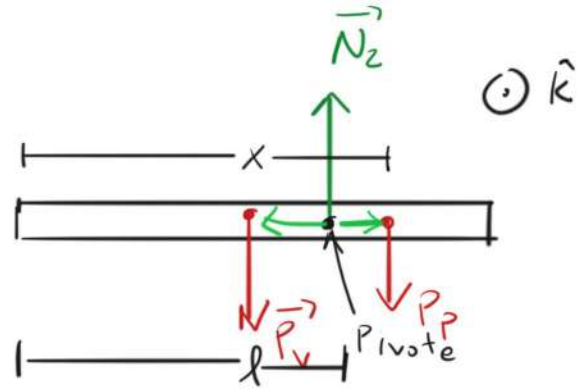
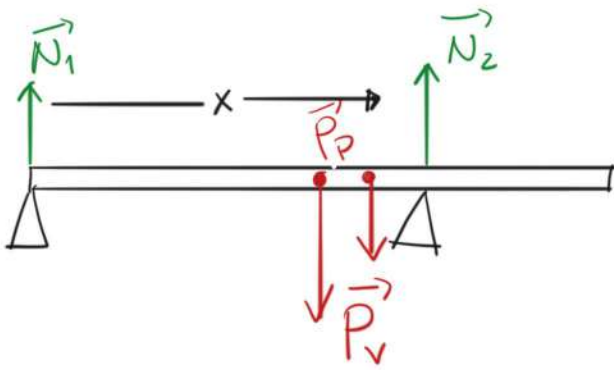


Práctico 3

14



b) $\sum \vec{F}_{ext} : N_2 - P_v - P_p = 0 \Rightarrow N_2 = P_v + P_p$

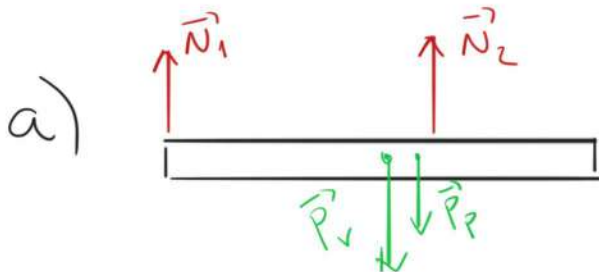
$\vec{\tau}_{N_2} = 0 \times N_2(\hat{k})$ $\vec{\tau}_{P_v} = (l - \frac{l}{2})Mg\hat{k}$; $\vec{\tau}_{P_p} = (x - l)mg(-\hat{k})$

$0 = \tau_{P_v} - \tau_{P_p} + \tau_{N_2} = (l - \frac{l}{2})Mg - (x - l)mg + 0$ (*)

$\tau_{P_p} > \tau_{P_v} \Rightarrow (l - \frac{l}{2})Mg > (x - l)mg$

$(l - \frac{l}{2}) \frac{Mg}{mg} > (x - l)$

$l + (l - \frac{l}{2}) \frac{M}{m} > x$



$N_1 + N_2 - P_v - P_p = 0$

$\vec{\tau}_{N_1} + \vec{\tau}_{N_2} + \vec{\tau}_{P_v} + \vec{\tau}_{P_p} = 0$

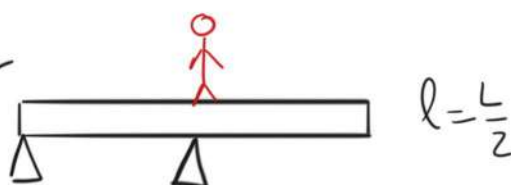
Justo antes del giro : $N_1 = 0 \Rightarrow N_2 = P_v + P_p$

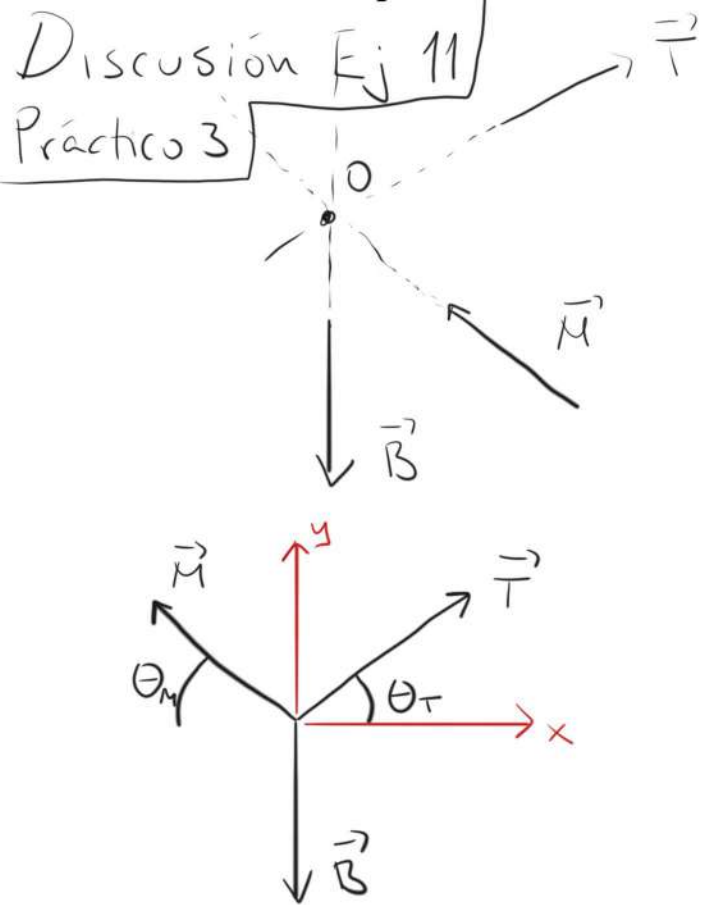
$= Mg + mg$

$N_2 = (M + m)g$

\uparrow no depende de l !!

Caso particular





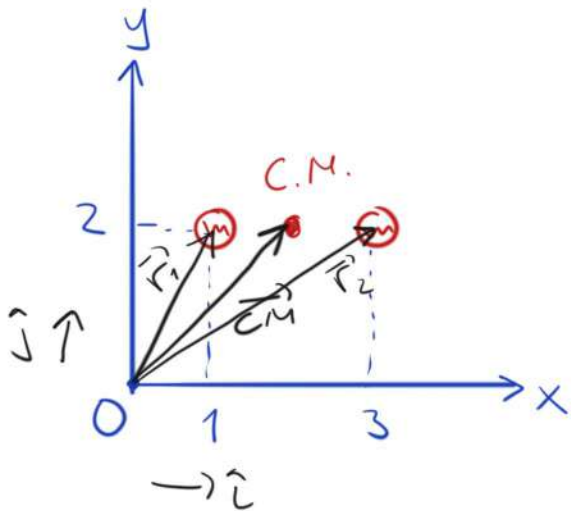
$$\vec{T} + \vec{M} + \vec{B} = 0$$

$$\sum \vec{F}_{ext} :$$

$$\sum F_x = T \cos \theta_T - M \cos \theta_M = 0$$

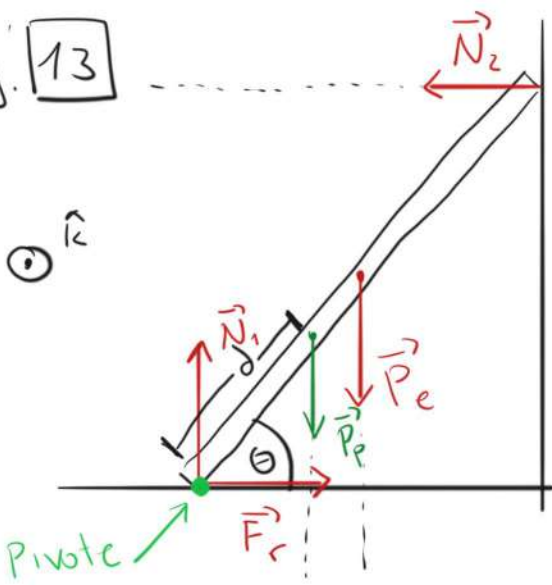
$$\sum F_y = T \sin \theta_T + M \sin \theta_M - B = 0$$

Ejemplo sencillo de cálculo del centro de masas



$$\begin{aligned} \vec{C.M.} &= \frac{m \vec{r}_1 + m \vec{r}_2}{m + m} \\ &= \frac{m(1\hat{i} + 2\hat{j}) + m(3\hat{i} + 2\hat{j})}{2m} \\ &= \frac{4m\hat{i} + 4m\hat{j}}{2m} = 2\hat{i} + 2\hat{j} \end{aligned}$$

Ej. 13



$$\begin{aligned} \sum F_x &= F_r - N_2 \Rightarrow N_2 = F_r = \mu N_1 \\ \sum F_y &= N_1 - P_e - P_p \Rightarrow N_1 = P_p + P_e \end{aligned}$$

$$\vec{T}_{N_2} + \vec{T}_{P_p} + \vec{T}_{P_e} = 0 \quad \left\{ \begin{array}{l} P_e = m_e g \\ P_p = m_p g \end{array} \right.$$

$$\vec{T}_{N_2} = L \sin \theta N_2 \hat{k}$$

$$\vec{T}_{P_p} = d \cos \theta P_p (-\hat{k}); \quad \vec{T}_{P_e} = \frac{L}{2} \cos \theta P_e (-\hat{k})$$