$

$$+ \left(2 \sum_{i=1}^N m_i \dot{\mathbf{r}}_i \cdot \ddot{\mathbf{r}}_i \right)$$

4T

$$2 \sum_{i=1}^N \dot{\mathbf{r}}_i \cdot \nabla_i U$$



TEOREMA DEL VIRIAL

$$I = \sum_{i=1}^n m_i r_i^2$$

$$\dot{I} = 2 \sum_{i=1}^n m_i \bar{r}_i \dot{r}_i$$

$$\ddot{I} = 2 \sum_{i=1}^n m_i (\dot{r}_i \cdot \dot{r}_i + \bar{r}_i \cdot \ddot{r}_i)$$

$$= \left(2 \sum_{i=1}^n m_i \dot{r}_i^2 \right) + \left(2 \sum_{i=1}^n m_i \bar{r}_i \cdot \ddot{r}_i \right)$$

4T

$$2 \sum_{i=1}^n \bar{r}_i \cdot \nabla_i U$$

$$2 \sum_{i=1}^n \left(x_i \frac{\partial U}{\partial x_i} + y_i \frac{\partial U}{\partial y_i} + z_i \frac{\partial U}{\partial z_i} \right) = -2U$$





TEOREMA DEL VIRIAL

$$I = \sum_{i=1}^n m_i r_i^2$$

$$\dot{I} = 2 \sum_{i=1}^n m_i \dot{r}_i \cdot \ddot{r}_i$$

$$\ddot{I} = 2 \sum_{i=1}^n m_i (\dot{r}_i \cdot \dot{r}_i + \ddot{r}_i \cdot \ddot{r}_i)$$

$$= \left(2 \sum_{i=1}^n m_i \dot{r}_i^2 \right) + \left(2 \sum_{i=1}^n m_i \ddot{r}_i \cdot \ddot{r}_i \right)$$

4T

$$2 \sum_{i=1}^n \dot{r}_i \cdot \nabla_i U$$

$$2 \sum_{i=1}^n \left(x_i \frac{\partial U}{\partial x_i} + y_i \frac{\partial U}{\partial y_i} + z_i \frac{\partial U}{\partial z_i} \right) = -2U$$

$$\ddot{I} = 4T - 2U \rightarrow > 0$$



TEOREMA DEL VIRIAL

$$I = \sum_{i=1}^N m_i r_i^2$$

$$\dot{I} = 2 \sum_{i=1}^N m_i \vec{r}_i \cdot \vec{\dot{r}}_i$$

$$\ddot{I} = 2 \sum_{i=1}^N m_i (\vec{r}_i \cdot \vec{\ddot{r}}_i + \vec{\dot{r}}_i \cdot \vec{\ddot{r}}_i)$$

$$= \left(2 \sum_{i=1}^N m_i \dot{r}_i^2 \right) + \left(2 \sum_{i=1}^N m_i \vec{r}_i \cdot \vec{\ddot{r}}_i \right)$$

4T

$$2 \sum_{i=1}^N \vec{r}_i \cdot \nabla_i U$$

$$2 \sum_{i=1}^N \left(x_i \frac{\partial U}{\partial x_i} + y_i \frac{\partial U}{\partial y_i} + z_i \frac{\partial U}{\partial z_i} \right) = -2U$$

$$\ddot{I} = 4T - 2U \rightarrow > 0$$

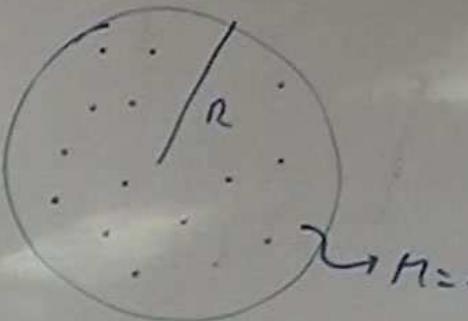
$$4T = 2U$$

$$2T = |\varepsilon_p|$$

$$100 \cdot m = \Delta = M$$

$$0 \quad v_{\text{max}}$$

$$\langle v \rangle = \frac{v_{\text{max}}}{2}$$



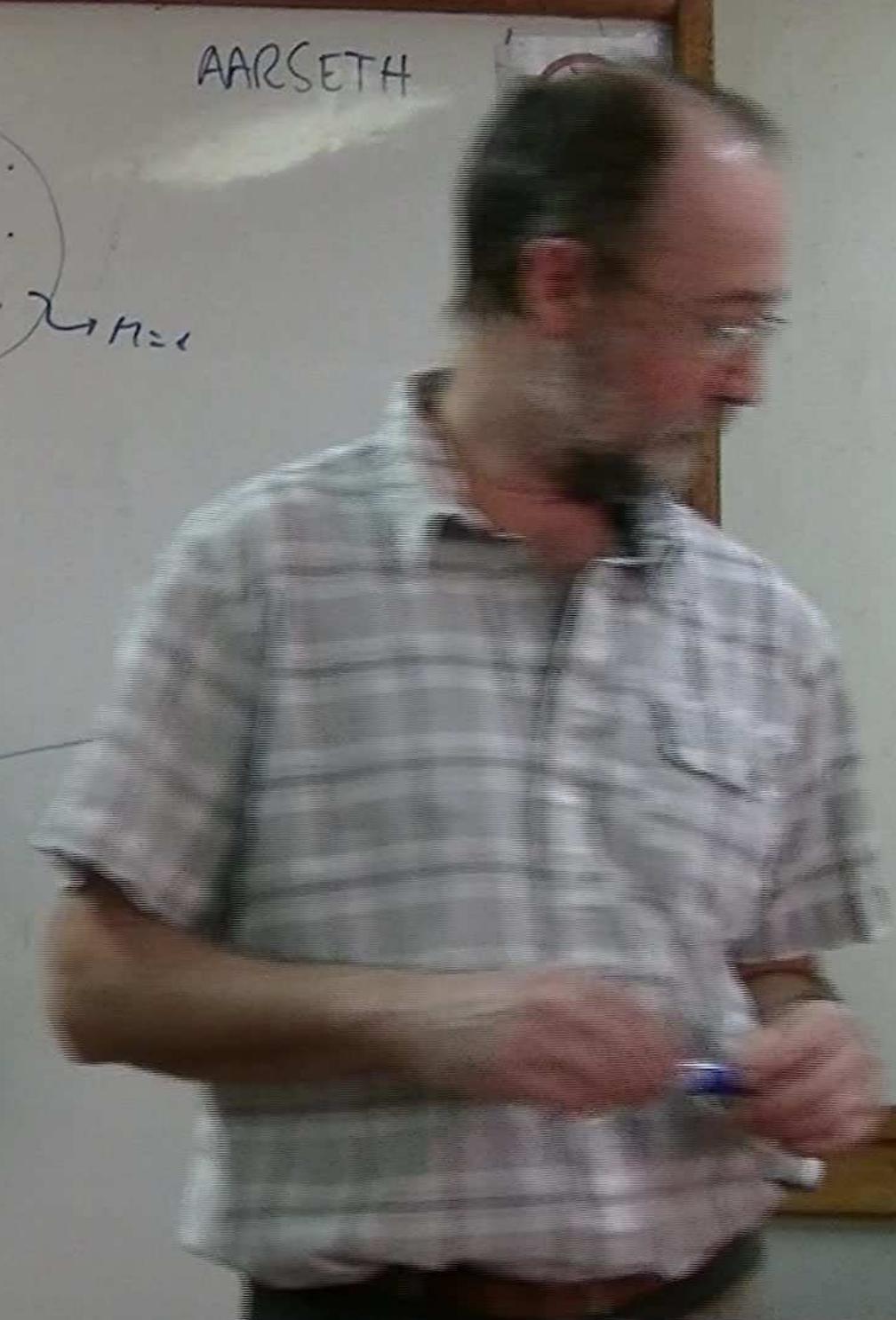
AARSETH

$$2 \sum_{i=1}^n \left(x_i \frac{\partial U}{\partial x_i} + y_i \frac{\partial U}{\partial y_i} + z_i \frac{\partial U}{\partial z_i} \right) = -2U$$

$$\boxed{\ddot{I} = 4T - 2U \rightarrow > 0}$$

$$4T = 2U$$

$$\boxed{2T = |\epsilon_p|}$$



$$100 \cdot m = \Delta = M$$

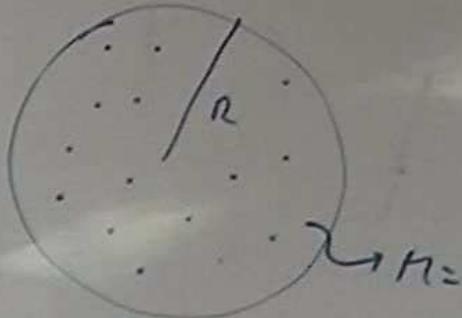
$$O \xrightarrow{v_{max}}$$

$$\langle v \rangle = \frac{v_{max}}{2}$$

$$\langle v \rangle^2 = \frac{3}{5} \frac{1}{R}$$

$$R=1 \Rightarrow$$

$$\frac{8M \cdot \langle v \rangle^2}{8} = \frac{3}{5} G \frac{m^2}{R}$$



AARSETH



$$2T = |\epsilon_p|$$

$$100 \cdot m = s = M$$

$$O \xrightarrow{v_{max}}$$

$$\langle v \rangle = \frac{v_{max}}{2}$$

$$\langle v \rangle^2 = \frac{3}{5} \frac{1}{R} \Rightarrow \langle v \rangle$$

$$R=1 \Rightarrow$$

$$2T = |\epsilon_p|$$

AARSETH

$$2\pi/P = M = \sqrt{\frac{\mu}{a^3}}$$



$$100 \cdot m = \Delta = M$$

$$O \xrightarrow{v_{max}}$$

$$\langle v \rangle = \frac{v_{max}}{2}$$

$$\langle v \rangle^2 = \frac{3}{5} \frac{1}{R} \Rightarrow \langle v \rangle = 0.77$$

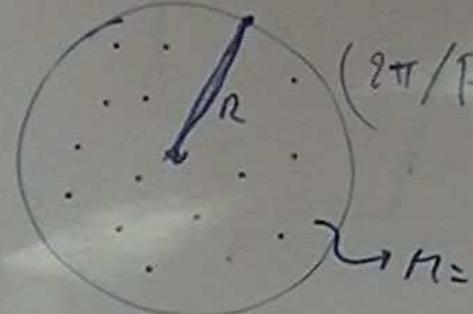
$$R=1 \Rightarrow$$

$$100 \cdot m = \Delta = M$$

$$O \xrightarrow{v_{max}}$$

$$\langle v \rangle = \frac{v_{max}}{2}$$

$$\frac{8M \cdot \langle v \rangle^2}{8} = \frac{3}{5} \frac{G M h^2}{R}$$



AARSETH



$$(8\pi/P) = M = \sqrt{\frac{\mu}{a^3}}$$

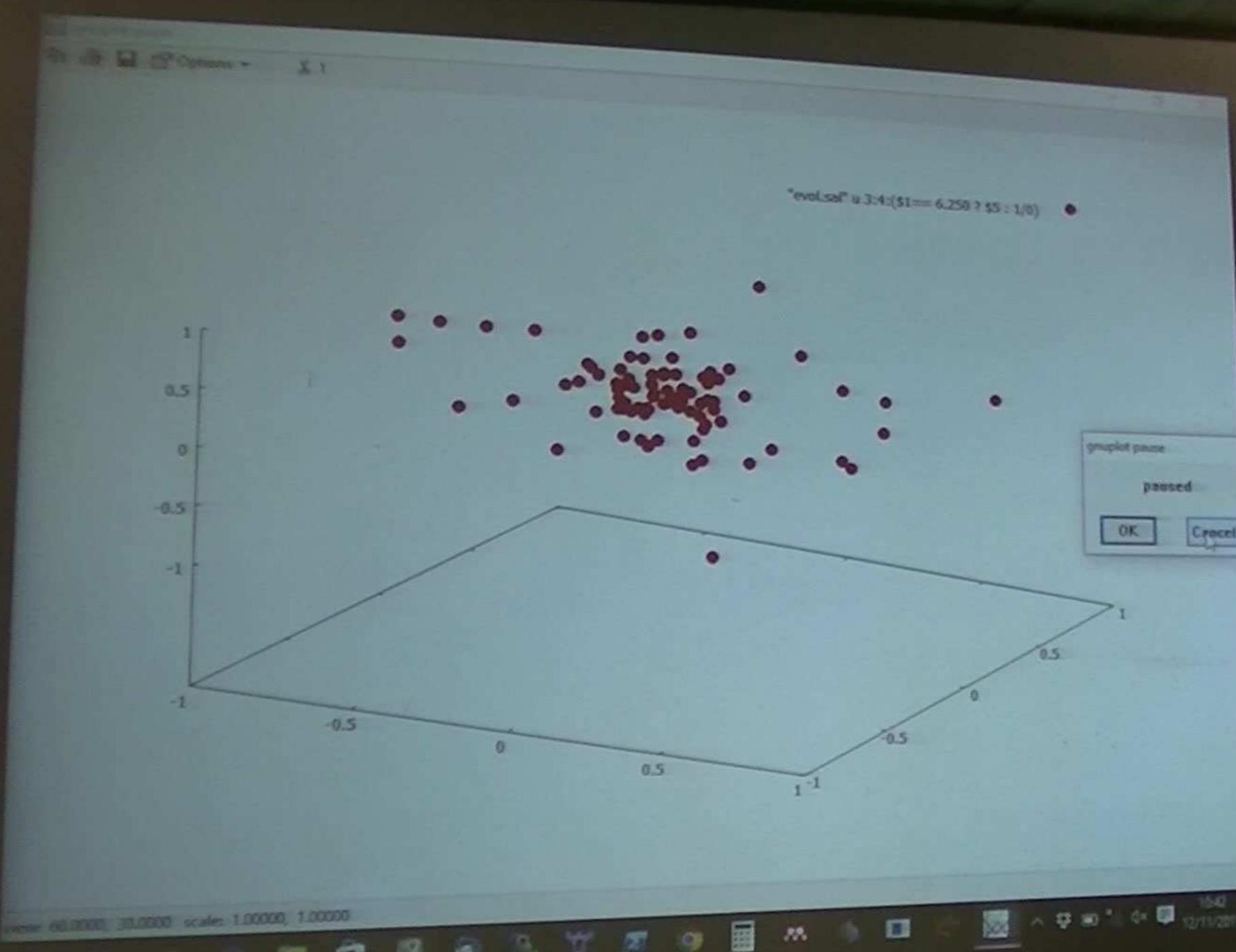
$$= \sqrt{\frac{1}{(R/2)^3}}$$

$$= \sqrt{2^3} = 2\sqrt{2}$$

$$P = \frac{2\pi}{2\sqrt{2}} \approx 2$$

$$T_{cambio} \sim 1$$

$$2T = |\epsilon_p|$$



$$100 \cdot m_0 = \Delta = M$$

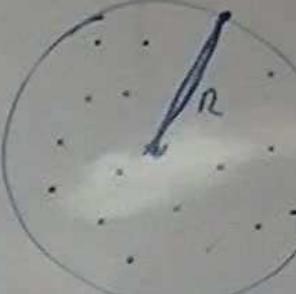
$$\frac{1}{5} \frac{1}{R} \Rightarrow \langle V \rangle = 0.77$$

$\rightarrow 1 \Rightarrow$

$$V_{max} \sim 1.5$$

$$2T = |\varepsilon_p|$$

AARSETH



$$(2\pi/P) = n = \sqrt{\frac{L^2}{a^3}}$$

$$n_{circular} = \sqrt{\frac{1}{(R/2)^2}}$$

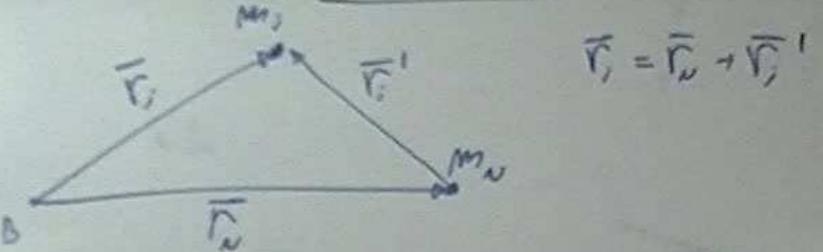
$$= \sqrt{2^3} = 2\sqrt{2}$$

$$P = \frac{2\pi}{2\sqrt{2}} \sim 2$$

$$T_{circular} \sim 1$$



TRANSFORMACION DE ORIGEN (m_0)



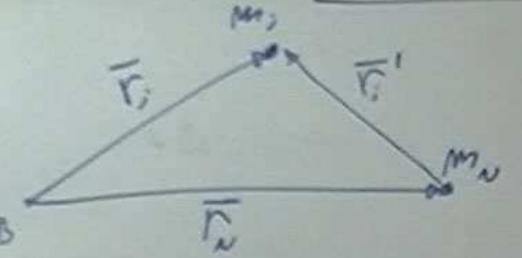
$$\vec{r}_i = \vec{r}_0 + \vec{r}'_i$$

$$\delta x_i = \delta x'_i$$

$$U = k^2 m_0 \sum_{j=1}^n \frac{m_j}{r_{0j}}$$



TRANSFormación de ORIGEN (m₀)



$$\bar{r}_i = \bar{r}_n + \bar{r}'_i$$

$$\delta x_i = \delta x'_i$$

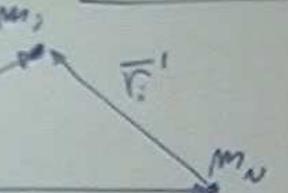
U'

$$U = h^2 m_0 \sum_{j=1}^{N-1} \frac{m_j}{r_{nj}} + \boxed{h^2 \sum_{i < j} \sum_{j=1}^{N-1} \frac{m_i m_j}{r_{ij}}}$$

$$\nabla_r U =$$



TRANSFORMACION DE ORIGEN (m₀)



$$\bar{r}_i = \bar{r}_0 + \bar{r}'_i$$

$$\partial x_i = \partial x'_i$$

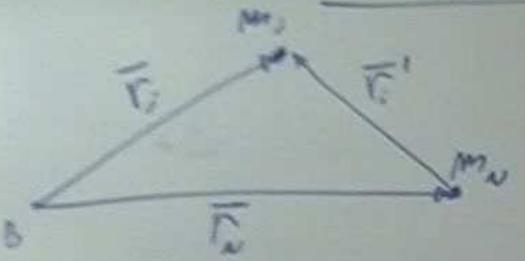
U'

$$= h^2 m_0 \sum_{j=1}^{N-1} \frac{m_j}{r_{nj}} + \boxed{h^2 \sum_{i>i} \sum_{j=1}^{N-1} \frac{m_i m_j}{r_{ij}}}$$

$$r_i'^2 \cdot \left(\frac{\partial r'_i}{\partial x_i} \right) = \frac{x'_i}{h^2}$$



TRANSFORMACION DE ORIGEN (m₀)



$$\vec{r}_i = \vec{r}_0 + \vec{r}'_i$$

$$\partial x_i = \partial x'_i$$

U'

$$U = h^2 \sum_{j=1}^{N-1} \frac{m_j}{r_{0j}} + \boxed{h^2 \sum_{i < j} \sum_{j=1}^{N-1} \frac{m_i m_j}{r_{ij}}}$$

$$\nabla_r U = -h^2 m_0 m_i \frac{\vec{r}'_i}{r_i^3} + \nabla_r U'$$

$$\ddot{\vec{r}}_0 = -h^2 \sum_{j=1}^{N-1} m_j \frac{(\vec{r}_0 - \vec{r}_j)}{r_j^3} \rightarrow -\ddot{\vec{r}}'_j = h^2 \sum_{j=1}^{N-1} m_j \frac{\vec{r}'_j}{r_j}$$



$$\ddot{\bar{r}}_i = \ddot{\bar{r}}_i' + \ddot{\bar{r}}_N = \frac{1}{m_i} \nabla_i U$$

$$\ddot{\bar{r}}_i' + h^2 \sum_{j=1}^{N-1} m_j \frac{\ddot{\bar{r}}_j'}{r_{ij}^3} = \frac{1}{m_i}$$

$$U = h^2 \sum_{j=1}^{N-1} \frac{m_j}{\frac{r_{Nj}}{r_i'}} + \boxed{h^2 \sum_{i < j} \sum_{j=1}^{N-1} \frac{m_i m_j}{r_{ij}}}$$

$$\nabla_i U = -h^2 m_N m_i \frac{\bar{r}_i'}{r_i'^3} + \nabla_i U'$$

$$\ddot{\bar{r}}_N = -h^2 \sum_{j=1}^{N-1} m_j \frac{(\bar{r}_N - \bar{r}_j)}{r_{ij}'^3} = h^2 \sum_{j=1}^{N-1} m_j \frac{\bar{r}_j'}{r_{ij}'^3}$$

$$\ddot{\bar{r}}_i = \ddot{\bar{r}}_i' + \ddot{\bar{r}}_N = \frac{1}{m_i} \nabla_i U$$

$$\Rightarrow \ddot{r}_i + h^2 \sum_{j=1}^{N-1} m_j \frac{\bar{r}_j'}{r_j^3} = \frac{1}{m_i} \left[\nabla_i U - h^2 m_i m_j \frac{\bar{r}_j'}{r_j^3} \right]$$
$$+ h^2 m_i \frac{\bar{r}_i'}{r_i^3} + h^2$$





$$\ddot{\vec{r}}_i = \vec{r}_i'' + \vec{r}_N'' = \frac{1}{m_i} \nabla_i U$$

$$m_i \ddot{\vec{r}}_i + h^2 \sum_{j=1}^{N-1} m_j \frac{\vec{r}_j''}{r_{ij}^3} = \frac{1}{m_i} \left[\nabla_i U - h^2 m_{\text{sun}} \frac{\vec{r}_i''}{r_{\odot i}^3} \right]$$

$$\ddot{\vec{r}}_i'' + h^2 m_i \frac{\ddot{\vec{r}}_i''}{r_{\odot i}^3} + h^2 \sum_{\substack{j=1 \\ j \neq i}}^{N-1} m_j \frac{\ddot{\vec{r}}_j''}{r_{ij}^3}$$

ORigen en M_\odot

$$\ddot{\vec{r}}_i'' + h^2 (m_i + \alpha)$$





$$\dot{\vec{r}}_i = \vec{r}'_i + \vec{v}_i = \frac{1}{m_i} \nabla_i U$$

$$\sum_{j=1}^{N-1} m_j \frac{\vec{r}'_j}{r_{ij}^3} = \frac{1}{m_i} \left[\nabla_i U - h^2 m_{\infty} m_i \frac{\vec{r}'_i}{r_i^3} \right]$$

$$\frac{\vec{r}'_i}{r_i^3} + h^2 \sum_{\substack{j=1 \\ j \neq i}}^{N-1} m_j \frac{\vec{r}'_j}{r_{ij}^3} = \frac{1}{m_i} []$$

$$h^2 \left(m_i + m_{\infty} \right) \frac{\vec{r}'_i}{r_i^3} = - h^2 \sum_{\substack{j=1 \\ j \neq i}}^{N-1} m_j \frac{\vec{r}'_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U$$



R_{ij} 

$$\boxed{\ddot{\vec{r}}_i + \hbar^2 \left(m_i + m_n \right) \frac{\vec{r}_i}{r_i^3}} = -\hbar^2 \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \frac{\vec{r}_j}{r_j^3} + \frac{1}{m_i} \nabla_i U$$

$$R_{ij} = k^2 \left(\frac{1}{r_{ij}} - \frac{\bar{r}_i \cdot \bar{r}_j}{r_{ij}^3} \right)$$

$$\rightarrow m_j \nabla_i R_{ij} = k^2 \nabla_i \left(\frac{m_j}{r_{ij}} \right) -$$

$$\boxed{(m_j) \frac{\bar{r}_i}{r_{ij}^3}} = -k^2 \sum_{\substack{j=1 \\ j \neq i}}^{N-1} m_j \frac{\bar{r}_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U$$



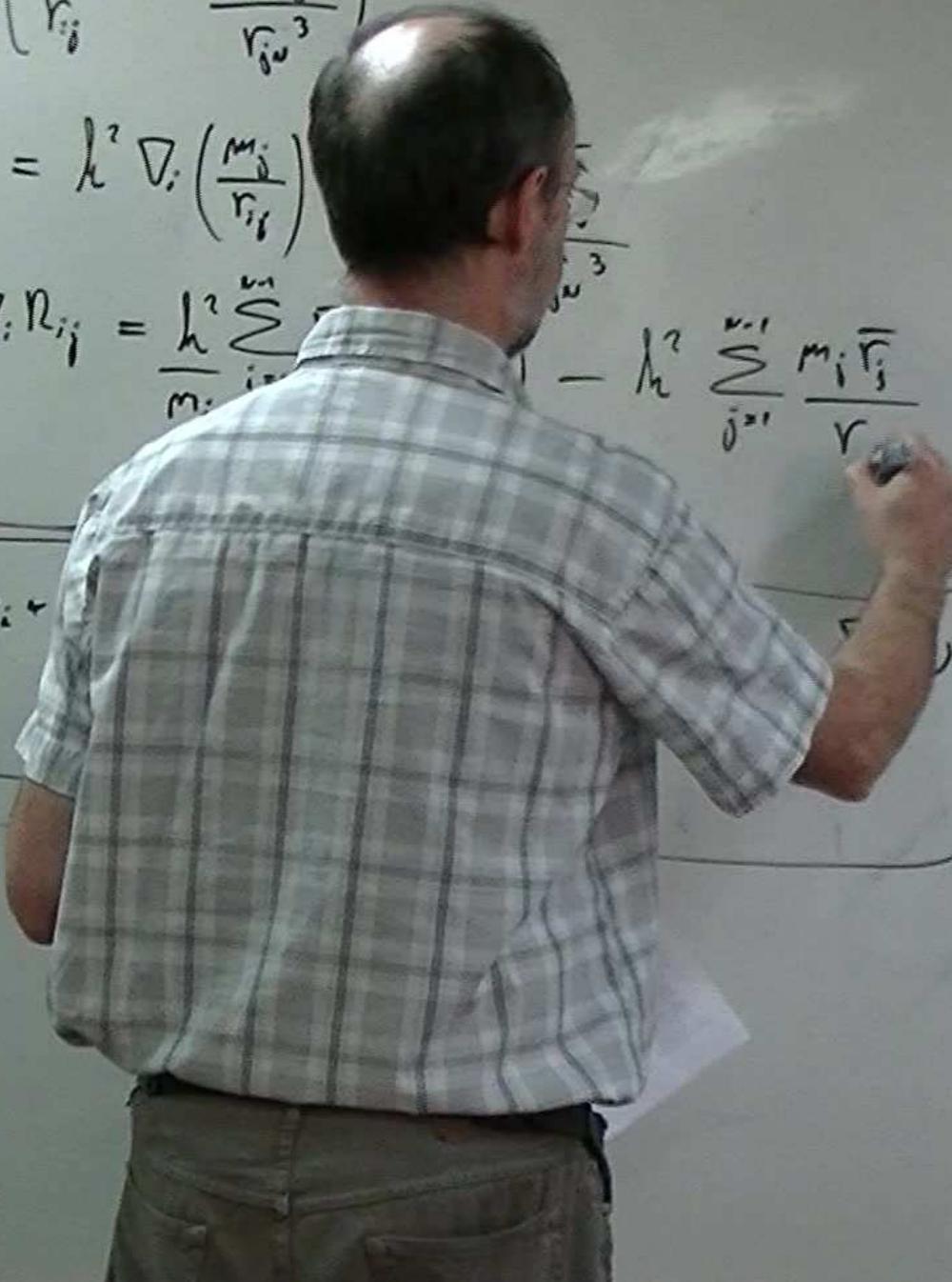


$$R_{ij} = h^2 \left(\frac{1}{r_{ij}} - \frac{\bar{r}_i \cdot \bar{r}_j}{r_{ij}^3} \right)$$

$$m_j \nabla_i R_{ij} = h^2 \nabla_i \left(\frac{m_j}{r_{ij}} \right)$$

$$\sum_{\substack{j=1 \\ j \neq i}}^m m_j \nabla_i R_{ij} = h^2 \sum_{j=1, j \neq i}^m \frac{m_j}{r_{ij}^3} - h^2 \sum_{j=1}^m \frac{m_j \bar{r}_j}{r}$$

$$\ddot{\bar{r}}_i + h^2 \left(m_i \cdot \right)$$





$$R_{ij} = h^2 \left(\frac{1}{r_{ij}} - \frac{\bar{r}_i \cdot \bar{r}_j}{r_{ij}^3} \right)$$

$$m_j \nabla_i R_{ij} = h^2 \nabla_i \left(\frac{m_j}{r_{ij}} \right) - h^2 m_j \frac{\bar{r}_j}{r_{ij}^3}$$

$$\sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \nabla_i R_{ij} = \frac{h^2}{m_i} \left(\sum_{\substack{j=1 \\ j \neq i}}^{n-1} \nabla_i \left(\frac{m_j m_i}{r_{ij}} \right) \right) - h^2 \sum_{\substack{j=1 \\ j \neq i}}^{n-1} \frac{m_i \bar{r}_j}{r_{ij}^3}$$

$\nabla_i U / m_i$

$$\ddot{\bar{r}}_i + h^2 \left(m_i + m_N \right) \frac{\bar{r}_i}{r_i^3} = -h^2 \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \frac{\bar{r}_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U$$

$$\ddot{\bar{r}}_i + h^2 \left(m_i + m_N \right) \frac{\bar{r}_i}{r_i^3} = \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j$$



$$R_{ij} = k \left(\frac{1}{r_{ij}} - \frac{\bar{r}_i \cdot \bar{r}_j}{r_{ij}^3} \right)$$

$$m_j \nabla_i R_{ij} = k \nabla_i \left(\frac{m_i}{r_{ij}} \right) - k \frac{m_j \bar{r}_j}{r_{ij}^3}$$

$$\sum_{\substack{j=1 \\ j \neq i}}^n m_j \nabla_i R_{ij} = \frac{k}{m_i} \left(\sum_{\substack{j=1 \\ j \neq i}}^n \nabla_i \left(\frac{m_j m_i}{r_{ij}} \right) \right) - k \sum_{\substack{j=1 \\ j \neq i}}^n \frac{m_i \bar{r}_j}{r_{ij}^3}$$

$$\ddot{\bar{r}}_i + k^2 (m_i + m_n) \frac{\bar{r}_i}{r_i^3} = -k^2 \sum_{\substack{j=1 \\ j \neq i}}^n m_j \frac{\bar{r}_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U'$$

$$\ddot{\bar{r}}_i + k^2 (m_i + m_n) \frac{\bar{r}_i}{r_i^3} = \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \nabla_i (R_{ij}) \rightarrow \text{Funciones Perturbadoras}$$



$$\vec{R}_{ij} = h^2 \left(\frac{1}{r_{ij}} - \frac{\vec{r}_i \cdot \vec{r}_j}{r_{ij}^3} \right)$$

$$m_j \nabla_i \vec{R}_{ij} = \left(\frac{m_j}{r_{ij}} \right) - h^2 \frac{m_j \vec{r}_j}{r_{ij}^3}$$

$$\sum_{j=1}^n m_j \left(\sum_{\substack{j=1 \\ j \neq i}}^n \nabla_i \left(\frac{m_j m_i}{r_{ij}} \right) \right) - h^2 \sum_{j=1}^{n-1} \frac{m_i \vec{r}_j}{r_{ij}^3}$$

$$\vec{F}_i = -h^2 \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \frac{\vec{r}_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U$$

$$\frac{1}{r_{ij}^3} = \sum_{j=1}^{n-1} \frac{1}{r_{ij}}$$

Funciones
Pertenecientes

$$\ddot{\bar{r}_i} + \lambda^2 (m_i + m_N) \frac{\bar{r}_i}{\bar{r}_i^3} = \lambda^2 \left(\frac{\bar{r}_j - \bar{r}_i}{\bar{r}_{ij}^3} \right) - \frac{\bar{r}_i}{\bar{r}_i}$$

$$\ddot{\bar{r}_i} + \lambda^2 (m_i + m_N) \frac{\bar{r}_i}{\bar{r}_i^3}$$

$$\ddot{\bar{r}_i} + \lambda^2 (m_i + m_N) \frac{\bar{r}_i}{\bar{r}_i^3}$$

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CICLOS
TURBULENTOS



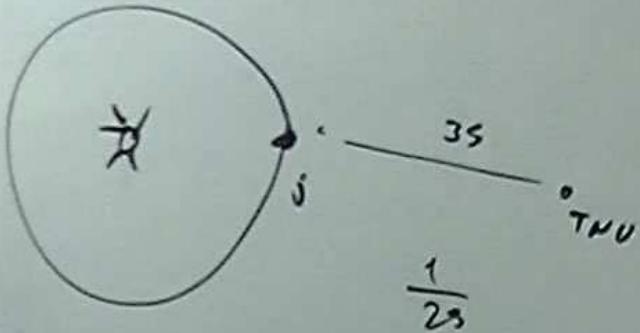
$$\ddot{\vec{r}}_i = \frac{G(m_i + m_\infty)}{r_i^3} \vec{r}_i - \sum_{j=1}^{n-1} m_j \left(\frac{\vec{r}_j - \vec{r}_i}{r_{ij}^3} \right) - \boxed{\frac{\vec{r}_i}{r_i^3}}$$

Dirrecta Indirecta

$$\ddot{\vec{r}}_i = -G \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \frac{\vec{r}_j}{r_{ij}^3} + \frac{1}{m_i} \nabla_i U$$

$$\ddot{\vec{r}}_i = \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \nabla_i R_{ij} \rightarrow \text{Funciones Perturbadoras}$$

$$\ddot{\vec{r}}_i + \hbar^2 (m_i + m_N) \frac{\vec{r}_i}{r_i^3} = \hbar^2 \sum_{j=1}^{n-1} m_j \left(\frac{\vec{r}_j - \vec{r}_i}{r_{ij}^3} \right)$$



Dirrecta

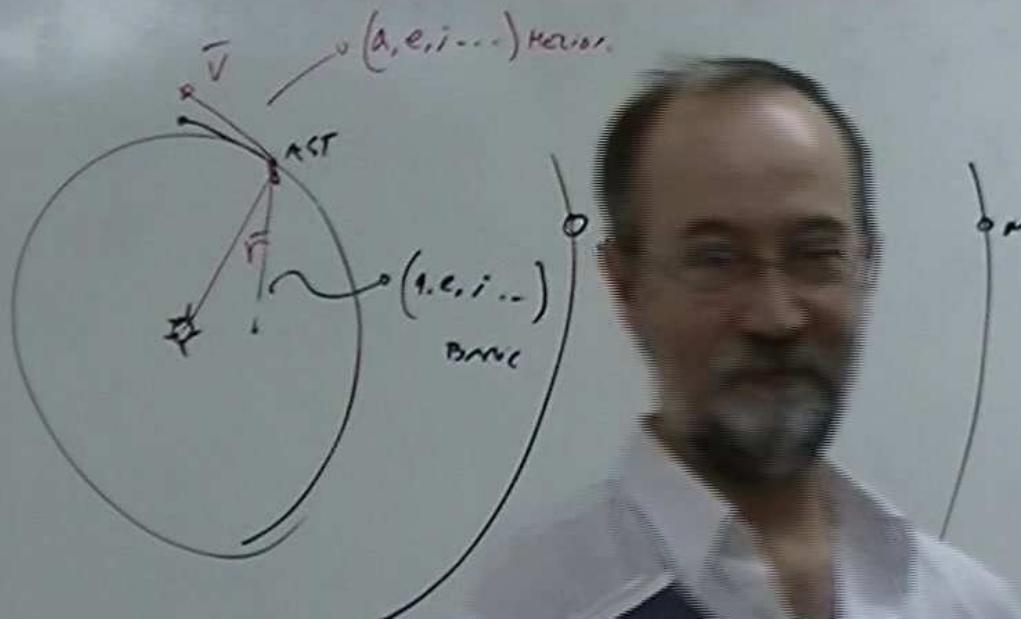
$$\boxed{\ddot{\vec{r}}_i + \hbar^2 (m_i + m_N) \frac{\vec{r}_i}{r_i^3}} = - \hbar^2 \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j \frac{\vec{r}_j}{r_{ij}^3}$$

$$\ddot{\vec{r}}_i + \hbar^2 (m_i + m_N) \frac{\vec{r}_i}{r_i^3} = \sum_{\substack{j=1 \\ j \neq i}}^{n-1} m_j D_i(R_{ij})$$

SISTEMA BANICÉNTRICO VS HELIOCÉNTRICO

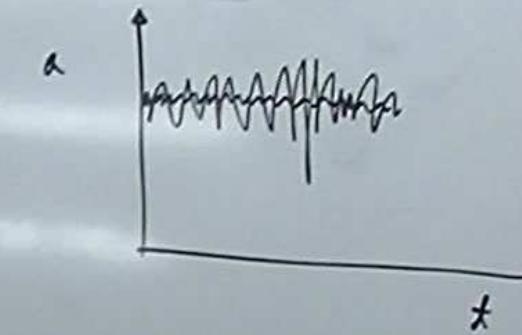
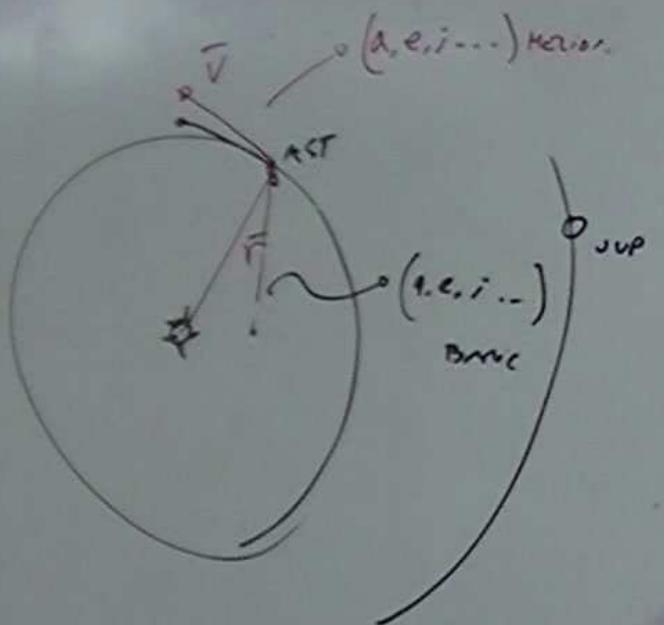


SISTEMA BANICÉNTRICO vs HELIOCÉNTRICO



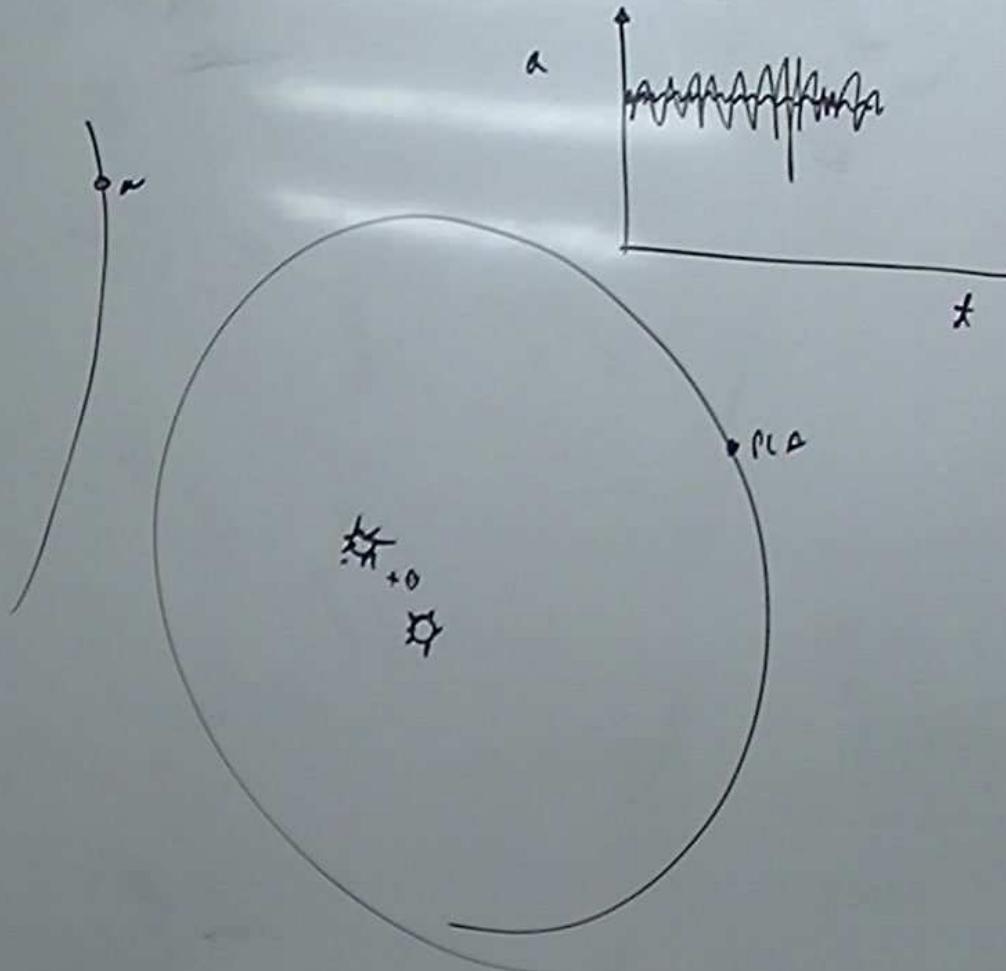
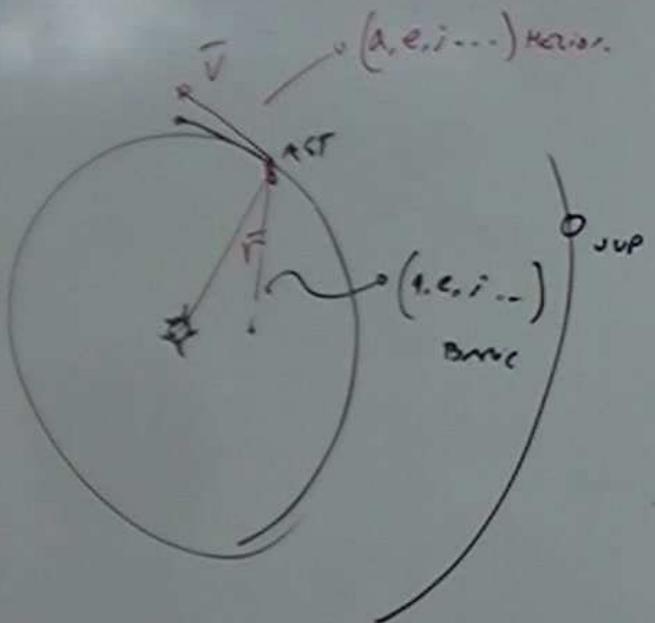
BRA AQUÍ

SISTEMA BANICÉNTRICO vs HELIOCÉNTRICO

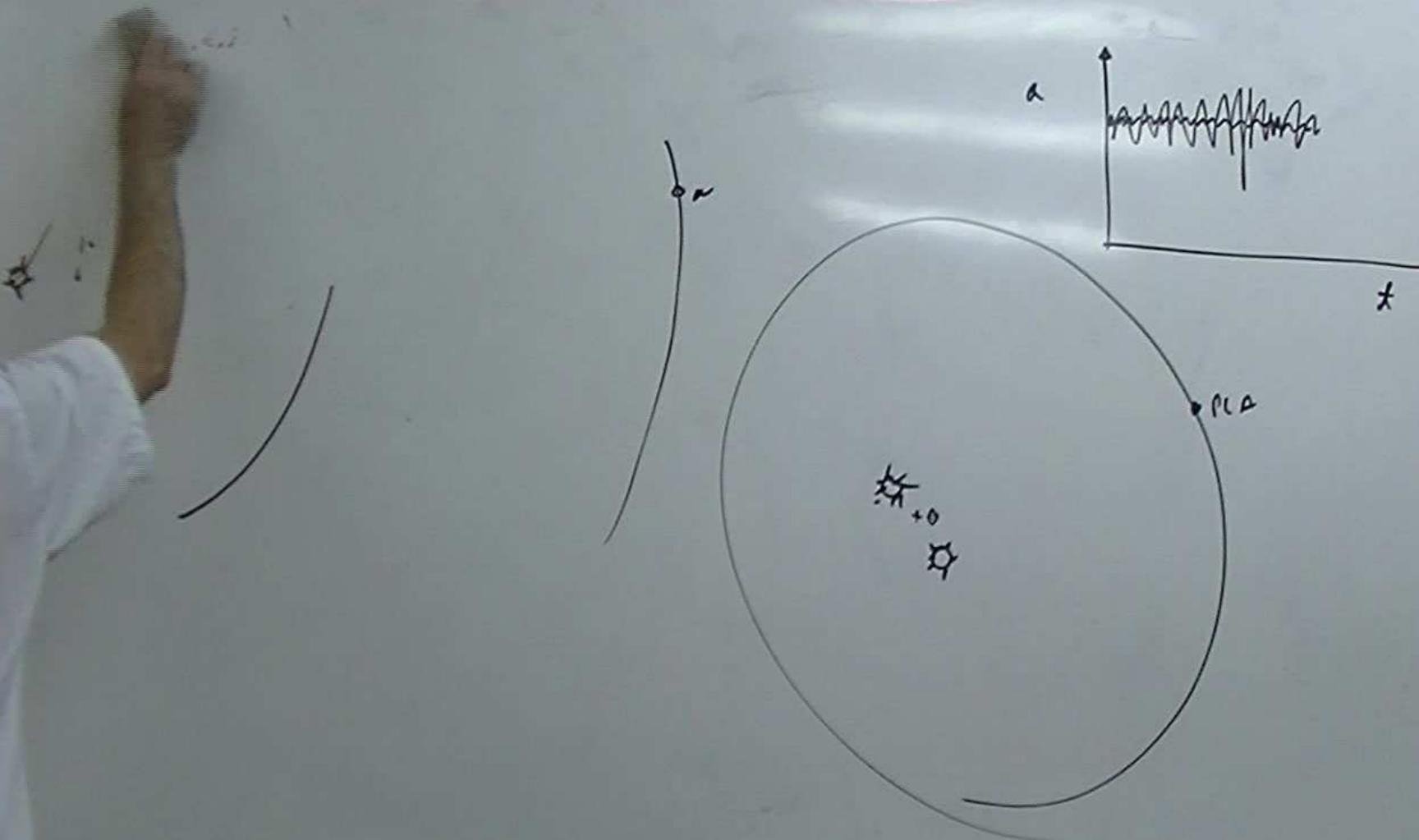


RA AQUÍ

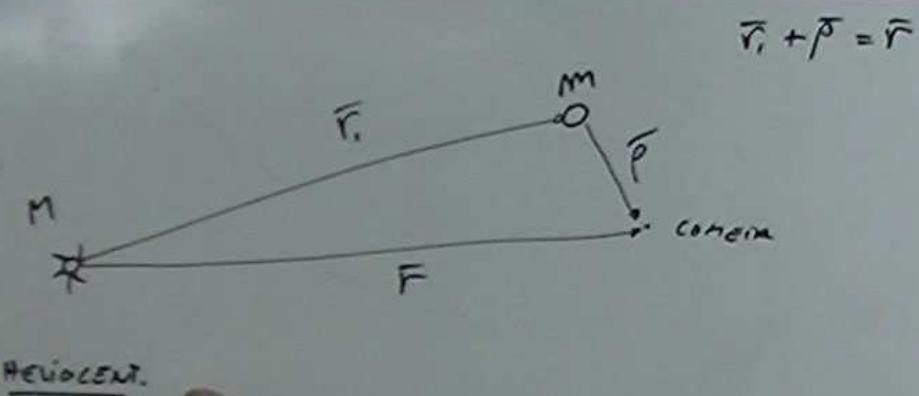
SISTEMA BANICÉNTRICO VS HELIOCÉNTRICO



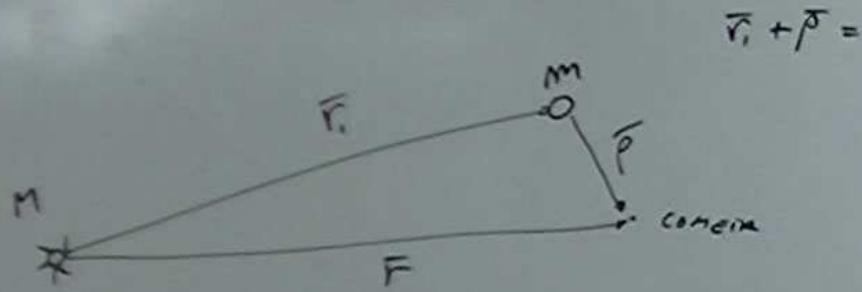
SISTEMA BANICÉNTRICO VS HELIOCÉNTRICO



SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO



SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

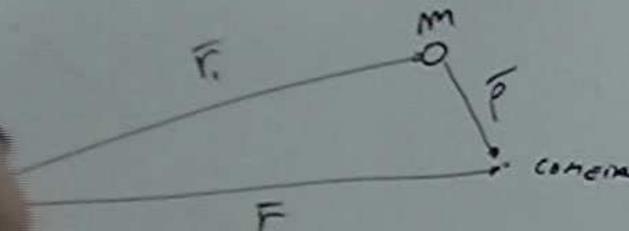
HELIOCENT.

$$\ddot{\vec{r}} = -\frac{k^2 M \vec{r}}{r^3} + k^2 \cdot m \left[\frac{\vec{r}_i - \vec{r}}{r^3} - \frac{\vec{r}_i}{r_i^3} \right]$$

PLANETOC.

SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

$$\bar{r}_i + \bar{p} = \bar{r}$$

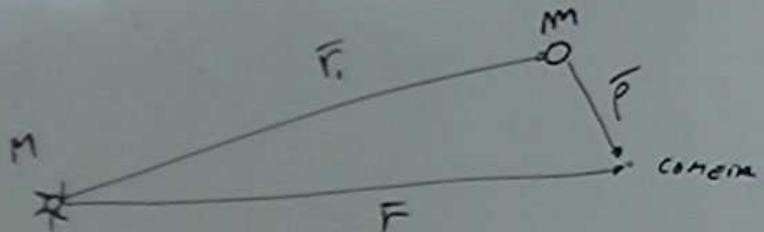


$$\ddot{\bar{r}} = -\frac{k^2 M \bar{r}}{r^3} + k^2 \cdot M \left[\frac{\bar{r}_i - \bar{r}}{p^3} - \frac{\bar{r}_i}{r^3} \right]$$

$$\ddot{\bar{p}} = -\frac{k^2 m \cdot \bar{p}}{p^3} + k^2 \cdot M \left[-\frac{\bar{r}_i - \bar{p}}{p^3} \right]$$

SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

$$\bar{r}_i + \bar{p} = \bar{r}$$

HELIOCENT.

$$\ddot{\bar{r}} = -\frac{k^2 M \bar{r}}{r^3} + k^2 \cdot M \left[\frac{\bar{r}_i - \bar{r}}{p^3} - \frac{\bar{r}_i}{r^3} \right]$$

PLANETOC.

$$\ddot{\bar{p}} = -\frac{k^2 m \cdot \bar{p}}{p^3} + k^2 \cdot M \left[\frac{-\bar{r}_i - \bar{p}}{r^3} - \frac{-\bar{r}_i}{r^3} \right]$$

SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

$\bar{r}_i + \bar{p} = \bar{r}$

REVIOLCENT.

$$\ddot{\bar{r}}_i = -\frac{k^2 M \bar{r}_i}{r_i^3} + k^2 \cdot M \left[\frac{\bar{r}_i - \bar{r}}{P_H^3} - \frac{\bar{r}_i}{r_i^3} \right]$$

PLANETOC.

$$\ddot{\bar{p}} = -\frac{k^2 (m \cdot \bar{p})}{P_P^3} + k^2 \left[M \left[\frac{-\bar{r}_i - \bar{p}}{r^3} - \frac{-\bar{r}_i}{r_i^3} \right] \right] \rightarrow P_P$$

ρ tal que: $\frac{C_H}{P_H} \approx \frac{C_P}{P_P}$ (ρ pequeño)

SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

$\vec{r}_i + \vec{p} = \vec{r}$

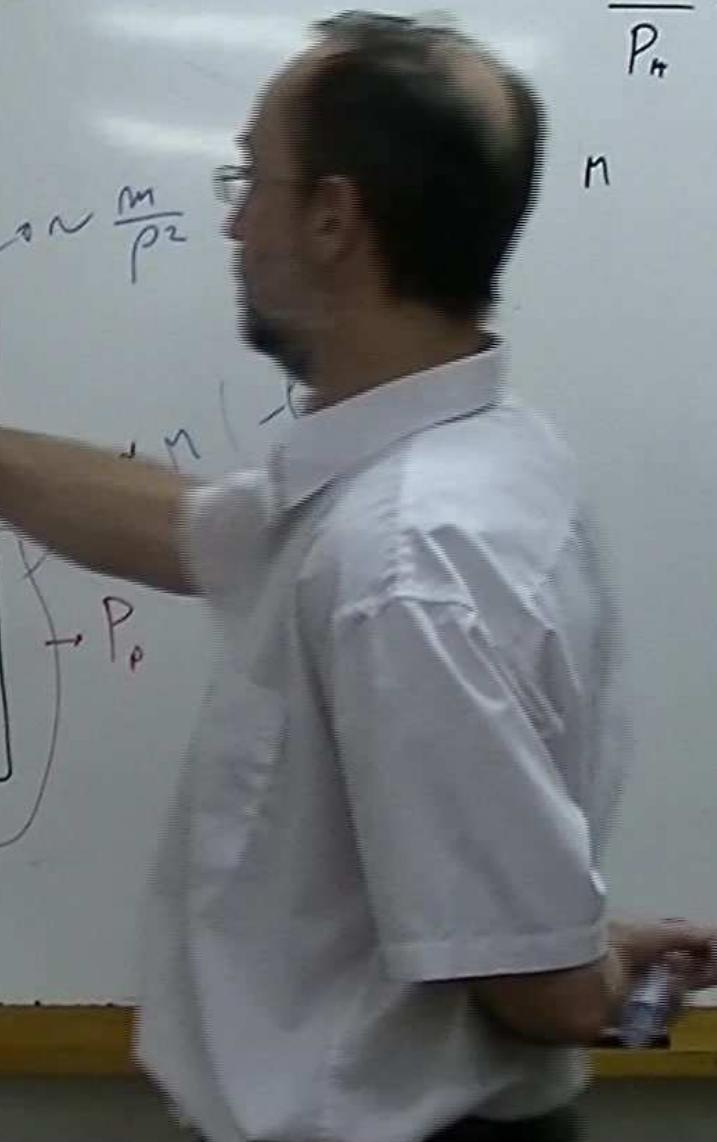
HELIOCENT.

$$\ddot{\vec{r}} = -k^2 \frac{M \vec{r}}{r^3} + k^2 \left[m \left[\frac{\vec{r}_i - \vec{r}}{P_H^3} - \frac{\vec{r}_i}{r^2} \right] \right] \sim \frac{m}{P^2}$$

PLANETOC.

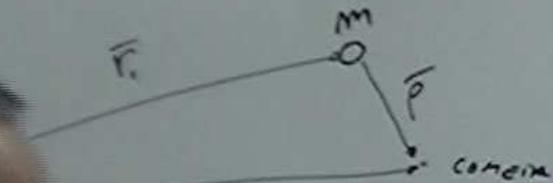
$$\ddot{\vec{p}} = -k^2 \frac{m \cdot \vec{p}}{P^3} + k^2 \left[m \left[\frac{-\vec{r}_i - \vec{p}}{r^3} - \frac{-\vec{r}_i}{r^3} \right] \right] \rightarrow P_P$$

P tal que: $\frac{C_H}{P_H} \approx \frac{C_P}{P_P}$ (P pequeño)



SISTEMA PLANETOCÉNTRICO VS HELIOCÉNTRICO

$$\bar{r}_i + \bar{P} = \bar{r}$$



$$F = -\frac{k^2 M \bar{r}}{r^3} + k^2 \left[M \left(\frac{\bar{r}_i - \bar{P}}{r^3} - \frac{\bar{r}_i}{r^3} \right) \right] \sim \frac{m}{r^2}$$

(C_H)

$$= -\frac{k^2 m \cdot \bar{P}}{r^3} + k^2 \left[M \left(\frac{-\bar{r}_i - \bar{P}}{r^3} - \frac{-\bar{r}_i}{r^3} \right) \right] \rightarrow P_p$$

(C_P)

tal que: $\frac{C_H}{P_H} \approx \frac{C_P}{P_P}$ (P Período)

$$\frac{m}{r^2} \frac{P^2}{m} \approx \frac{m \cdot r_i^3}{r^3 M P}$$

$\sim r_i^2$

$$P^2 \approx r_i^3 \cdot \frac{M^2}{m^2}$$

RADIO ESFERA DE INFLUENCIA

$$P \approx r_i \cdot \left(\frac{m}{M} \right)^{1/2} s$$

METODO DE COWELL

$$\bar{r}_{i+1} = \bar{r}_i + \bar{v}_i \cdot \Delta t$$

$$\bar{v}_{i+1} = \bar{v}_i + \ddot{\bar{r}}_i \cdot \Delta t$$

MÉTODO DE COWELL:

$$\bar{r}_{i+1} = \bar{r}_i + \bar{v}_i \Delta t$$

$$\bar{v}_{i+1} = \bar{v}_i + \ddot{\bar{r}}_i \Delta t$$

MÉTODO DE ENCKE:

$$\ddot{\bar{r}}_i =$$

MÉTODO DE COWELL:

$$\bar{r}_{i+1} = (\bar{r}_i + \bar{v}_i \Delta t)_{t_{i+1} - t_i}$$

$$\bar{v}_{i+1} = (\bar{v}_i + (\ddot{\bar{r}}_i) \Delta t)$$

MÉTODO DE ENCKE:

$$\ddot{\bar{r}}_i = (\bar{k}_i) + \bar{p}_i$$

$$S_i(\bar{r}_i, \bar{v}_i)$$

$$\bar{r}_{i+1} = S_i(t_{i+1})$$

MÉTODO DE COWELL:

$$\bar{r}_{i+1} = (\bar{r}_i + \bar{v}_i \Delta t) \xrightarrow{t_{i+1} - t_i}$$

$$\bar{v}_{i+1} = (\bar{v}_i + (\ddot{\bar{r}}_i) \Delta t)$$

MÉTODO DE ENCKE:

$$\ddot{\bar{r}}_i = (\bar{k}_i) + \bar{p}_i$$

$$S_i(\bar{r}_i, \bar{v}_i)$$

$$\bar{r}_{i+1} = S_i(t_{i+1})$$

$$\bar{v}_{i+1} = S_i(t_{i+1}) + (\bar{p}_i) \Delta t$$

MÉTODO DE COWELL:

$$\bar{r}_{i+1} = (\bar{r}_i + \bar{v}_i) \Delta t$$

$$\bar{v}_{i+1} = (\bar{v}_i + \ddot{\bar{r}})$$

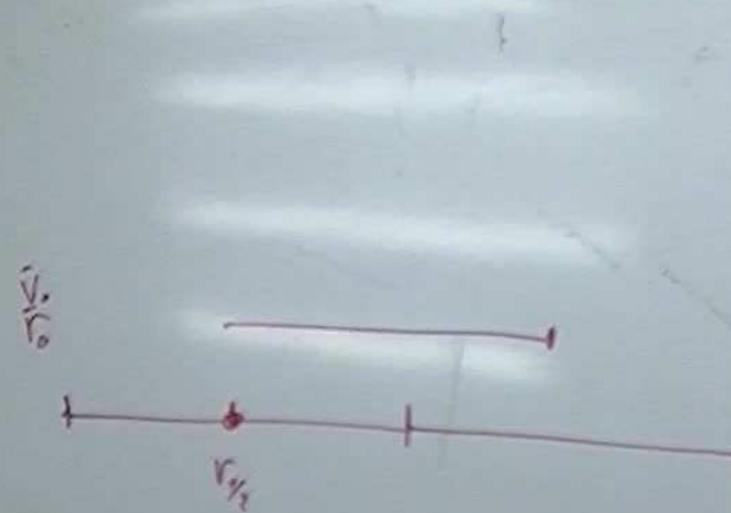
MÉTODO DE EUCKE:

$$\ddot{\bar{r}}_i = (\bar{k}_i + \bar{p})$$

$$S_i(\cdot)$$

$$\bar{r}_{i+1} = S_i(t_{i+1})$$

$$\bar{v}_{i+1} = S_i(t_{i+1})$$



MÉTODO DE COWELL:

$$\tilde{\vec{r}}_{i+1} = (\tilde{\vec{r}}_i + \tilde{\vec{v}}_i) \Delta t$$

$$\tilde{\vec{v}}_{i+1} = (\tilde{\vec{v}}_i + (\ddot{\vec{r}}_i) \Delta t)$$

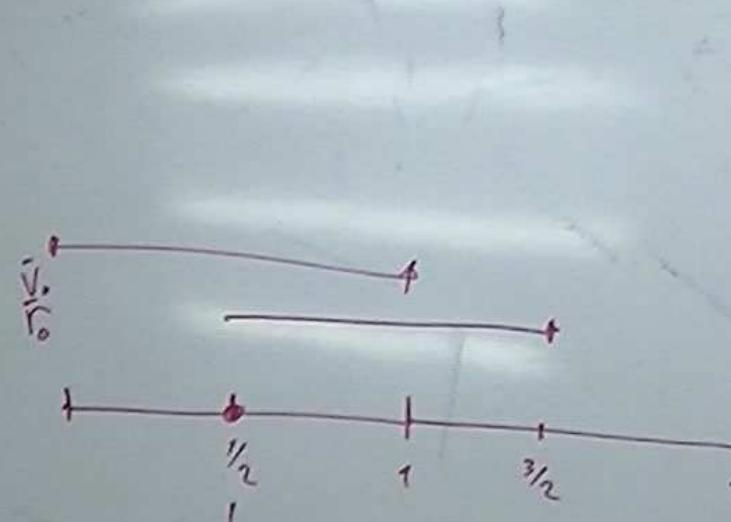
MÉTODO DE EULER:

$$\tilde{\vec{r}}_i = (\tilde{\vec{r}}_i + \tilde{\vec{p}}_i)$$

$$S_i(\tilde{\vec{r}}_i, \tilde{\vec{v}}_i)$$

$$\tilde{\vec{r}}_{i+1} = S_i(t_{i+1})$$

$$\tilde{\vec{v}}_{i+1} = S_i(t_{i+1}) + (\tilde{\vec{p}}_i) \Delta t$$



MÉTODO DE COWELL:

$$\tilde{\vec{r}}_{i+1} = \tilde{\vec{r}}_i + \tilde{\vec{v}}_i \Delta t$$

$$\tilde{\vec{v}}_{i+1} = \tilde{\vec{v}}_i + \tilde{\vec{r}}_i \Delta t$$

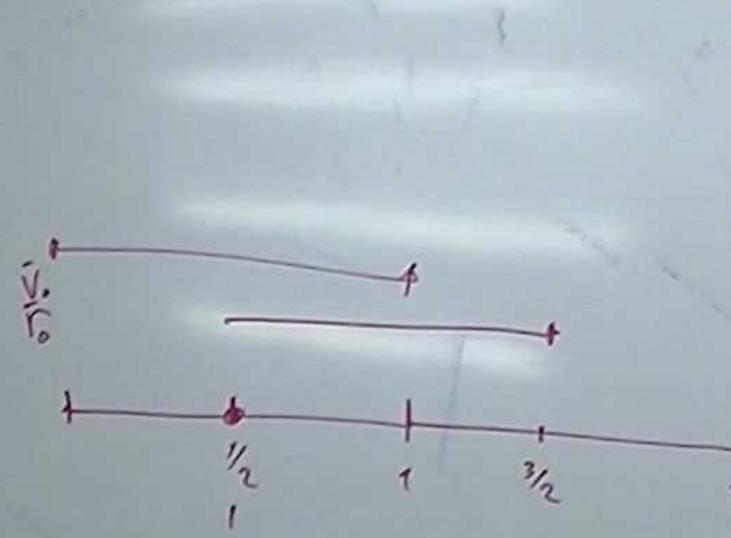
MÉTODO DE EULER:

$$\tilde{\vec{r}}_i = \tilde{\vec{r}}_0 + \tilde{\vec{p}}_i$$

$$S_i(\tilde{\vec{r}}_i, \tilde{\vec{v}}_i)$$

$$\tilde{\vec{r}}_{i+1} = S_i(t_{i+1})$$

$$\tilde{\vec{v}}_{i+1} = S_i(t_{i+1}) + \tilde{\vec{p}}_i \Delta t$$



- AARSETH
- RADAU (RADAU) 1985
- EVOLVANT
- SWIFT (LEVISON-DODDAN) 1994
SYNBA

MÉTODO DE COWELL:

$$\bar{r}_{i+1} = \bar{r}_i + \bar{v}_i \Delta t$$

$$\bar{v}_{i+1} = \bar{v}_i + \bar{r}_i \Delta t$$

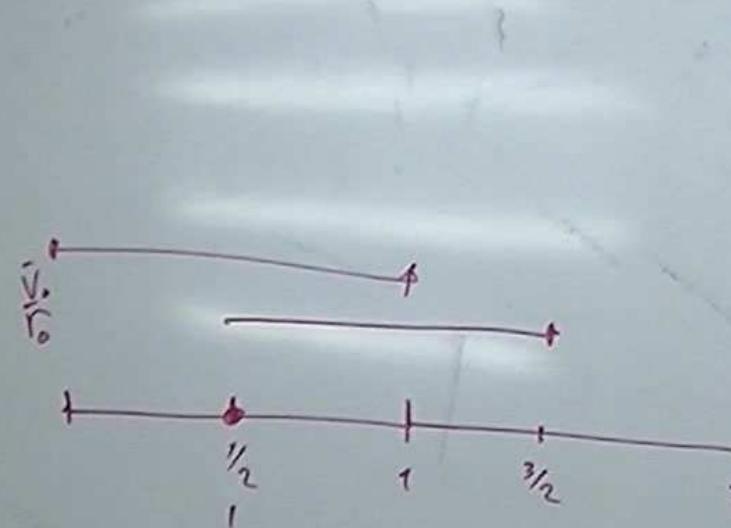
MÉTODO DE EULER:

$$\bar{r}_i = \bar{k}_i + \bar{p}_i$$

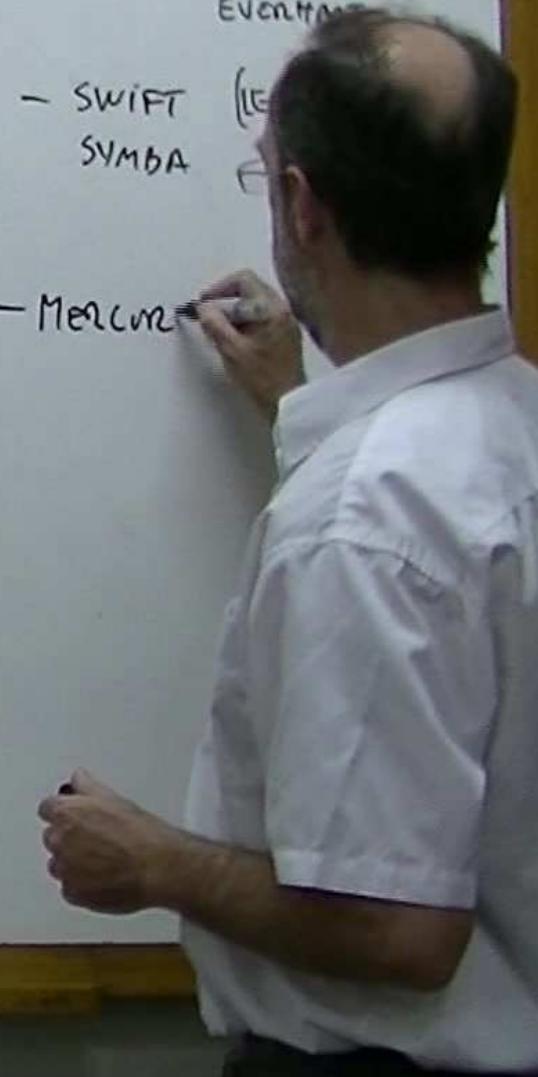
$$S_i(\bar{r}_i, \bar{v}_i)$$

$$\bar{r}_{i+1} = S_i(t_{i+1})$$

$$\bar{v}_{i+1} = S_i(t_{i+1}) + \bar{p}_i \Delta t$$



- AARSETH
- RAMS (RADAU) MPS
- EVENHAN
- SWIFT (LE)
SYMPA
- MERCURY



MÉTODO DE COWELL:

$$\tilde{\vec{r}}_{i+1} = (\tilde{\vec{r}}_i) + (\tilde{\vec{v}}_i) \Delta t$$

$$\tilde{\vec{v}}_{i+1} = (\tilde{\vec{v}}_i) + (\ddot{\vec{r}}_i) \Delta t$$

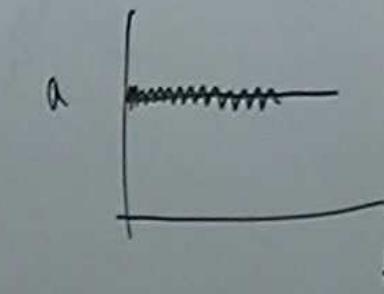
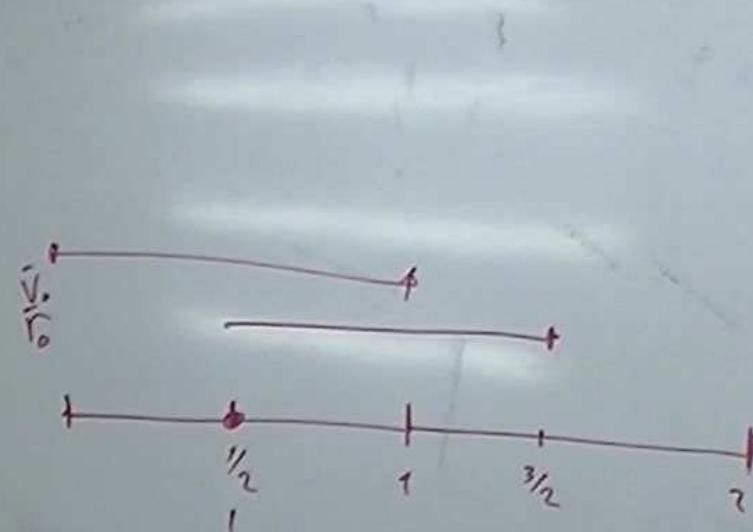
MÉTODO DE EULKE:

$$\tilde{\vec{r}}_i = (\tilde{\vec{r}}_i) + \tilde{\vec{p}}_i$$

$$S_i(\tilde{\vec{r}}_i, \tilde{\vec{v}}_i)$$

$$\tilde{\vec{r}}_{i+1} = S_i(t_{i+1})$$

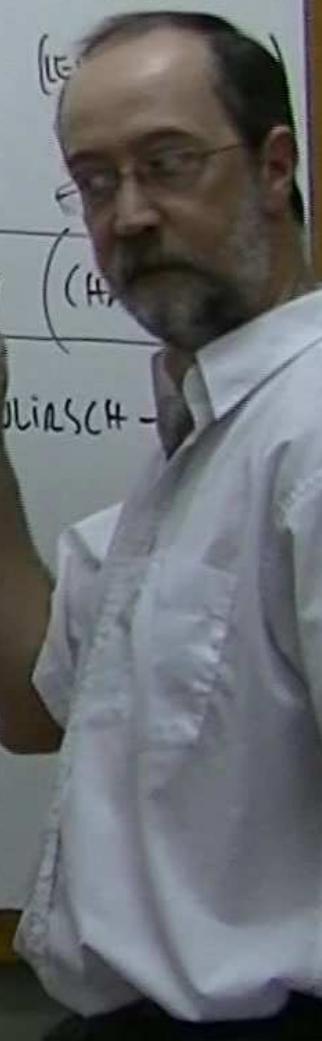
$$\tilde{\vec{v}}_{i+1} = S_i(t_{i+1}) + (\tilde{\vec{p}}_i) \Delta t$$



- AARSETH
- RADAU (RADAU) IIPs
- EVENHANT
- SWIFT (LE) SYMBA

Mercury (H)

OLINSCH-



MÉTODO DE COWELL:

$$\tilde{\mathbf{r}}_{i+1} = (\tilde{\mathbf{r}}_i + \tilde{\mathbf{v}}_i) \Delta t$$

$$\tilde{\mathbf{v}}_{i+1} = (\tilde{\mathbf{v}}_i + \tilde{\mathbf{r}}_i) \Delta t$$

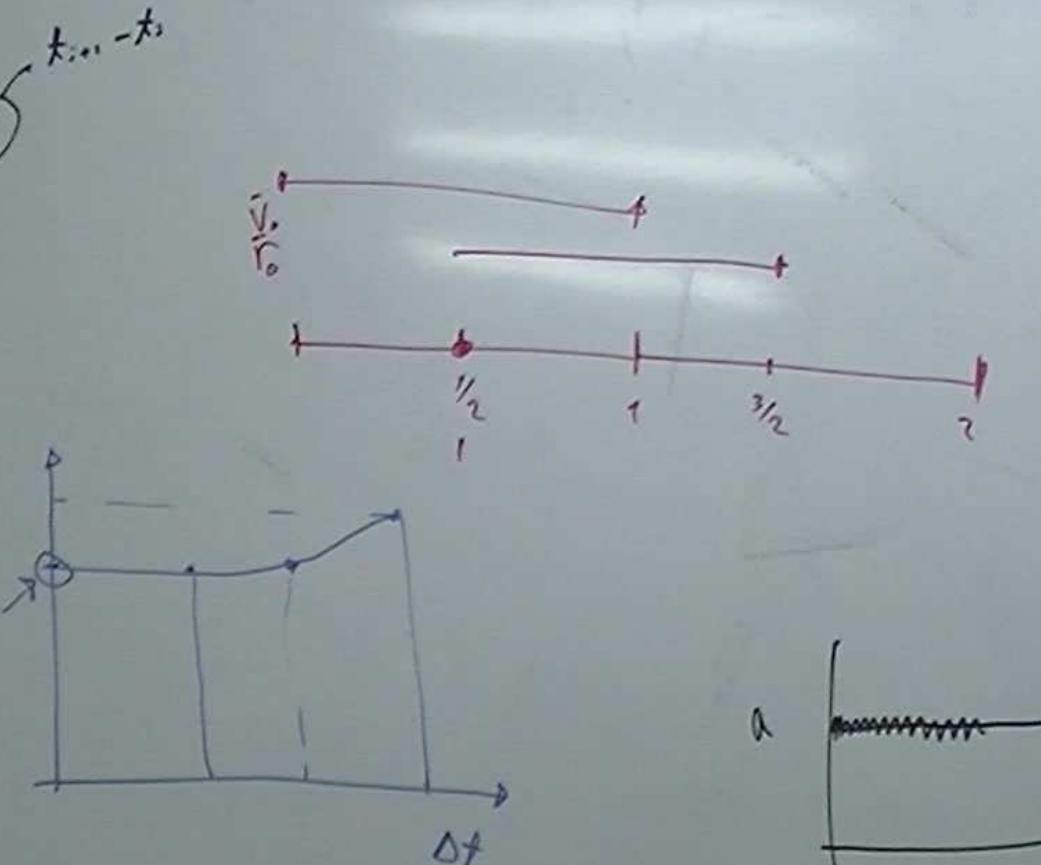
MÉTODO DE EULKE:

$$\tilde{\mathbf{r}}_i = (\tilde{\mathbf{k}}_i + \tilde{\mathbf{p}}_i)$$

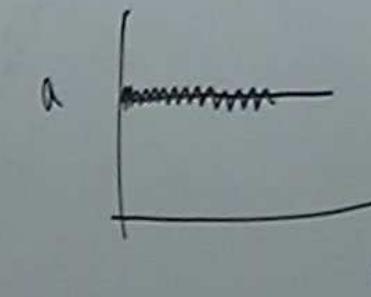
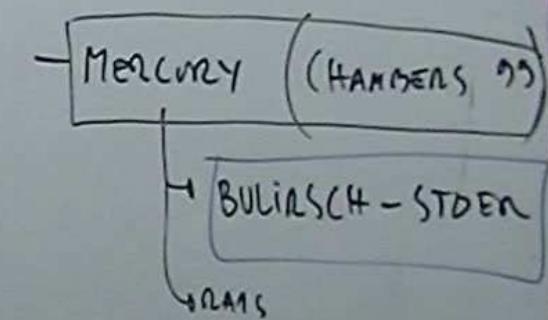
$$S_i(\tilde{\mathbf{r}}_i, \tilde{\mathbf{v}}_i)$$

$$\tilde{\mathbf{r}}_{i+1} = S_i(t_{i+1})$$

$$\tilde{\mathbf{v}}_{i+1} = S_i(t_{i+1}) + (\tilde{\mathbf{p}}_i) \Delta t$$

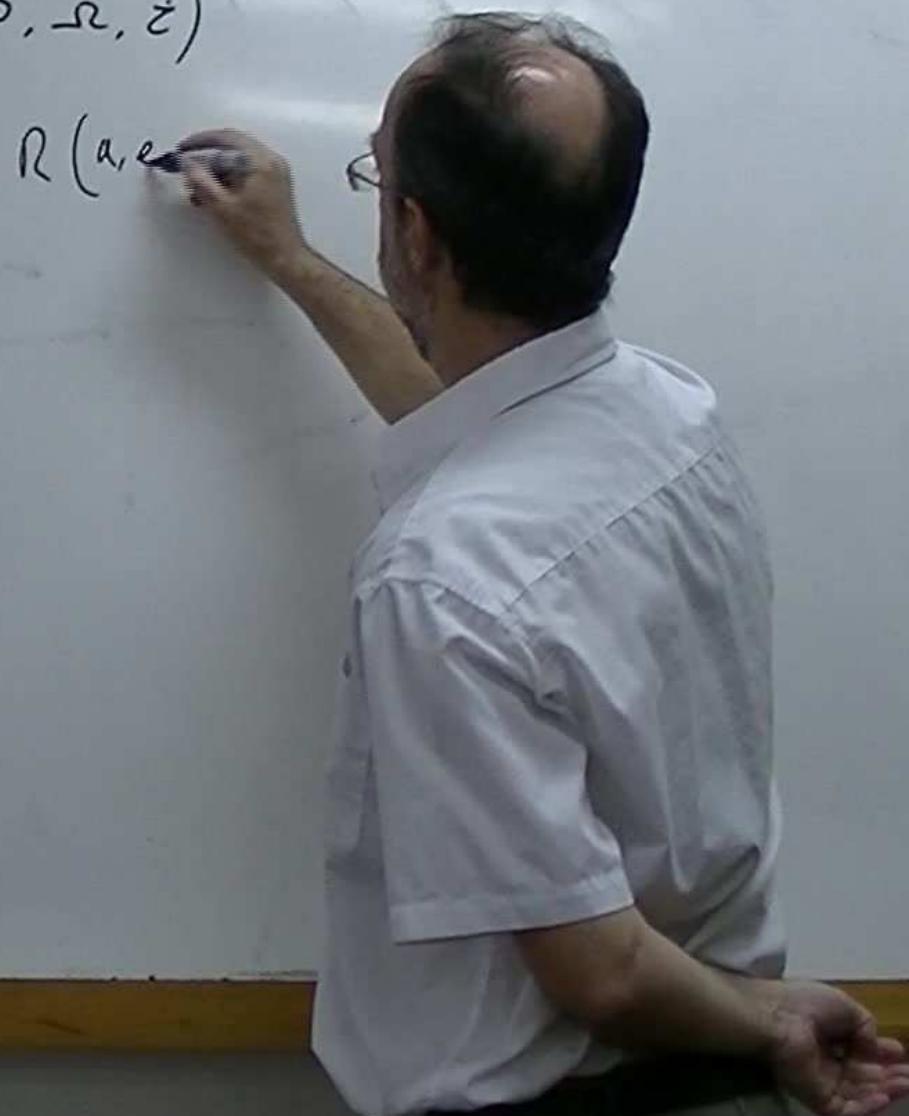


- AARSETH
- RADAU (RADAU) 1985
EVERHART
- SWIFT (LEVISON-DODDAN)
SYMBA 1994



NOTICIAS TEORÍA DE PERTURBACIONES

$$\begin{matrix} T \\ R(\bar{r}) \end{matrix} \left\{ \begin{matrix} T(r) \\ R(a,e) \end{matrix} \right. \Rightarrow (a, e, i, \dot{\omega}, \dot{\nu}, \dot{z})$$



NOTICIONES TEORÍA DE PERTURBACIONES

T.L.

 $\vec{r}(t)$ $\Rightarrow (a, e, i, \omega, \Omega, \dot{\varphi})$ $R(a, e, i, \dots)$

LAGRANGE

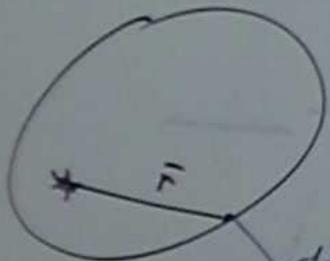


NOTICIONES TEORÍA DE PERTURBACIONES

$$\left. \begin{array}{l} \vec{r} \\ \dot{\vec{r}} \\ R(\vec{r}) \end{array} \right\} \vec{r}(t) \Rightarrow (a, e, i, \omega, \Omega, \zeta) \\ R(a, e, i, \dots)$$

LAGRANGE

GAUSS



$$d\vec{F} = R \cdot \hat{r} + T \cdot \hat{\theta} + N \cdot \hat{\gamma}$$

$$d\varepsilon = d\vec{r} \cdot \delta \vec{F}$$



NOCIÓN DE TEORÍA DE PERTURBACIONES

$$\left. \begin{array}{l} T = T(r) \\ R(\vec{r}) \end{array} \right\} \vec{F}(r) \rightarrow (a, e, i, \omega, \Omega, \zeta)$$

LAGRANGE

GAUSS

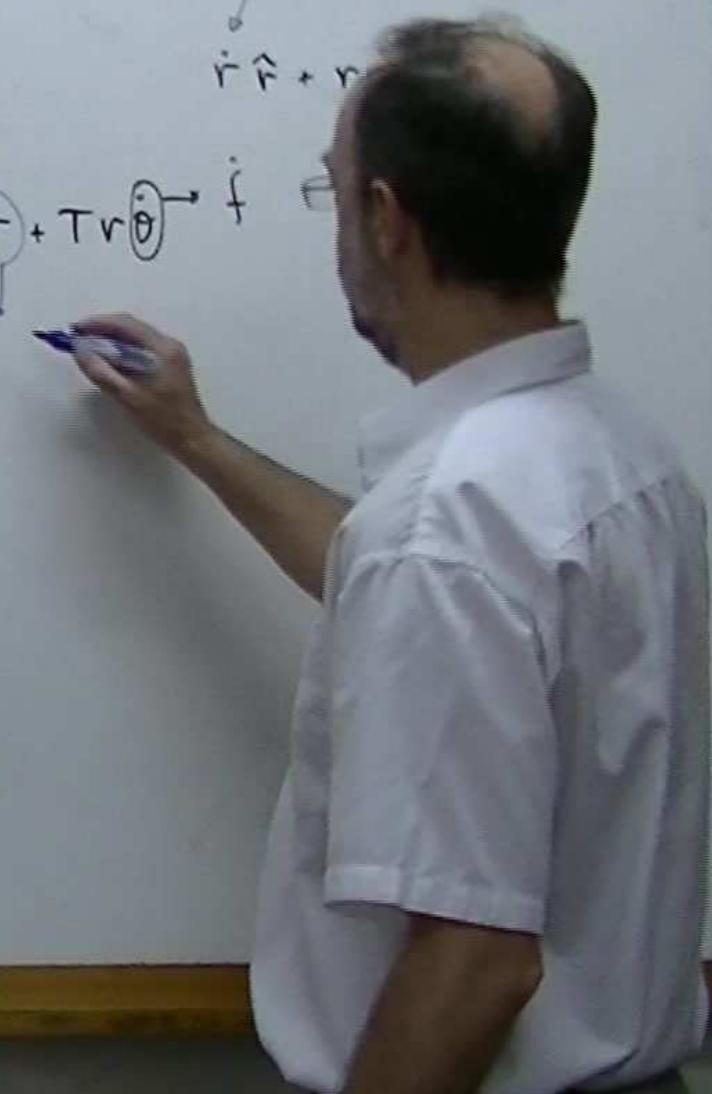


$$\vec{dF} = R \cdot \hat{r} + T \cdot \hat{\theta} + N \cdot \hat{\gamma}$$

$$\frac{d\varepsilon}{dt} = \frac{d\vec{r}}{dt} \cdot \vec{dF} = \dot{\vec{r}} \cdot \vec{dF}$$

$\dot{\vec{r}} \cdot \vec{dF} + \dots$

$$\frac{d\varepsilon}{dt} = R \dot{r} + Tr \dot{\theta} \rightarrow \dot{\varepsilon}$$



NOCIONES TEÓRICAS DE PERTURBACIONES

$$\left. \begin{array}{l} \vec{r} \\ \dot{\vec{r}} \\ \ddot{\vec{r}} \end{array} \right\} \vec{r}(t) \quad \Rightarrow (\dot{a}, e, i, \omega, \Omega, \zeta) \\ R(\vec{r}) \quad \quad \quad R(a, e, i, \dots)$$

LAGRANGE

GAUSS

$$d\vec{F} = R \cdot \hat{r} + T \cdot \hat{\theta} + N \cdot \hat{n}$$

$$\frac{d\varepsilon}{dt} = \frac{d\vec{r}}{dt} \cdot \vec{F} = \dot{\vec{r}} \cdot \vec{F}$$

$\dot{r} \hat{r} + r \dot{\theta} \hat{\theta}$

$$\frac{d\varepsilon}{dt} = R \dot{r} + T r \dot{\theta} \rightarrow \dot{f} \rightarrow \frac{h}{r^2} \quad r^2 \dot{f} = h$$

(r, f)

$$\varepsilon = -\frac{f}{2a}$$

$$\dot{\varepsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\dot{a} = R, T, r$$

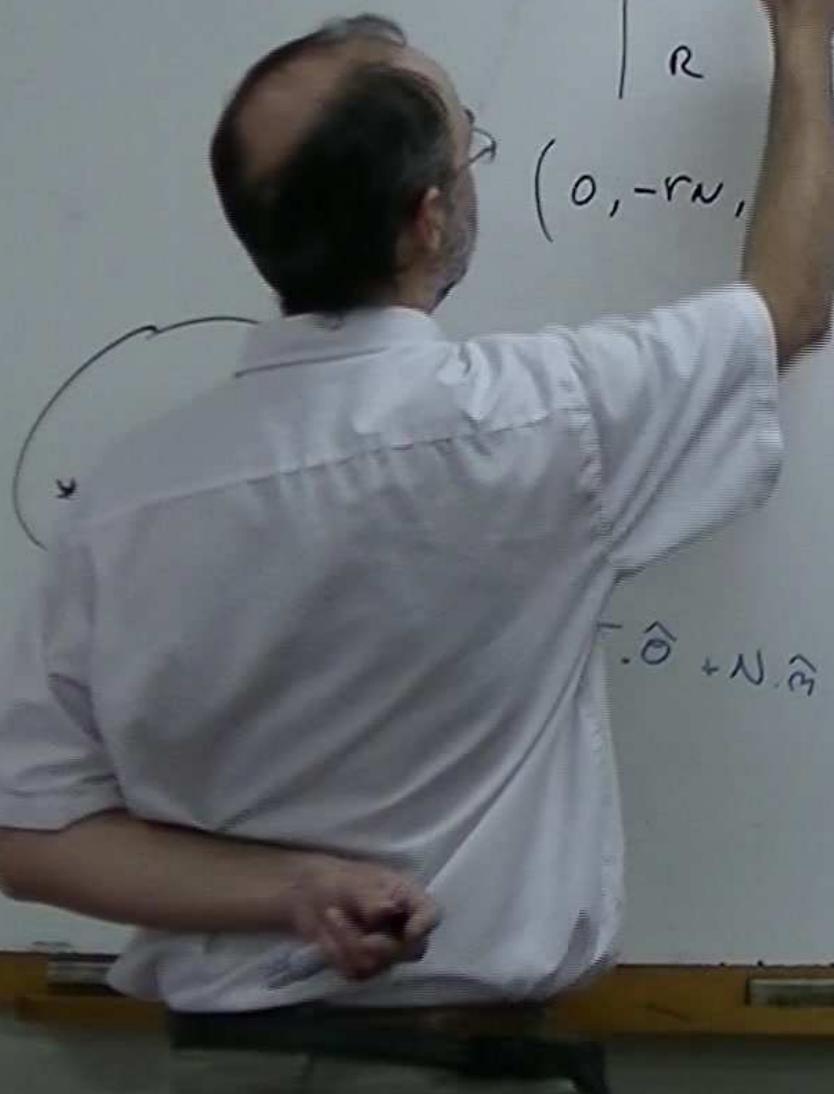
NOACIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} = \vec{F} \wedge \vec{\delta F}$$

$$\begin{vmatrix} i & \dot{r} \\ r & 0 \\ R & N \end{vmatrix}$$

$$(0, -rn,$$

GAUSS



$$\frac{d\epsilon}{dt} = \frac{d\vec{r}}{dt} \cdot \vec{\delta F} = \dot{\vec{r}} \cdot \vec{\delta F}$$

$$\dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\frac{d\epsilon}{dt} = R\dot{r} + Tr\dot{\theta} \rightarrow \dot{f} \rightarrow \frac{h}{r^2} \quad r^2 \dot{f} = h$$

$$\epsilon = -\frac{f}{2a}$$

$$\dot{\epsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\dot{a} = R, T, r$$

NOACIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} = \vec{F} \wedge \vec{\delta F} = -rN\hat{\theta} + rT\hat{\alpha}$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ r & 0 & 0 \\ R & TN & \end{vmatrix}$$

$$(0, -rN, rT)$$



$$d\vec{F} = R\cdot\hat{r} + T\cdot\hat{\theta} + N\cdot\hat{\alpha}$$

$$\frac{d\varepsilon}{dt} = \frac{d\vec{r}}{dt} \cdot \vec{\delta F} = (\dot{\vec{r}}) \cdot \vec{\delta F}$$

$$\dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\frac{d\varepsilon}{dt} = R(\dot{r}) + Tr(\dot{\theta}) \rightarrow \frac{h}{r^2} \quad r^2\dot{f} = h$$

$$\varepsilon = -\frac{f}{2a}$$

$$\dot{\varepsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\dot{a} = R, T, r$$

NOACIONES TEORÍA DE PERTURBACIONES

$$\frac{d\bar{h}}{dt} = \bar{F} \wedge \bar{\delta F} = -rN\hat{\theta} + rT\hat{\alpha}$$

$$\dot{h} = \sqrt{mu(r)} \Rightarrow \dot{e}$$

$$\bar{h} = h \cdot \hat{h} \Rightarrow \frac{d\bar{h}}{dt} = \left[\frac{dh}{dt} \hat{h} + h \cdot \frac{d\hat{h}}{dt} \right]$$

$$\frac{d\varepsilon}{dt} = \frac{d\bar{r}}{dt} \cdot \bar{\delta F} = \dot{\bar{r}} \cdot \bar{\delta F}$$

$$\dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\frac{d\varepsilon}{dt} = R\dot{r} + Tr\dot{\theta} \rightarrow \dot{f} \xrightarrow{(r, f)} \frac{h}{r^2} \quad r^2 \dot{f} = h$$

$$\varepsilon = -\frac{f}{2a}$$

$$\dot{\varepsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\dot{a} = R, T, r$$

NOCIONES TEORÍA DE PERTURBACIONES

$$\frac{d\bar{h}}{dt} = \bar{F} \wedge \bar{\delta F} = -rN\hat{\theta} + rT\hat{\alpha}$$

$$h = \sqrt{\mu a(1-e^2)} \quad \Rightarrow \dot{e}$$

$$\bar{h} = h \cdot \hat{h} \Rightarrow \frac{d\bar{h}}{dt} = \left[\frac{dh}{dt} \hat{h} + h \cdot \frac{d\hat{h}}{dt} \right]$$

$$\frac{dh}{dt} = r \cdot T$$

$$\varepsilon = -\frac{f}{2a}$$

$$\dot{\varepsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\frac{d\varepsilon}{dt} = \frac{d\bar{r}}{dt} \cdot \bar{\delta F} = \dot{\bar{r}} \cdot \bar{\delta F}$$

$$r^2 \dot{f} = h$$

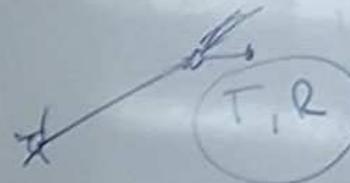
$$\frac{d\varepsilon}{dt} = R\dot{r} + Tr\dot{\theta} \rightarrow \dot{f}$$

$$\dot{a} = R, T, r$$

DUNTO A (*) $\Rightarrow \dot{e} = T, R \dots$

NOCIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} = \vec{r} \wedge \vec{F} = -rN\hat{\theta} + rT\hat{\alpha}$$



$$\frac{d\varepsilon}{dt} = \frac{d\vec{r}}{dt} \cdot \vec{F} = \dot{\vec{r}} \cdot \vec{F}$$

$$h = \sqrt{\mu a(1-e^2)} \Rightarrow$$

$$\vec{h} = h \cdot \hat{h} = h \begin{pmatrix} \hat{x} \\ \hat{y} \\ \hat{z} \end{pmatrix}$$

$$\frac{d\varepsilon}{dt} = R\dot{r} + Tr\dot{\theta} \Rightarrow \dot{f} = \frac{h}{r^2} \quad r^2 \dot{f} = h$$

$$\varepsilon = -\frac{f}{2a}$$

$$\dot{\varepsilon} = \frac{f}{2a^2} \cdot \dot{a}$$

$$\dot{a} = R, T, r$$

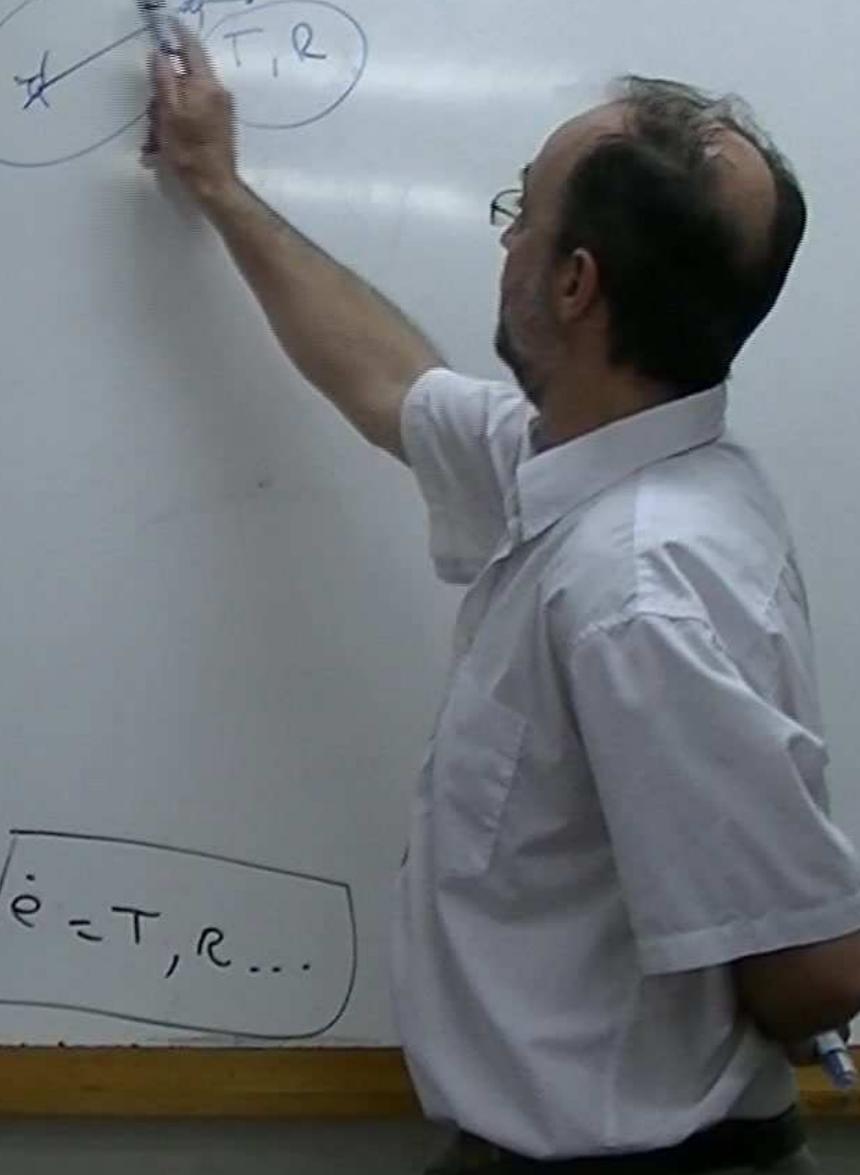
* $\Rightarrow \dot{\varepsilon} = T, R \dots$

NOACIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} = \vec{F} \wedge \vec{df} = -rN\hat{\theta} + rT\hat{A}$$

$$h = \sqrt{\mu a(1-e^2)} \stackrel{(2)}{\Rightarrow} \dot{e}$$

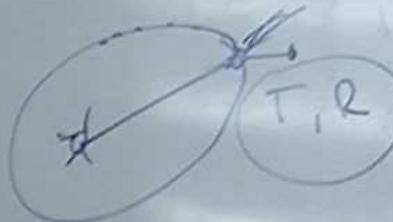
$$\tilde{h} = h \cdot \hat{h} \Rightarrow \frac{d\tilde{h}}{dt} = \left[\frac{dh}{dt} \hat{h} + h \cdot \hat{h} \cdot \frac{d\hat{h}}{dt} \right] \stackrel{(3)}{\Rightarrow} \frac{dh}{dt} = r \cdot T$$



$$\text{JUNTO A } (2) \Rightarrow \dot{e} = T, R \dots$$

NOTICIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} = \vec{F} \wedge \vec{df} = -rN\hat{\theta} + rT\hat{A}$$



$$h = \sqrt{mu(1-e^2)} \quad \text{---} \quad \dot{e} = \frac{de}{dt}$$

$$\tilde{h} = h \cdot \hat{h} \Rightarrow \frac{d\tilde{h}}{dt} = \left[\frac{dh}{dt} \hat{h} + h \cdot \frac{d\hat{h}}{dt} \right]$$

$$\frac{dh}{dt} = r \cdot T$$

JUNTO A (*) $\Rightarrow \dot{e} = T, R \dots$

EC. MEDIAS

$$\langle \dot{a} \rangle = \frac{1}{2\pi} \int_0^{2\pi} \dot{a}(r, T, \xi) d\xi$$



NOACIONES TEORÍA DE PERTURBACIONES

$$\frac{dh}{dt} \hat{h} + h \frac{d\hat{h}}{dt}$$

$\rightarrow r.T$

$$\frac{dh}{dt} = r.T$$

JUNTO A $\star \Rightarrow \dot{\epsilon} = T, R \dots$

EC. MEDIAS

$$\langle \dot{a} \rangle = \frac{1}{2\pi} \int_0^{2\pi} \dot{a} dm$$

$$\dot{a}(r, t, \xi)$$

$$(r)T(\xi)$$

$$r^2 f = h$$

$$r^2 dt = h \cdot dt = h \cdot \frac{dm}{m} \Rightarrow dm = \frac{m}{h} \cdot r^2 dt$$

$$m = m \cdot t$$

$$dm = m \cdot dt$$

NOCIONES TEORÍA DE PERTURBACIONES

T, R const

$$\langle \dot{a} \rangle = 0 \cdot T$$

\Rightarrow Evolución secular

$a, e, i, \omega, \Omega, \dots$

EC. MEDIAS

$$\langle \dot{a} \rangle = \frac{1}{2\pi} \int_0^{2\pi} \dot{a}(r, t, \xi) d\eta$$

$$r^2 \dot{f} = h$$

$$r^2 \dot{d}t = h \cdot dt = h \cdot \frac{dm}{m} \Rightarrow dm = \frac{m}{h} \cdot r^2 dt$$

$$m = m \cdot t$$

$$dm = m \cdot dt$$

NOACIONES TEORÍA DE PERTURBACIONES

T, R OTROS

$$\langle \dot{a} \rangle = \odot \cdot T$$

⇒ EVOLUCIÓN SECUNDARIA

a, e, i, ω, n, ...

EC. MEDIAS

$$\langle \dot{a} \rangle = \frac{1}{2\pi} \int_0^{2\pi} \dot{a}(r, t, \xi) d\eta$$

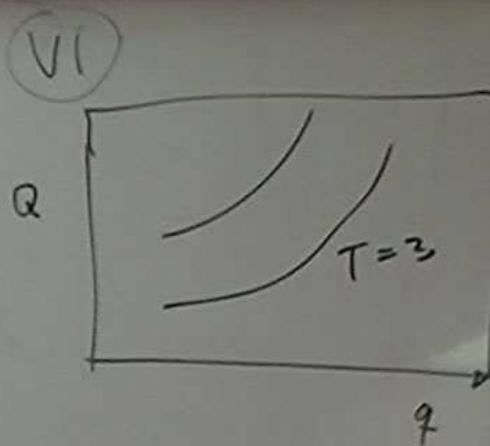
$$r^2 f = h$$

$$r^2 (\dot{\lambda} t) = h \cdot dt = h \cdot \frac{dM}{m} \Rightarrow dM = \frac{m}{h} \cdot r^2 \lambda t$$

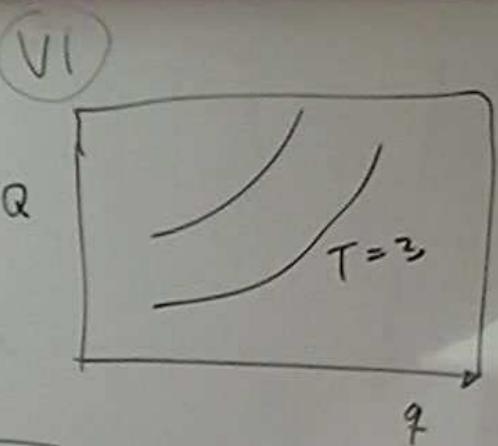
$$M = m \cdot t$$

$$dM = m \cdot dt$$

① $T(q, \dot{q})$
 $i=0$



$$\textcircled{1} \quad T(q, Q)_{i=0}$$

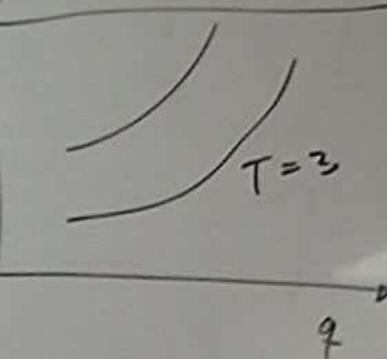


$$\boxed{T = 3 \\ q = 1 \\ Q = 1}$$

$$U = \sqrt{3 - T}$$

(2)

$$\textcircled{1} \quad T(q, Q)$$

 $i=0$ \textcircled{VI} Q 

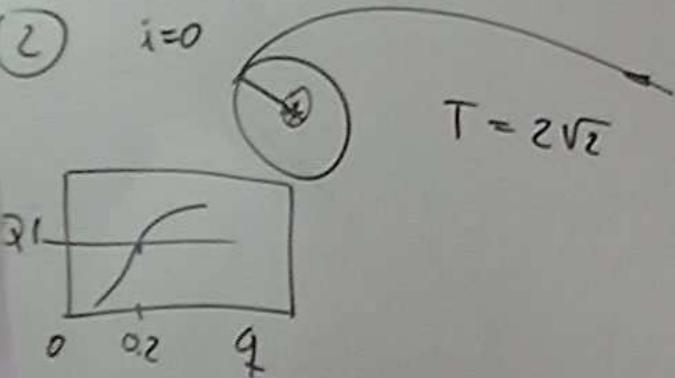
$$T = 3$$

$$q = 1$$

$$Q = 1$$

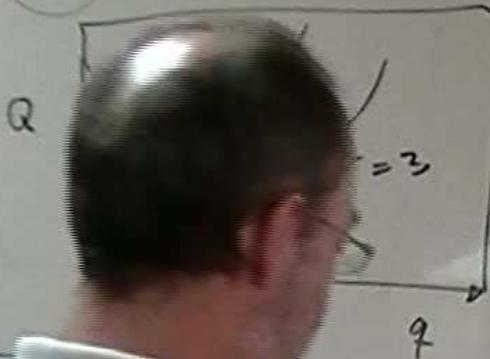
$$U = \sqrt{3 - T}$$

$$\textcircled{2} \quad i=0$$



① $T(q, Q)$
 $i=0$

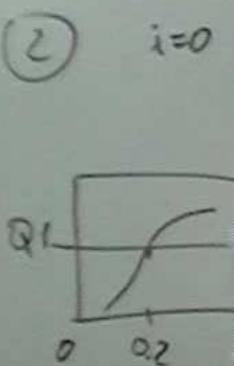
(VI)



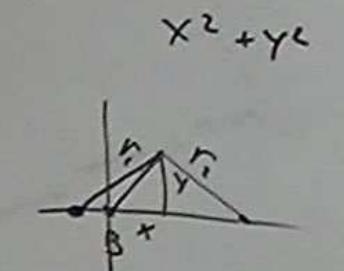
$$\begin{aligned} T &= 3 \\ q &= 1 \\ Q &= 1 \end{aligned}$$

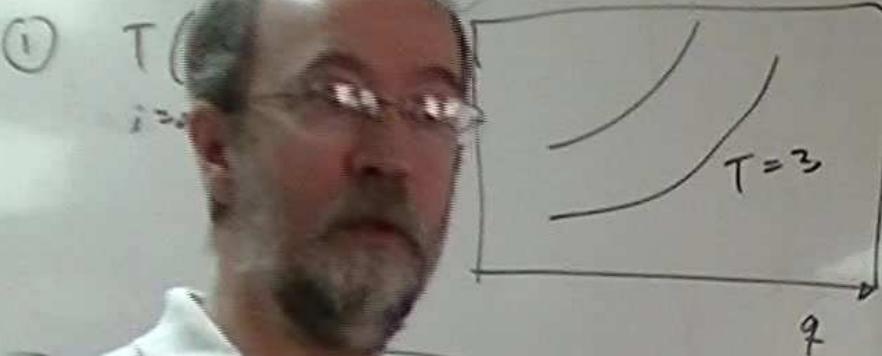
$$U = \sqrt{3-T}$$

② $i=0$



③ $\begin{aligned} z &= 0 \\ N^2 &= 0 \end{aligned}$



(1) T 

(2)

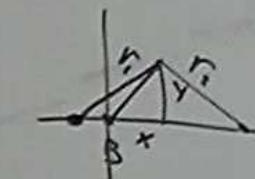
$$z^2 = 2\sqrt{2}$$

$$\begin{cases} T = 3 \\ g = 1 \\ Q = 1 \end{cases}$$

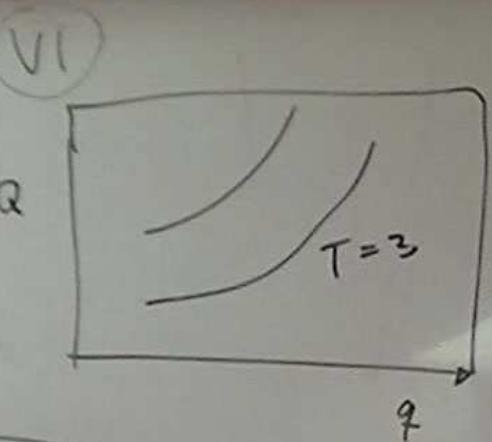
$$U = \sqrt{3-T}$$

$$\begin{cases} z = 0 \\ N^2 = 0 \end{cases}$$

$$P \subset (r_1, r_2, \mu)$$



$$C_{min} = 3 - \mu(1-\mu) \approx 2.999$$

(1) $T(q, Q)$ 

$$\begin{cases} T = 3 \\ q = 1 \\ Q = 1 \end{cases}$$

$$U = \sqrt{3-T}$$

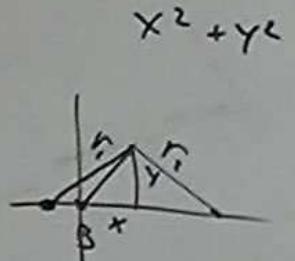
$$T = 2\sqrt{2}$$



~~q~~
~~Q~~

(3)

$$\begin{cases} z = 0 \\ N^2 = 0 \end{cases}$$

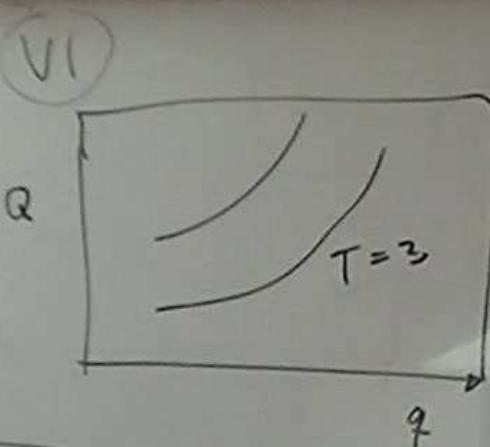


$$\Rightarrow C(r_1, r_2, \mu)$$

$$C_{\min} = 3 - \mu(1-\mu) \approx 2.99,$$

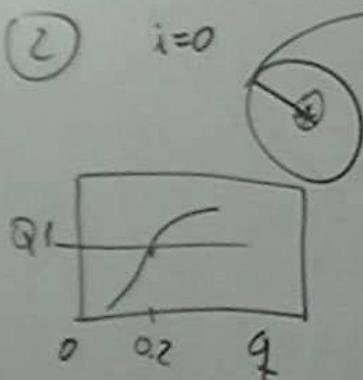
$$\textcircled{1} \quad T(q, Q)$$

$i=0$



$$\begin{cases} T = 3 \\ q = 1 \\ Q = 1 \end{cases}$$

$$U = \sqrt{3-T}$$

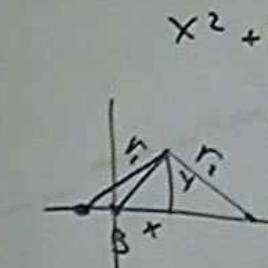


$$T = 2\sqrt{2}$$

$$\ddot{\gamma} = -\dot{\gamma}$$

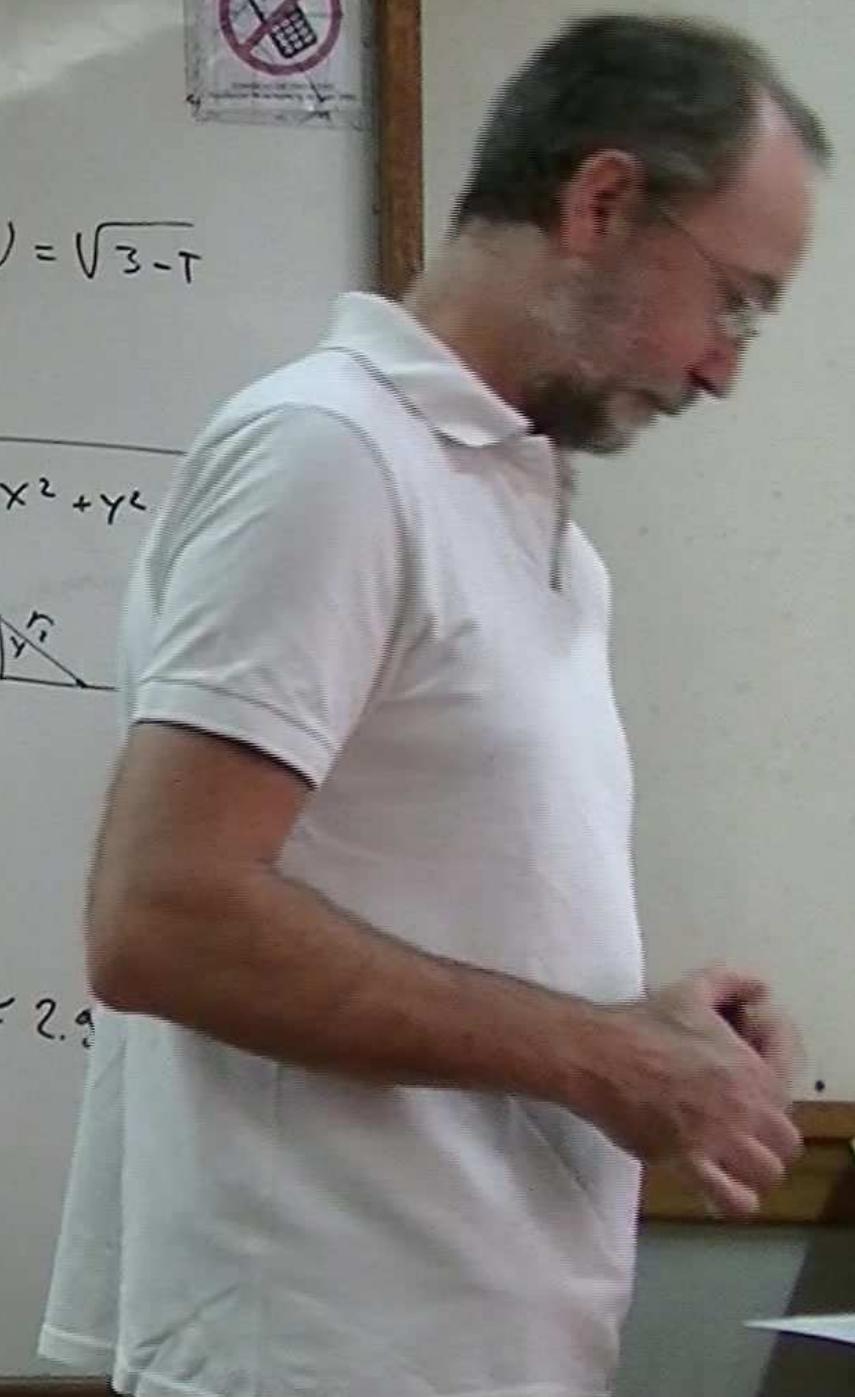
~~γ~~ $\cdot \dot{\gamma} \ddot{\gamma}$

(3) $\begin{cases} z=0 \\ N^z=0 \end{cases}$

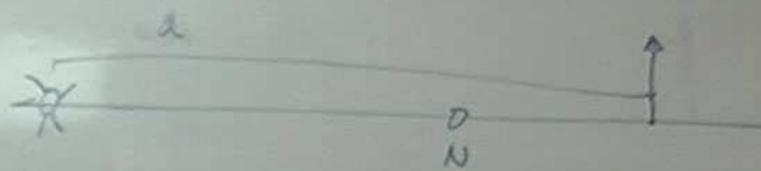


$$\Rightarrow C(r_1, r_2, \mu)$$

$$C_{\min} = 3 - \mu(1-\mu) \approx 2.9$$



(9)



$$\mu = 0.00005$$

$$d \in (x, y, r, \alpha)$$

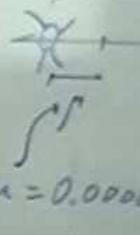
$$m = \frac{2}{3} M_0$$

$$M =$$



(9)

$$a = r_e$$

D
N

$$\mu = 0.00005$$

$$dC(x, y, \mu, \nu)$$

$$m = \frac{2}{3} M_{\odot} \rightarrow$$

$$h^2(M_0 + M_{\odot})$$



$$m = \sqrt{\frac{h^2}{a^3}}$$

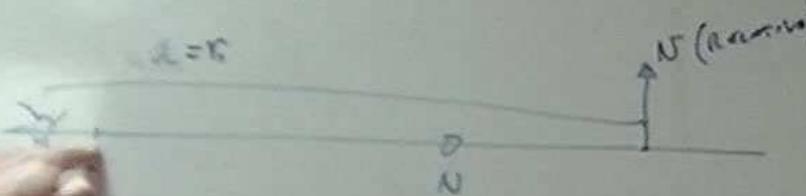
$$(M) = \bar{a}^{3/2}$$

$$\frac{2}{3} \rightarrow a = r_e$$

$$\alpha = r_0$$

$$\mu = 0.00005$$

$$dC(x, r, \gamma, \delta)$$



$$1. (r, -r)$$

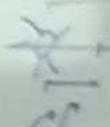
$$M = \frac{2}{3} M_{\odot}$$

$$M = \sqrt{\frac{R^3 (M_0 + M_{\odot})}{a^3}}$$

$$(M) = \bar{a}^{3/2}$$

$$V^2 = \left(\frac{2}{r} - \frac{1}{a} \right)^{\frac{2}{3}} \rightarrow a = r$$

$$\lambda = r_0$$



$$\mu = 0.00005$$

$\mathcal{C}(x, y, \gamma, \delta)$

N (radio)

N

$$M = \frac{2}{3} M_{\odot}$$

$$R^2(M_0 + M_{\text{ter}})$$



$$(M) = \sqrt{\frac{r}{a^3}}$$

$$(M) = \bar{a}^{3/2}$$

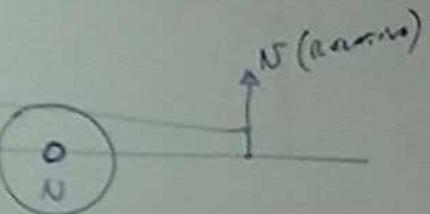
$$V^2 = \left(\frac{2}{r} - \frac{1}{a} \right)^{\frac{2}{3}} \rightarrow a = r$$

$$V^2 = \frac{1}{a}$$

VEL NEL SIST.

$$1. (r_1, -r)$$

$$N_{n_{0,ss}} = \bar{a}^{1/2} - r_1 + \lambda$$



$$M = \frac{2}{3} M_{\odot}^{1/2}$$

$$M = \sqrt{\frac{R^3 (M_{\odot} + M_{\text{ter}})}{a^3}}$$

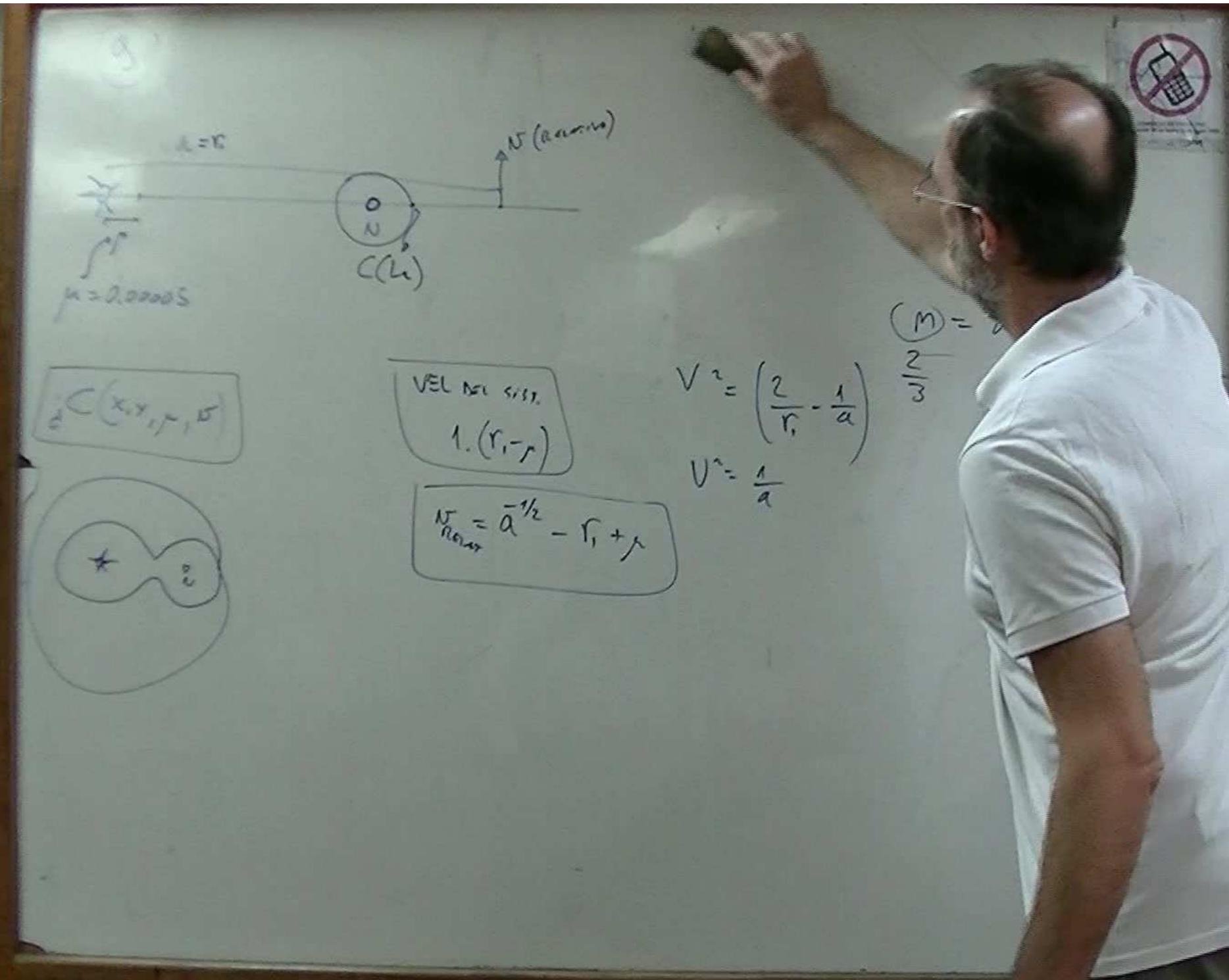
$$(M) = \bar{a}^{3/2}$$

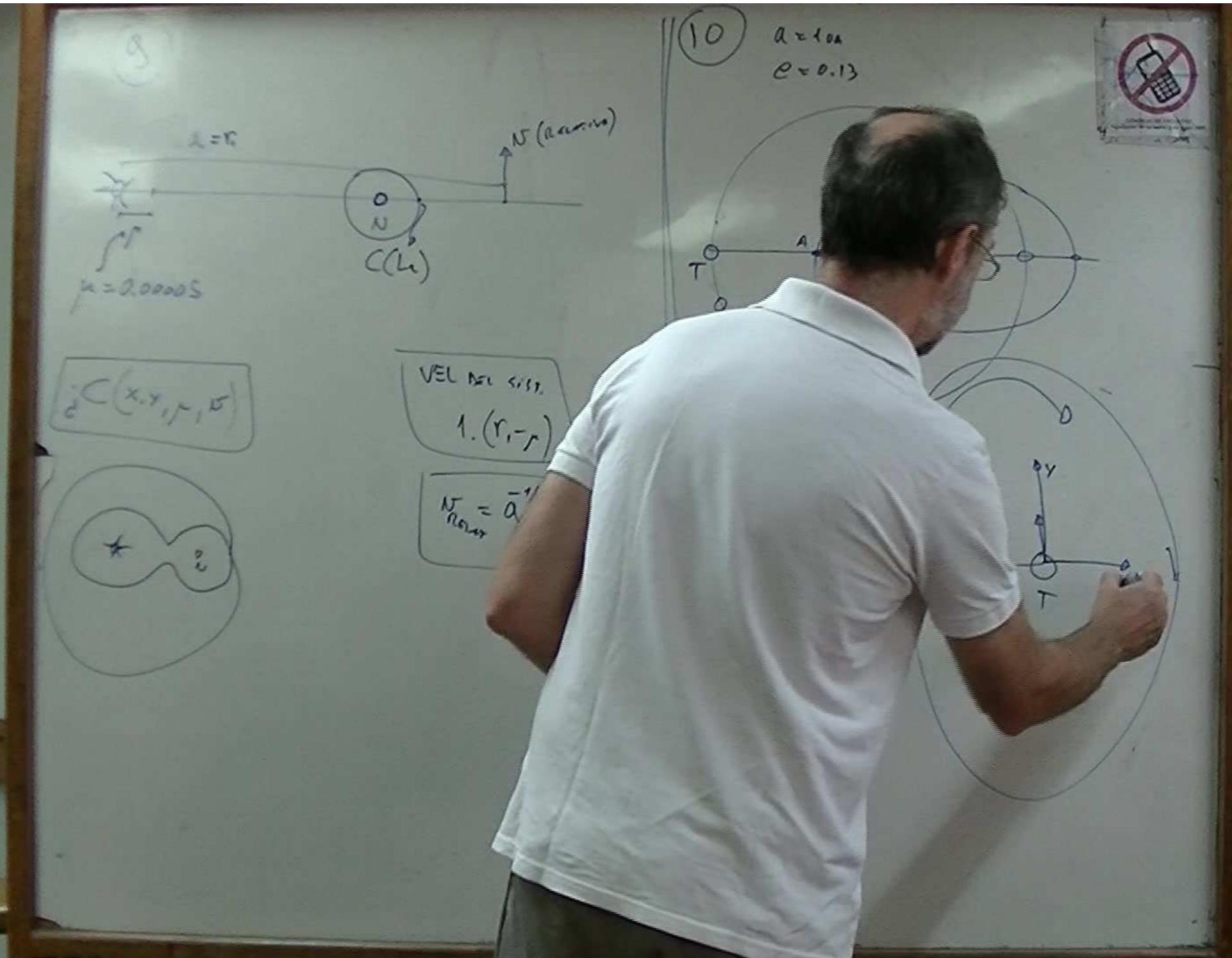
$$V^2 = \left(\frac{2}{r_i} - \frac{1}{a} \right)^{\frac{2}{3}} \rightarrow a = r_i$$

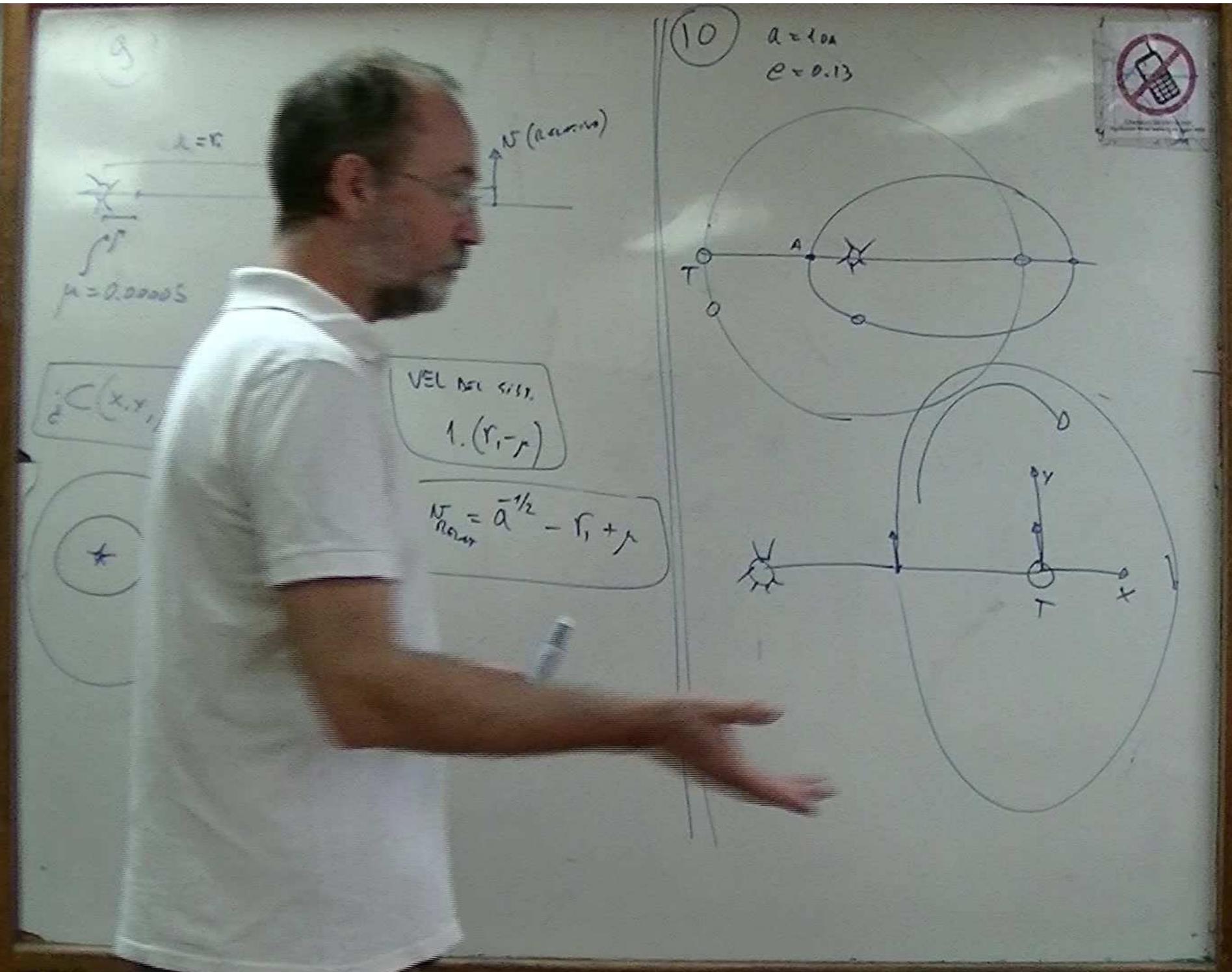
$$V^2 = \frac{1}{a}$$

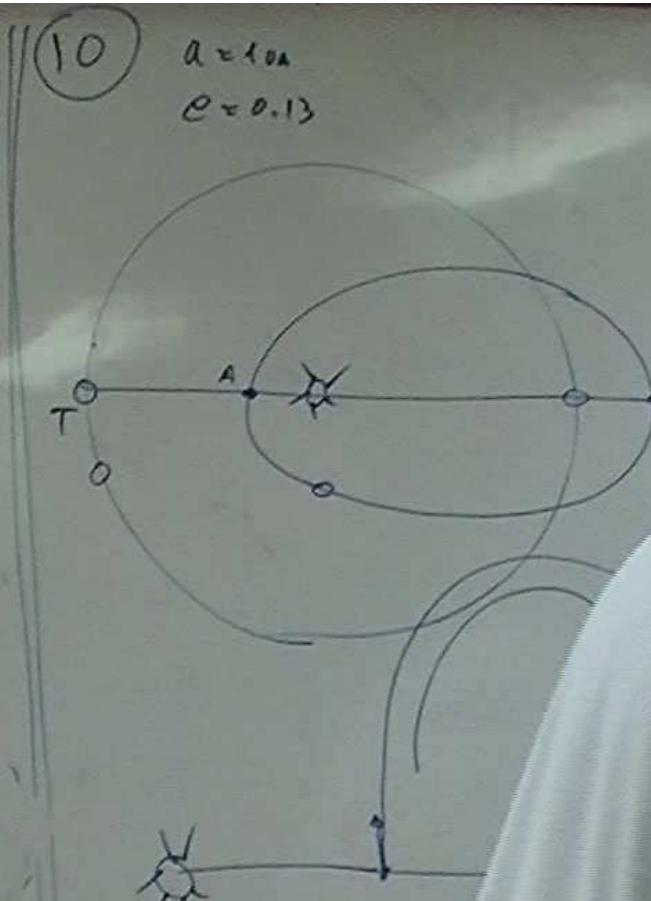
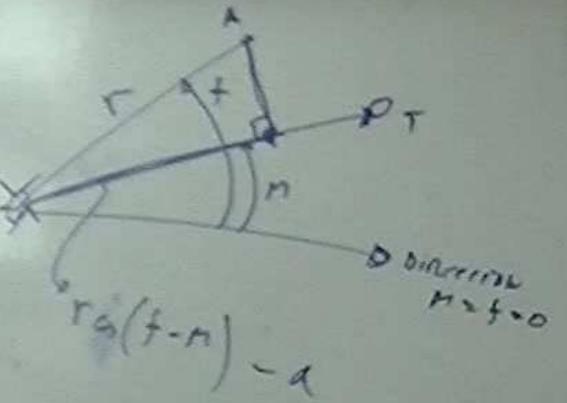
VEL NEL SIST.
1. $(r_i, -r)$

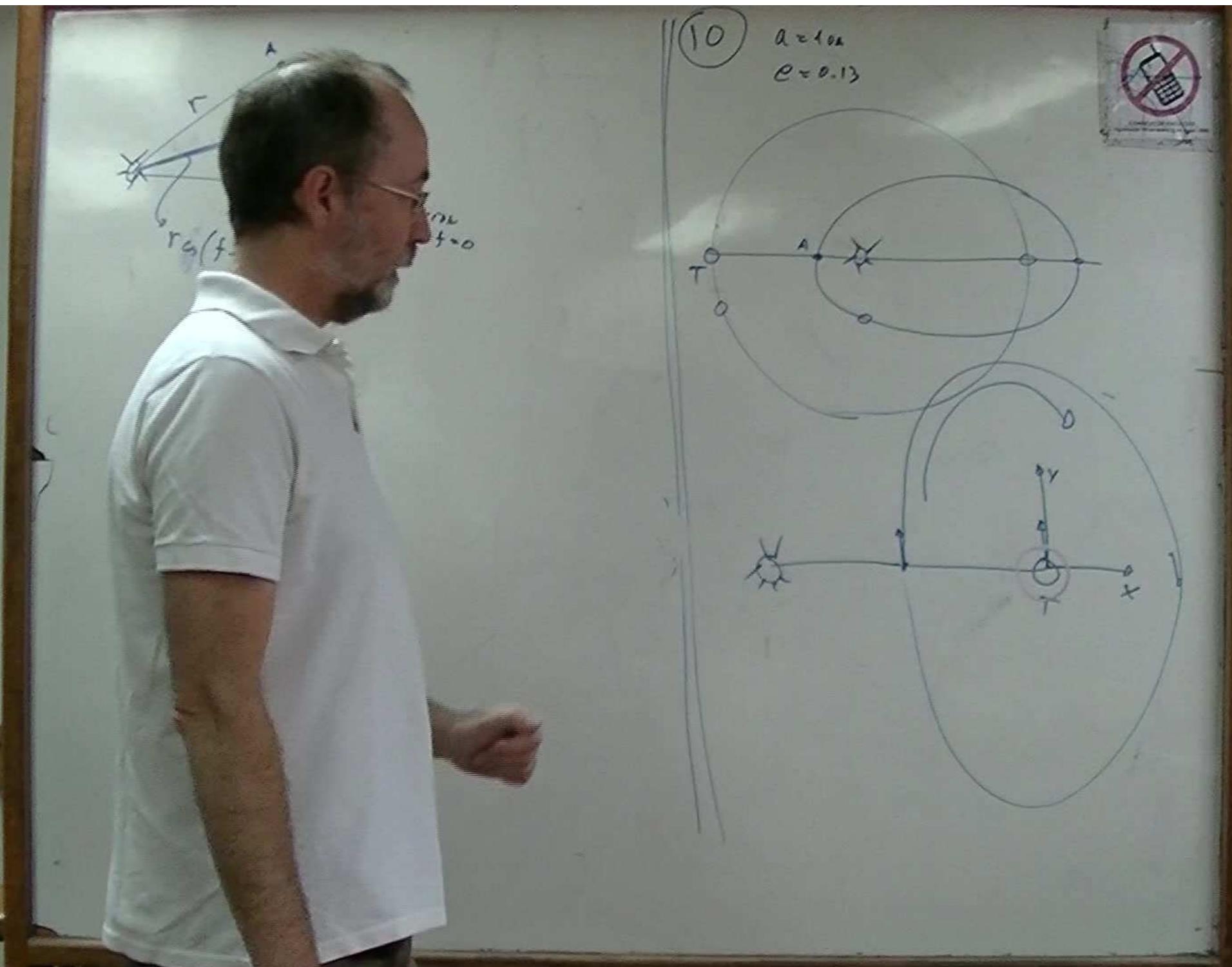
$$N_{\text{relax}} = \bar{a}^{1/2} - r_i + \lambda$$

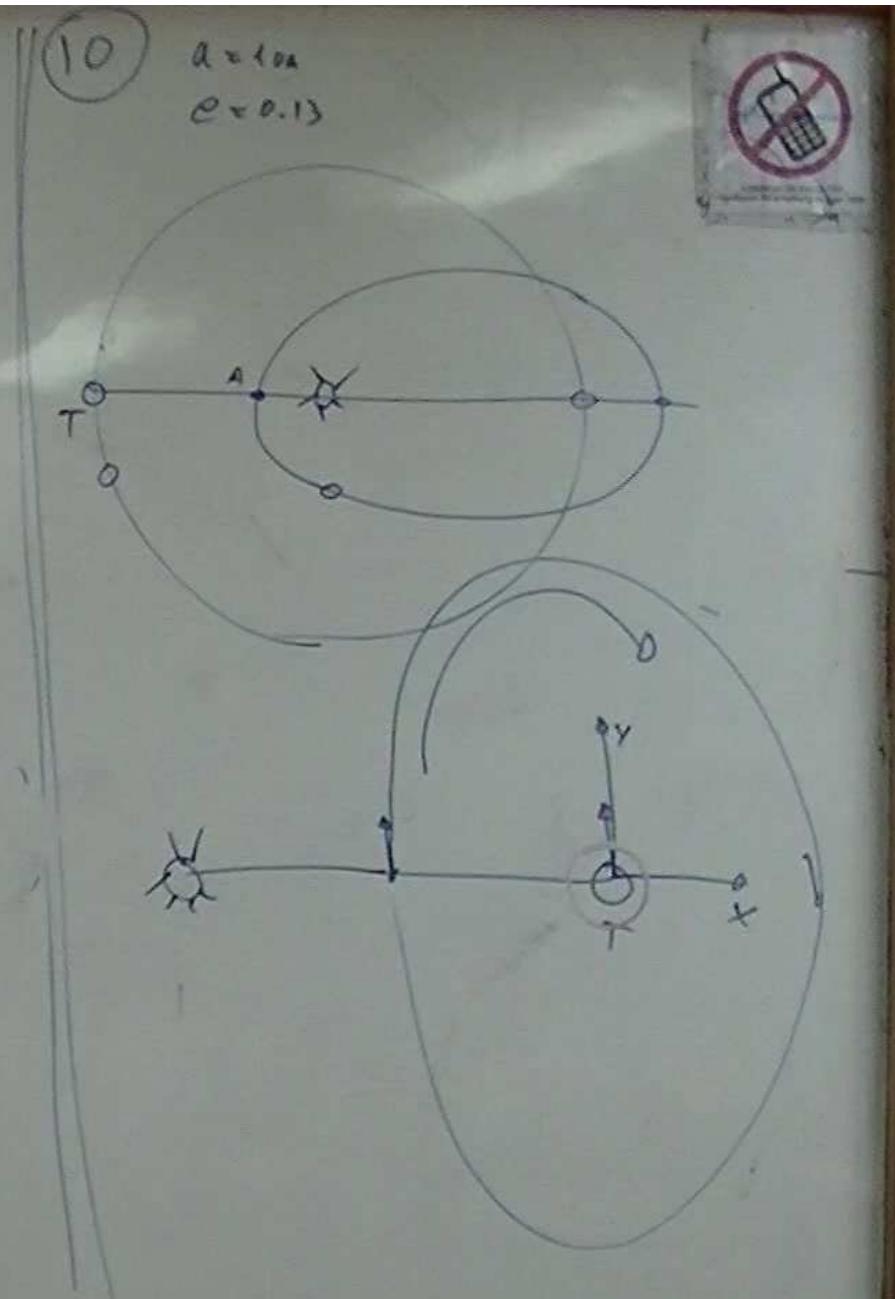


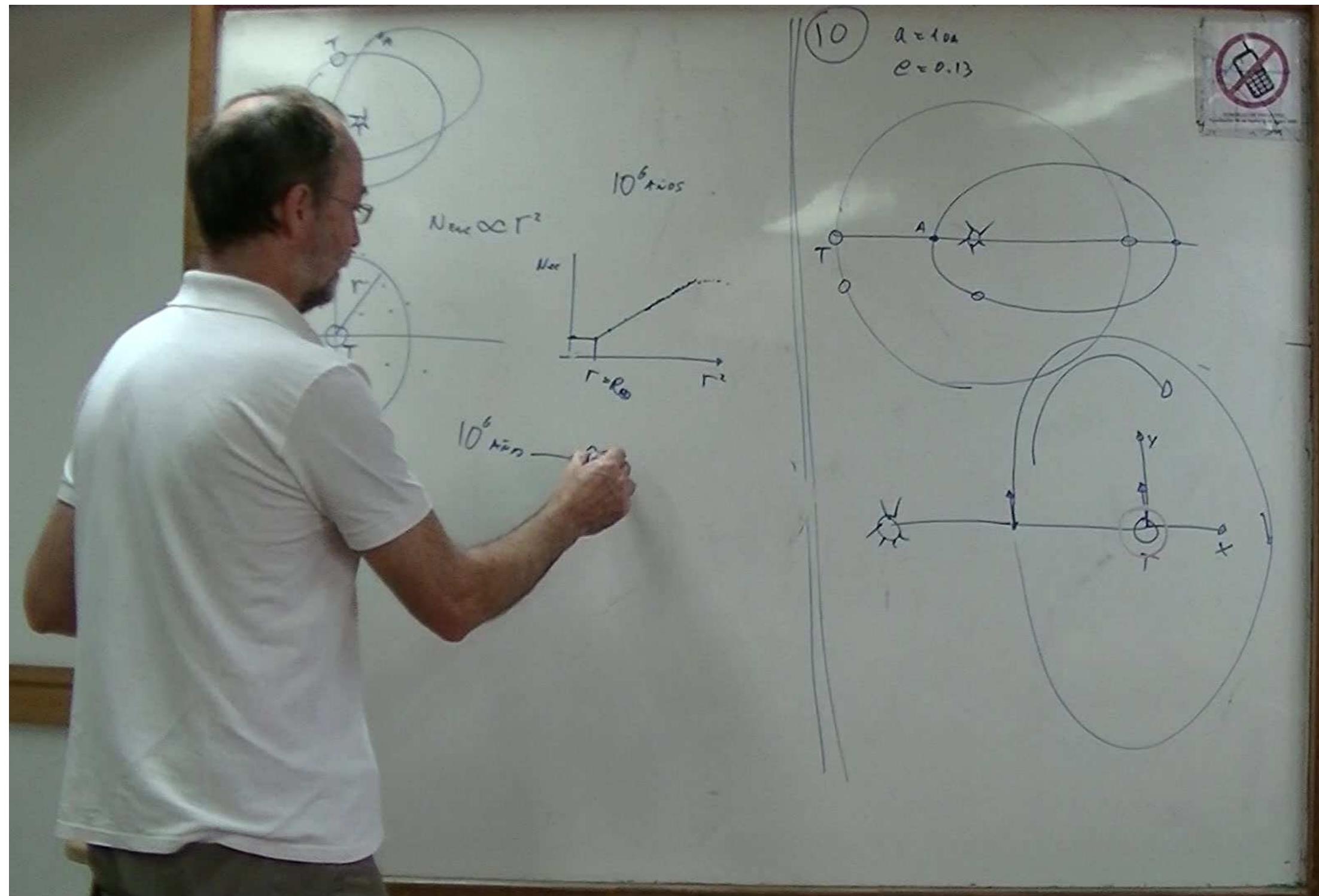


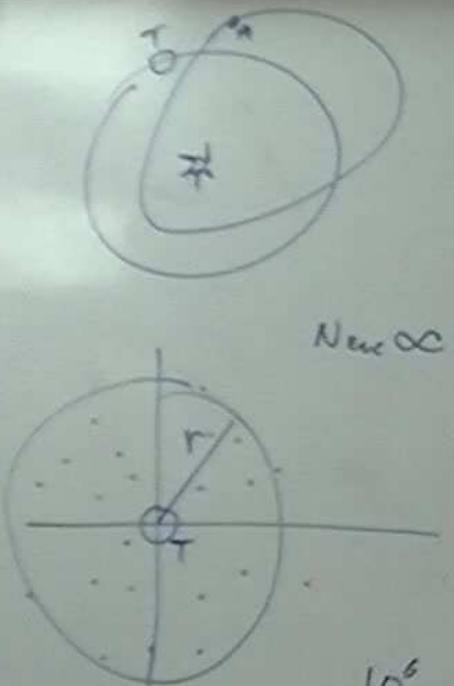






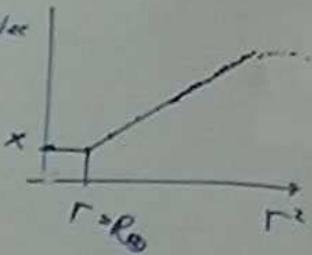






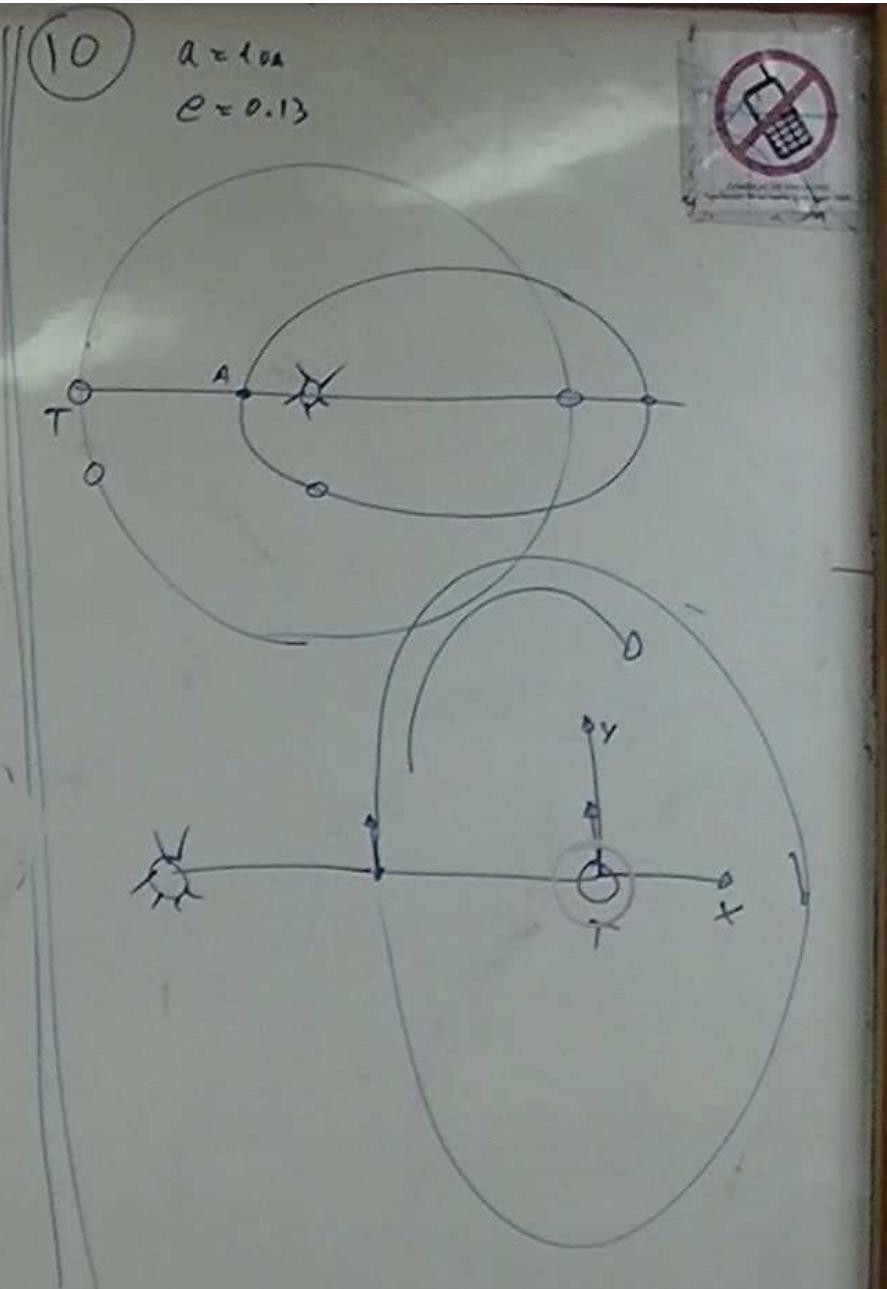
$$N_{\text{ec}} \propto r^2$$

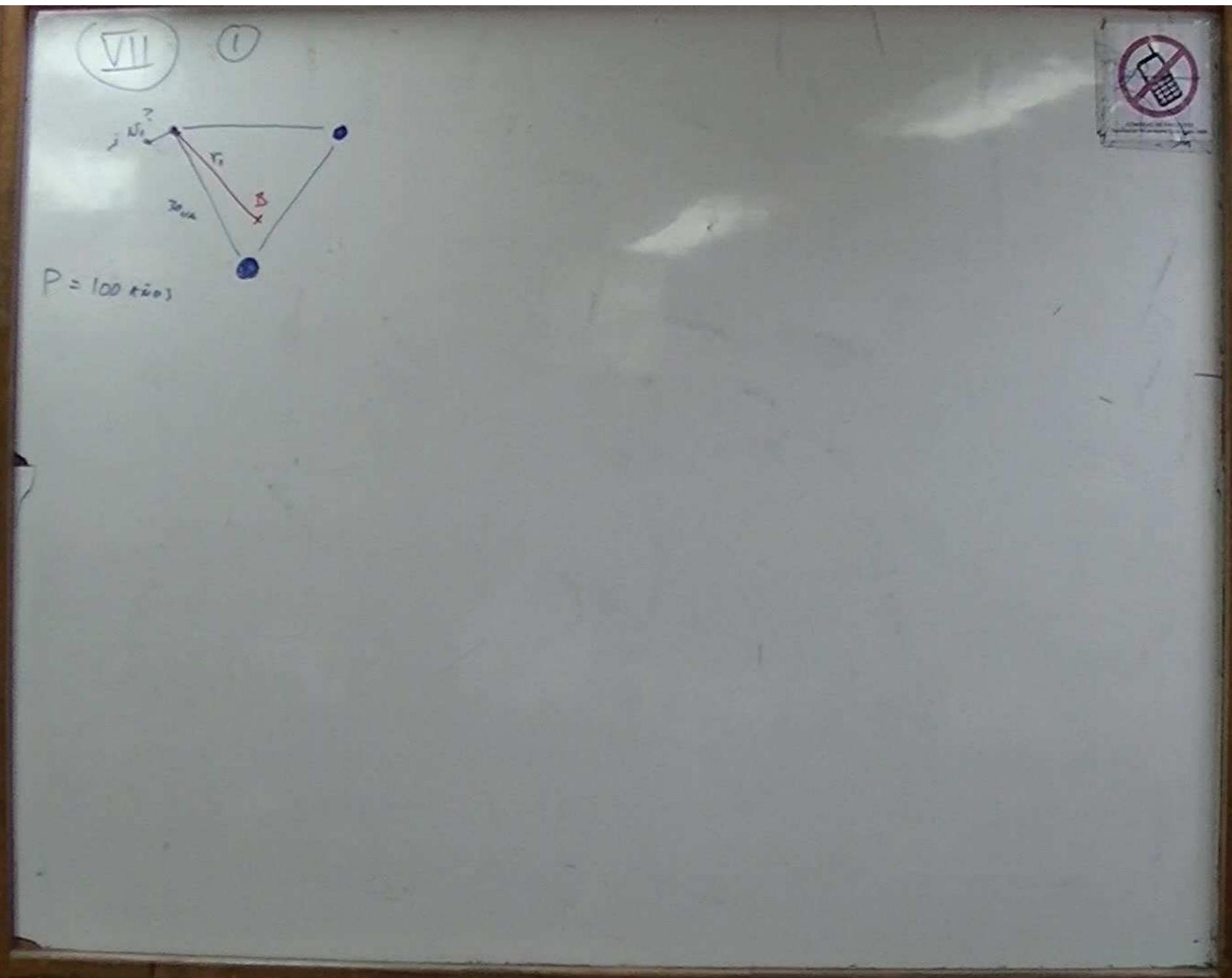
10^6 años



10^6 años $\rightarrow X$ "colisiones"

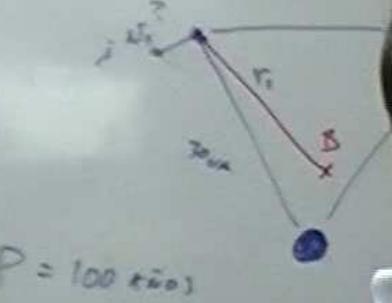
Vida Punto $\rightarrow 1$





(VII)

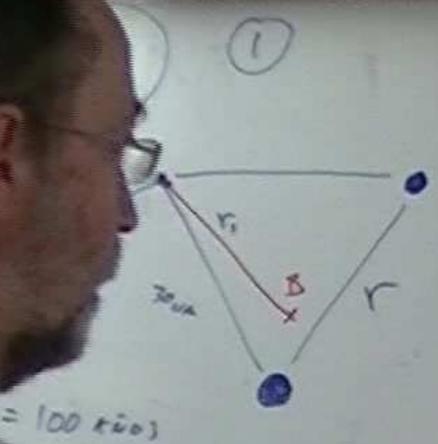
(I)



$$P = 100 \text{ kNm}$$

$$\ddot{\vec{r}}_1 = -\frac{1}{r^3} \left[m_2 (\vec{r}_1 - \vec{r}_2) + m_3 (\vec{r}_1 - \vec{r}_3) \right]$$





$$\ddot{\vec{r}}_1 = -\frac{1}{r^3} \left[m_2 (\vec{r}_1 - \vec{r}_2) + m_3 (\vec{r}_1 - \vec{r}_3) \right]$$

$\underbrace{\quad}_{m = (m_1 + m_2 + m_3) \vec{r}_1}$

$$m_1^2 r^2 + m_3^2 r^2 + 2m_2 m_3 r^2 \cdot \cos 60^\circ = M^2 r^2$$



(VII)

(1)

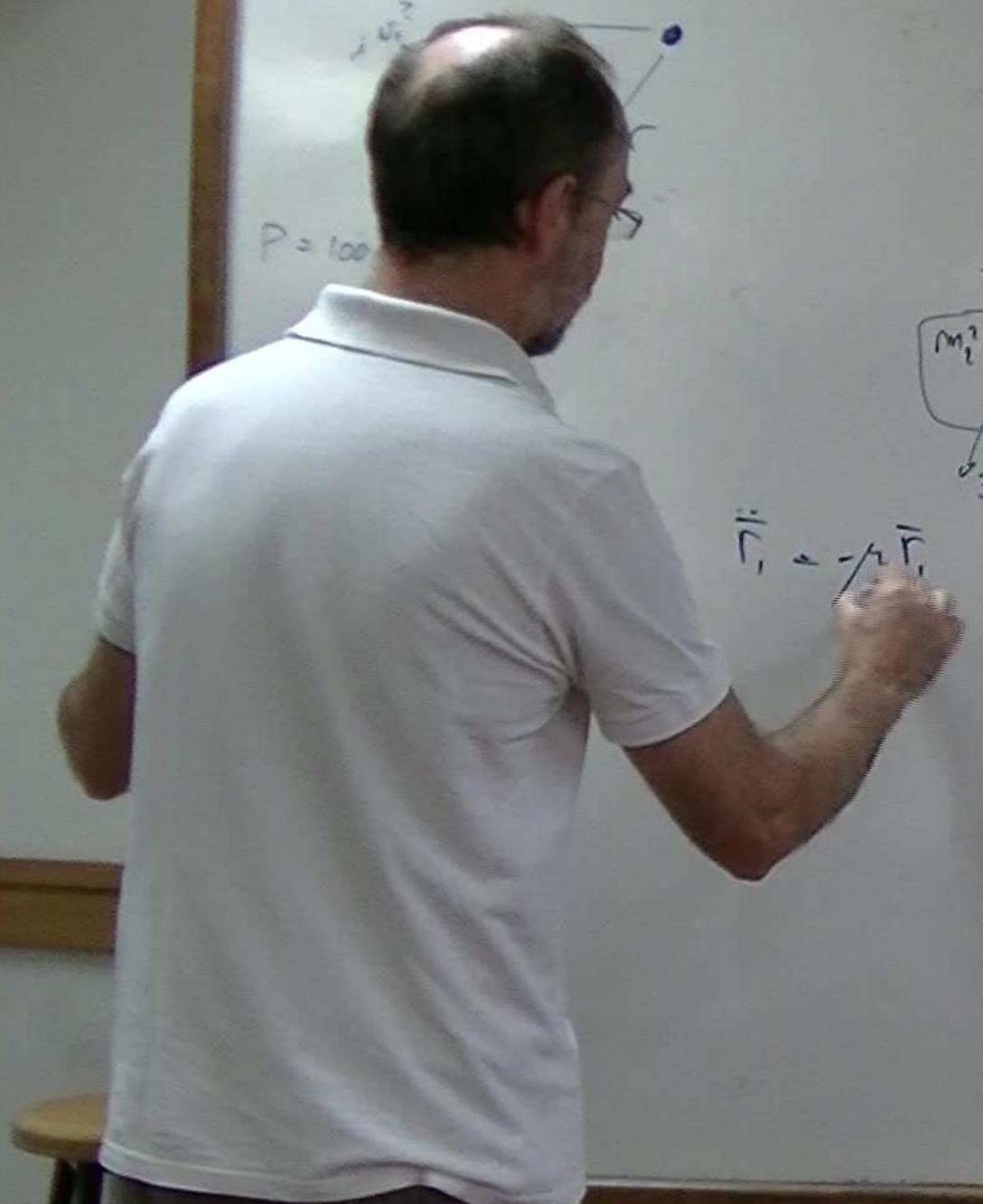
 $P = 100$ 

$$\ddot{\vec{r}}_1 = -\frac{1}{r^3} \left[m_2 (\vec{r}_1 - \vec{r}_2) + m_3 (\vec{r}_1 - \vec{r}_3) \right]$$

$$\text{---} = \frac{m}{(m_1 + m_2 + m_3)} \vec{r}_1$$

$$m_1^2 r^2 + m_3^2 r^2 + 2m_2 m_3 r^2 \cdot \cos 60^\circ = M^2 r_1^2$$

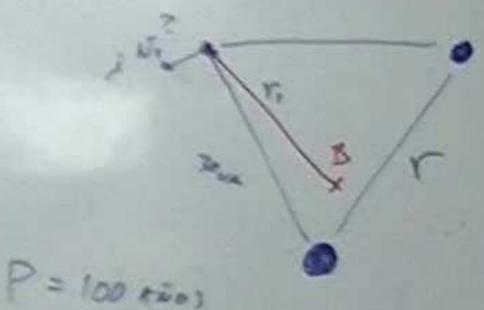
30 m

 r_1 



VII

I



$$P = 100 \text{ dias}$$

$$\ddot{\vec{r}}_1 = -\frac{1}{r^3} \left[m_2 (\vec{r}_1 - \vec{r}_2) + m_3 (\vec{r}_1 - \vec{r}_3) \right]$$

$\text{---} M$

$$\theta = \overbrace{(m_1 + m_2 + m_3)}^M \vec{r}_1$$

$$m_1^2 P^2 + m_3^2 r^2 + 2m_2 m_3 r^2 \cdot \cos 60^\circ = M^2 r_1^2$$

$$\ddot{\vec{r}}_1 = -\frac{m_2 \vec{r}_1}{r_1^3}$$

$$M = \sqrt{m_1}$$

$$\theta = \frac{\left(m_1^2 + m_2 m_3 + m_3^2 \right)^{3/2}}{M^2}$$

$$E_1^2 = h_1 \left(\frac{2}{r_1} - \frac{1}{a} \right)$$

$$r_1 = 30 \text{ au}$$

M²



VII
I

$$P = 100 \text{ días}$$

$$\bar{r}_1^2 = \mu_1 \left(\frac{2}{\bar{r}_1} - \frac{1}{\alpha} \right)$$

$$m = \sqrt{\frac{\mu_1}{\alpha}}$$

$$\frac{2\pi}{100}$$



$$\ddot{\bar{r}}_1 = -\frac{1}{\bar{r}_1^3} \left[m_2 (\bar{r}_1 - \bar{r}_2) + m_3 (\bar{r}_1 - \bar{r}_3) \right]$$

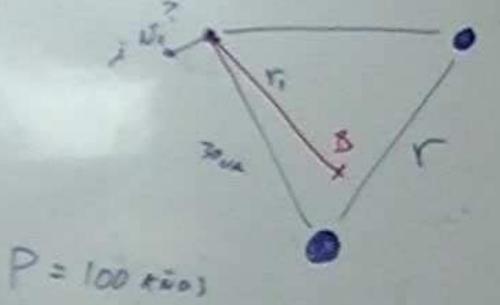
$$m = (m_1 + m_2 + m_3) \bar{r}_1$$

$$m_1^2 \nu^2 + m_3^2 r^2 + 2m_2 m_3 r^2 \cos 60^\circ = M^2 \bar{r}_1^2$$

$$\ddot{\bar{r}}_1 = -\frac{\bar{r}_1}{\bar{r}_1^3}$$

$$\nu = \frac{(m_1^2 + m_2 m_3 + m_3^2)^{3/2}}{M^2}$$

(VII)



(1)

(2)

$$\rho a_0 = \dots$$

$$K_0 M_0 + K_1 M_1 + K_2 M_2 \approx 0$$

 a_0 a_1 

$$\bar{\mu}_1^2 = \mu_1 \left(\frac{2}{\bar{r}_1} - \frac{1}{a_1} \right)$$

$$\bar{r}_1 = \frac{\bar{r}_1}{r_1}$$

$$M = \sqrt{\frac{\mu_1}{a_1^3}}$$

$$\frac{2\pi}{100}$$

$$0 \frac{(m_1^2 + m_2 m_3 + m_3^2)^{3/2}}{M^2}$$

(VII)

$$\frac{1}{h} \cdot \frac{d^2}{dt^2} \left(\frac{r_i}{R_i} \right) = 4\zeta + 2\psi = \ddot{\vartheta}$$

?

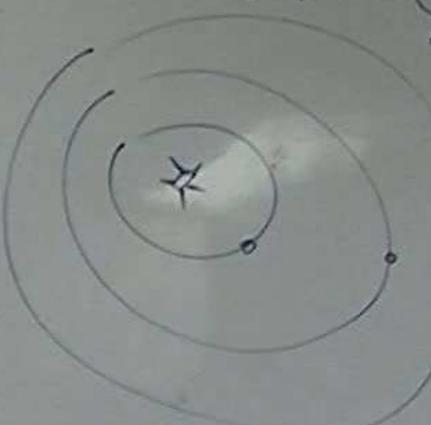
?

$$\bar{R}_i \\ \bar{R}_j$$

(2)

$$K_0 M_0 + K_1 M_1 + K_2 M_2 \approx 0$$

$$o_1 \quad a_1$$



$$3M_j = 1M_a$$

$$3\sqrt{\frac{L}{a_1}} = \sqrt{\frac{L}{a_2}}$$

(3)

2.4

2.6

m q

$$\Rightarrow 3 \cdot a_1^{-3/2} = a_2^{-3/2}$$

(VII)

$$\frac{1}{\hbar} \cdot \frac{d^2}{dt^2} (\tilde{\gamma}) = 4\zeta + 2U = \ddot{I}$$

$$\zeta = T - U$$

\ddot{I}

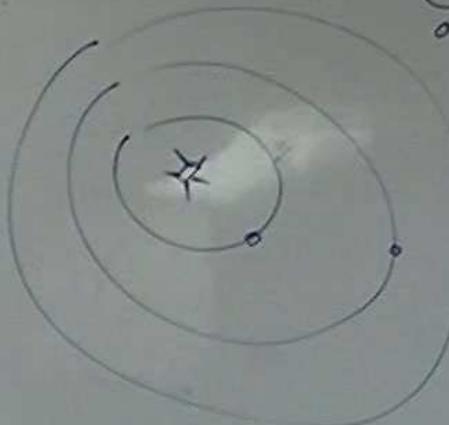
$$\tilde{R}_i$$

$$\tilde{R}_j$$

(2)

$$\alpha_0 = \dots$$

$$K_0 M_0 + K_1 M_1 + K_2 M_2 \approx 0$$

 α_1 α_2 

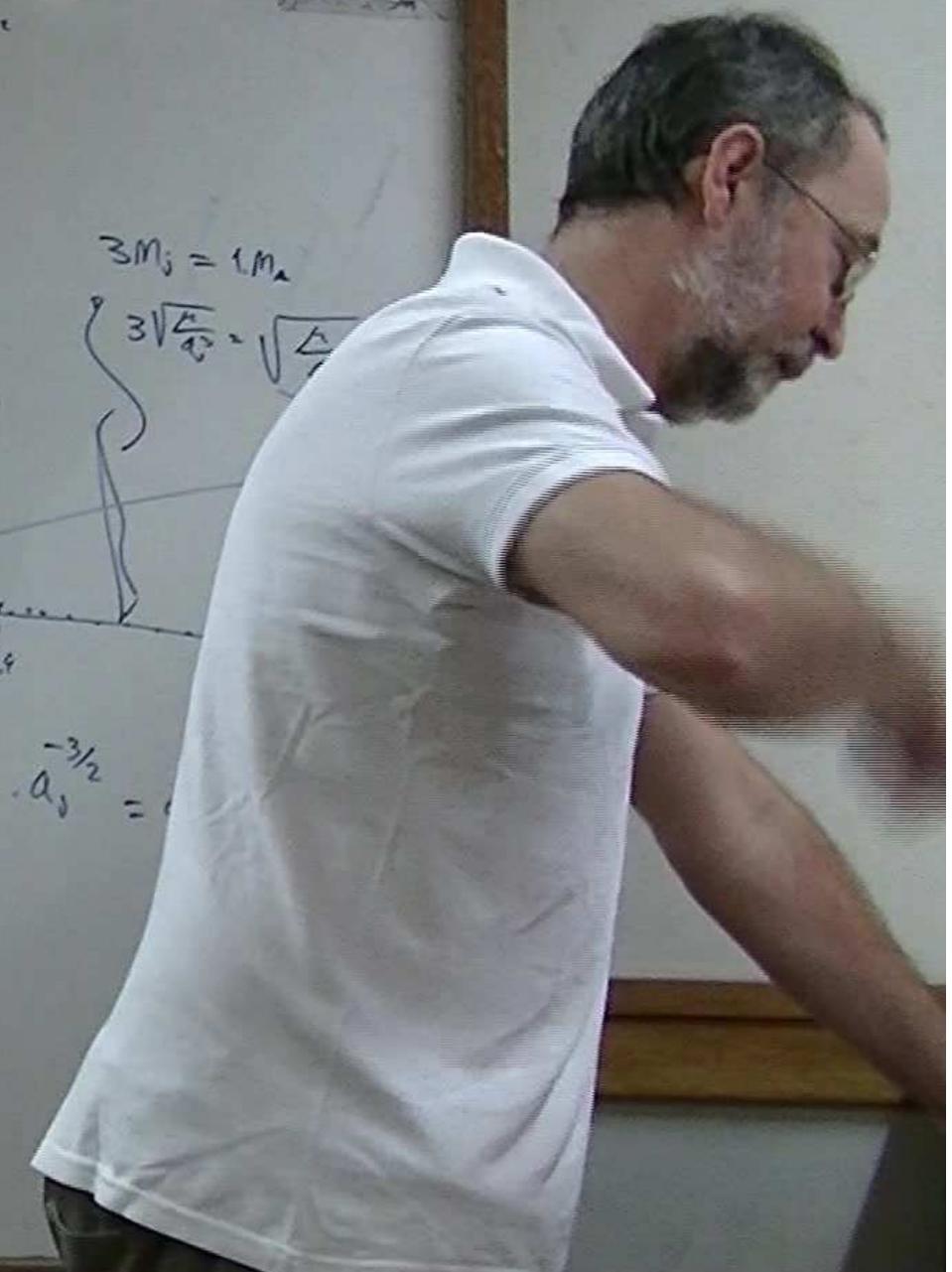
(3)

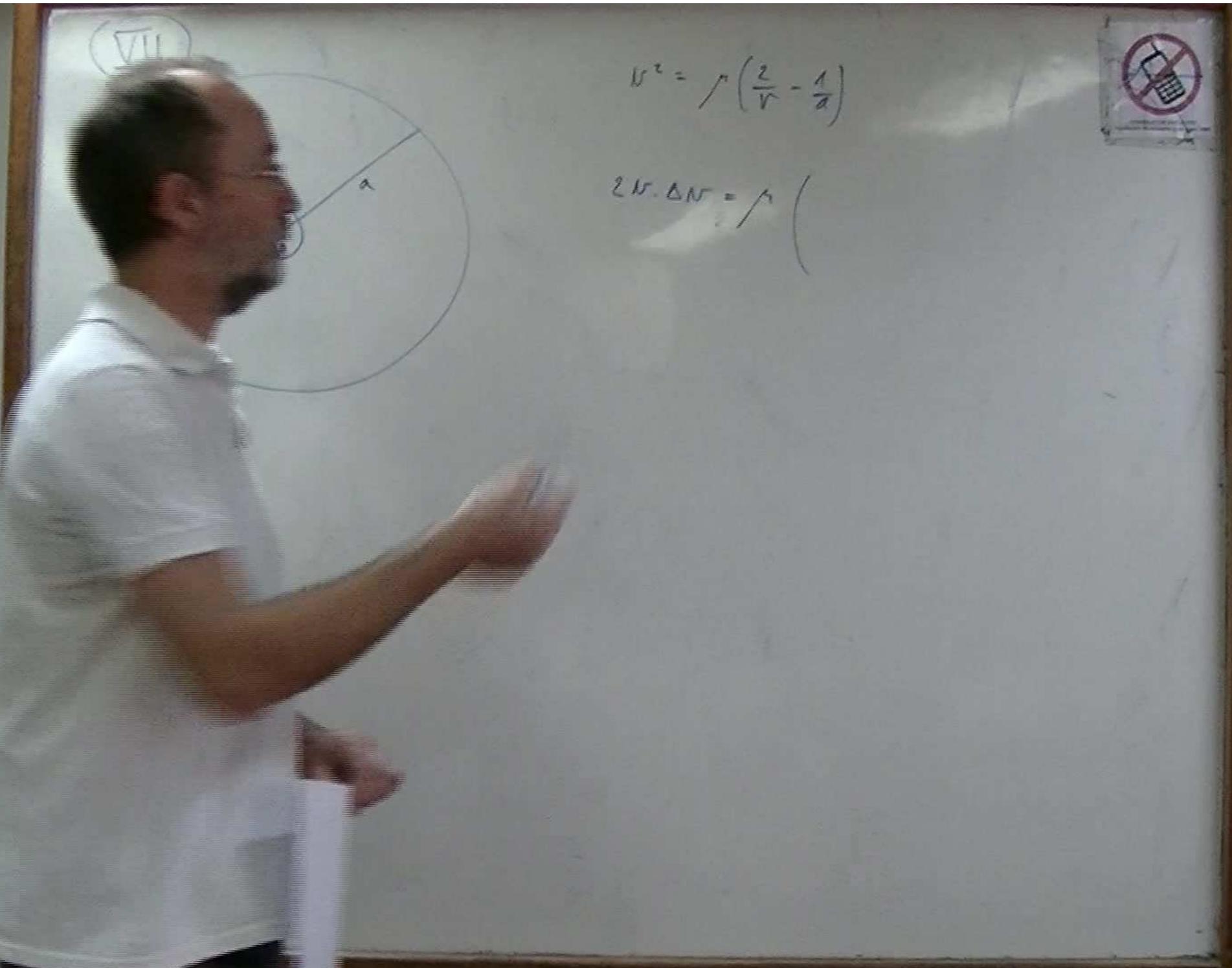
$$3M_j = 1M_a$$

$$3\sqrt{\frac{a}{a_0}} \cdot \sqrt{\Delta}$$

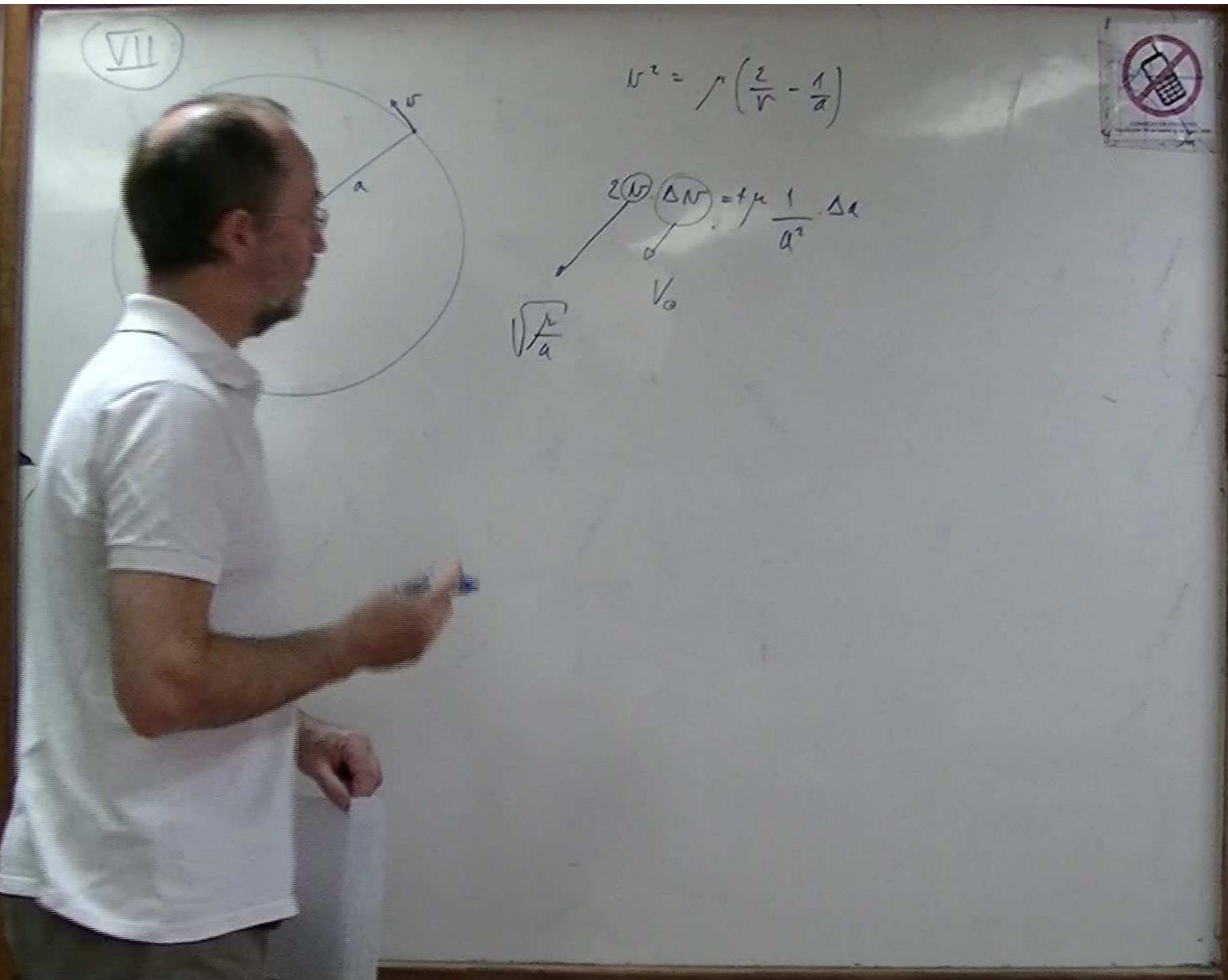
 a_0

$$\Rightarrow 3 \cdot a_0^{-3/2} =$$

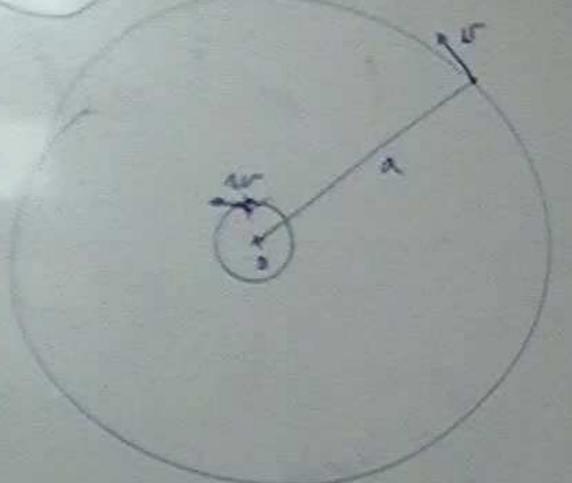




VII



VII



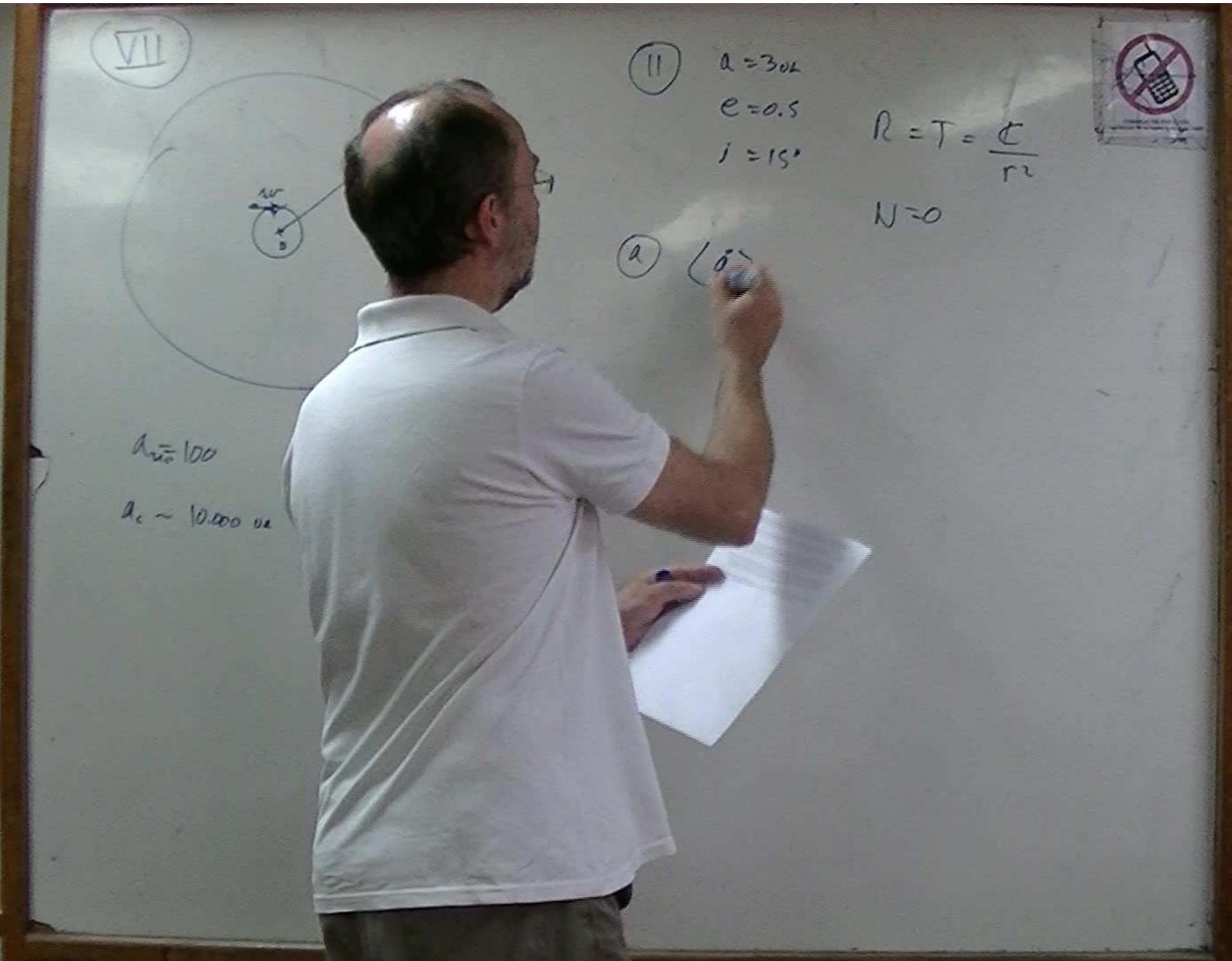
$$a = 100$$

$$v^2 = \mu \left(\frac{2}{r} - \frac{1}{a} \right)$$

$$\Delta v = \sqrt{\mu} \cdot \frac{1}{a^2} \cdot \Delta a$$

 v_0 







(11)

$$a = 300L$$

$$e = 0.5$$

$$i = 15^\circ$$

$$R = T = \frac{C}{r^2}$$



$$N=0$$

$$\langle \ddot{a} \rangle = \dots$$

$$\ddot{a} = \bigcirc \cdot \left[R \cdot e \cos f + T \left(1 + e \cdot \cos f \right) \right]$$

$$\langle \ddot{a} \rangle = \frac{1}{\pi} \int_0^{2\pi} d\eta$$

$$\frac{1}{2\pi} \int_0^{2\pi} r^2 \dots df$$



$$a_{\text{ter}} = 100$$

$$d_c \sim 10,000 \text{ au}$$

(II)

$$a = 300L$$

$$e = 0.5$$

$$i = 15^\circ$$

$$R = T = \frac{C}{r^2}$$



$$N = 0$$

$$\langle \ddot{a} \rangle = \dots$$

$$\ddot{a} = \int_0^{2\pi} \left[R \cdot e^{nr\theta} + T(1 + e \cdot \cos\theta) \right] d\theta$$

$$\langle \ddot{a} \rangle = \frac{1}{\pi} \int_0^{2\pi} dr$$

$$\frac{1}{2\pi} \int_0^{2\pi} r^2 \dots d\theta$$

$$\langle \ddot{a} \rangle = \frac{2C}{h\sqrt{a}(1-e^2)} = \frac{0.1}{100,365,25}$$

CÁMARA

ALFREDO SILVEIRA

REPARTO POR ORDEN
DE APARICIÓN

Profesor T. Gallardo

Alumno A. Silveira

" " F. Lopez

" " -----

(11)

$$a = 300 \text{ km}$$

$$e = 0.5$$

$$i = 15^\circ$$

$$R = T = \frac{C}{r^2}$$



$$N = 0$$

$$\langle \dot{\alpha} \rangle = \dots$$

$$\dot{\alpha} = \int_0^{2\pi} \left[R \cdot e \cdot n \sin f + T \left(1 + e \cdot \cos f \right) \right] d\theta$$

$$\langle \dot{\alpha} \rangle = \frac{1}{\pi} \int_0^{2\pi} r^2 \dots d\theta$$

$$\langle \dot{\alpha} \rangle = \frac{2 \textcircled{1}}{h \sqrt{a} (1-e^2)} = \frac{0.1}{100,365,25}$$