

22/20

$$5.3.d) \quad W = \{A \in M_2(\mathbb{R}) : A^t = A\}$$

$$W^\perp = \{B \in M_2(\mathbb{R}) : \langle B, A \rangle = 0 \quad \forall A \in W\}$$

$$\hookrightarrow B = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}, \quad A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

$$\langle B, A \rangle = \sum_{i,j=1}^2 b_{ij} a_{ij}$$

$$= b_{11} a_{11} + b_{12} a_{12} + b_{21} a_{21} + b_{22} a_{22} = 0$$

$$= \underbrace{b_{11}}_0 \underbrace{a_{11}}_0 + \underbrace{[b_{12} + b_{21}]}_0 \underbrace{a_{12}}_0 + \underbrace{b_{22}}_0 \underbrace{a_{22}}_0 = 0$$

$$\textcircled{B} = \begin{pmatrix} 0 & b_{12} \\ -b_{12} & 0 \end{pmatrix} \rightsquigarrow W^\perp = \{B \in M_2(\mathbb{R}) : B^t = -B\}$$

7. 1.6)

$$V = \mathbb{R}_2[x], \quad T(p) = p'$$

$$T(ax+b) = a$$

$$\text{Sea } p = ax+b, \quad f = cx+d \in V,$$

$$\begin{aligned} \langle T(p), f \rangle &= \langle a, cx+d \rangle = \int_0^1 a(cx+d) dx \\ &= a \left(\frac{2c}{2} + 2d \right) \end{aligned}$$

$$\langle p, T^*(f) \rangle = \langle ax+b, T^*(f) \rangle = \int_0^1 ax(T^*(f)) + bT^*(f) dx$$

$$\text{Si } \{v_1, v_2\} \text{ es bon. } \Rightarrow T^*(v) = \sum_{i=1}^2 \langle T(v), v_i \rangle v_i$$

Sea $\mathcal{B} = \{1, x\}$ la base canónica.

$$\langle 1, x \rangle = \int_0^1 1 \cdot x dx = \frac{1}{2} \neq 0 \Rightarrow \mathcal{B} \text{ no es ortogonal}$$

Aplicamos Gram-S: $w_1 = v_1 = 1$
 $w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\|w_1\|^2} w_1$
 $= x - \frac{\langle x, 1 \rangle}{\|1\|^2} 1$
 $w_2 = x - \frac{1}{2} \cdot 1$

$$\|1\|^2 = \left[\int_0^1 1 dx \right]^2 = 1^2 = 1$$

$$\mathcal{B}' = \left\{ 1, x - \frac{1}{2} 1 \right\}$$

$$\langle I, x - \frac{1}{2} I \rangle = \int_0^1 I \cdot x dx - \frac{1}{2} \int_0^1 I^2 dx$$

$$= \frac{1}{2} - \frac{1}{2} = 0$$

$$\|x - \frac{1}{2} I\| = \sqrt{\langle x - \frac{1}{2} I, x - \frac{1}{2} I \rangle} = \left[\int_0^1 x^2 + \frac{1}{4} I^2 - x \cdot I dx \right]^{1/2}$$

$$= \left[\frac{1}{3} + \frac{1}{4} - \frac{1}{2} \right]^{1/2}$$

$$= \left[\frac{4 + 3 - 6}{12} \right]^{1/2} = \sqrt{\frac{1}{12}}$$

Luego, $\mathcal{B} = \left\{ I, \frac{x - \frac{1}{2} I}{\sqrt{1/12}} \right\}$ es una b.o.n.

Recordar $T(\mathcal{B}x + b) = \mathcal{B}$.

$$T^*(\mathcal{B}x + b) = \sum_{i=1}^2 \langle T(\mathcal{B}x + b), v_i \rangle v_i$$

$$= \langle \alpha, I \rangle I + \langle \alpha, \frac{x - \frac{1}{2} I}{\sqrt{1/12}} \rangle \cdot \frac{x - \frac{1}{2} I}{\sqrt{1/12}}$$

$$\langle \alpha, I \rangle = \int_0^1 \alpha \cdot I \cdot dx = \alpha$$

$$\langle \alpha, \frac{x - \frac{1}{2} I}{\sqrt{1/12}} \rangle = \frac{\alpha}{\sqrt{1/12}} \int_0^1 x - \frac{1}{2} I dx$$

$$= \frac{2}{\sqrt{2/22}} \left[\frac{1}{2} - \frac{1}{2} \right] = 0$$

$$\boxed{T^*(cx+d) = c}$$

$$\text{es en } \mathcal{B} = \left\{ \mathbb{I}, \frac{x - \frac{1}{2}\mathbb{I}}{\sqrt{2/22}} \right\}$$

$$\langle T(ax+b), cx+d \rangle = \int_0^2 \partial cx + d \partial x = \frac{\partial c}{2} + d \partial$$

$$\langle \partial x + b, T^*(cx+d) \rangle = \int_0^2 \partial cx + \partial c = \frac{\partial c}{2} + \partial c$$

Revisar:

6.2.6)

$$T: \mathbb{C}^2 \rightarrow \mathbb{C}^2$$

$$T(x, y) = (2x + (3-3i)y, (3+3i)x + 5y)$$

$$\langle T(x, y), (z, w) \rangle =$$

$$= \underline{2x\bar{z}} + \overbrace{(3-3i)y\bar{z}} + \overbrace{(3+3i)x\bar{w}} + \underline{5y\bar{w}}$$

$$\begin{aligned} \langle (x, y), T(z, w) \rangle &= 2x\bar{z} + x\overbrace{(3-3i)\bar{w}} + \overbrace{(3+3i)z\bar{y}} + 5y\bar{w} \\ &= \underline{2x\bar{z}} + \overbrace{(3+3i)x\bar{w}} + \overbrace{(3-3i)\bar{z}y} + \underline{5y\bar{w}} \end{aligned}$$

$$8) T_2 = \frac{1}{2}(T + T^*)$$

$\left\langle v_1, T_2(w) \right\rangle$
 Querens

$$\left\langle T_2(v), w \right\rangle = \left\langle \frac{1}{2}(T + T^*)(v), w \right\rangle$$

$$= \left\langle \frac{1}{2}T(v) + \frac{1}{2}T^*(v), w \right\rangle$$

$$= \left\langle \frac{1}{2}T(v), w \right\rangle + \left\langle \frac{1}{2}T^*(v), w \right\rangle$$

$$= \left\langle \frac{1}{2}v_1, T^*(w) \right\rangle + \left\langle \frac{1}{2}v_1, \underbrace{(T^*)^*}_{T}(w) \right\rangle$$

$$T: V \rightarrow V$$

$$T^*: V \rightarrow V$$

$$= \left\langle \frac{1}{2}v_1, T^*(w) + T(w) \right\rangle$$

$$= \frac{1}{2} \left\langle v_1, T^*(w) + T(w) \right\rangle$$

$$= \left\langle v_1, \underbrace{\left\{ \frac{1}{2} \right\}}_{2/2} \left[\overline{T^*(w) + T(w)} \right] \right\rangle$$

$$= \left\langle v_1, \frac{1}{2} [T(w) + T^*(w)] \right\rangle$$

$$= \left\langle v_1, \frac{1}{2}(T + T^*)(w) \right\rangle$$

$$= \left\langle v_1, T_2(w) \right\rangle$$

1a) $\lambda \in \mathbb{C}$, $T_\lambda: \mathbb{C} \rightarrow \mathbb{C}$, $T_\lambda(z) = \lambda \cdot z$

a) Hallar para cuales λ , T_λ es autoadjunto.

$$\langle T_\lambda(z), w \rangle = \langle \lambda z, w \rangle = \lambda z \bar{w}$$

|| \leftarrow Queremos

$$\langle z, T_\lambda(w) \rangle = \langle z, \lambda w \rangle = \bar{\lambda} z \bar{w}$$

$$\lambda = \bar{\lambda} \text{ sii } \lambda \in \mathbb{R}$$

b) T_λ es positivo si:
 • $\langle T_\lambda(v), v \rangle > 0 \quad \forall v \neq 0$
 • Autoadjunto

$$\langle T_\lambda(z), z \rangle = \langle \lambda z, z \rangle = \lambda \langle z, z \rangle = \lambda |z|^2$$

$$\langle T_\lambda(z), z \rangle > 0 \text{ sii } \lambda > 0.$$

$\underbrace{\quad}_{z \neq 0}$

c) ¿Para cuales λ , T_λ es normal?

Recordar: T_λ es normal si $T_\lambda \circ T_\lambda^* = T_\lambda^* \circ T_\lambda$

$$\langle T_\lambda(z), w \rangle \stackrel{\text{sabemos}}{=} \langle z, T_\lambda^*(w) \rangle$$

$$\underline{\underline{\lambda z \bar{w}}}$$

$$\leftarrow \text{Vale sii } \boxed{T_\lambda^*(w) = \bar{\lambda} w}$$

$$\begin{aligned} \langle z, T_\lambda^*(w) \rangle &= \langle z, \bar{\lambda} w \rangle \\ &= \bar{\lambda} \langle z, w \rangle \\ &= \lambda z \bar{w} \end{aligned}$$

$$T_\lambda \circ T_\lambda^*(z) = T_\lambda(\bar{\lambda}z) = \lambda \bar{\lambda} z = |\lambda|^2 z$$

↑ "No unitario"

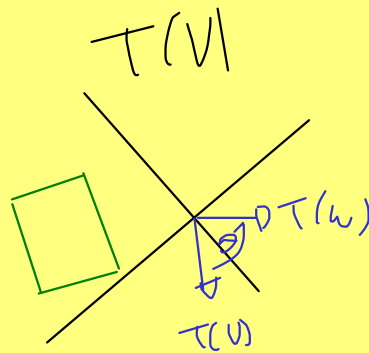
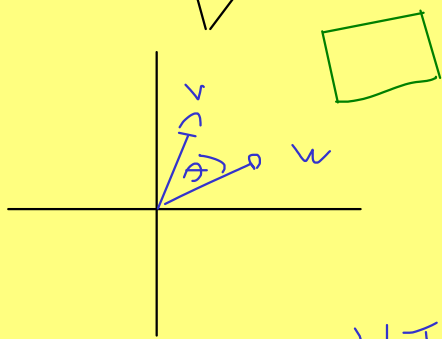
$$T_\lambda^* \circ T_\lambda(z) = T_\lambda^*(\lambda z) = \bar{\lambda} \lambda z = |\lambda|^2 z$$

Entonces T_λ es normal $\forall \lambda \in \mathbb{C}$.

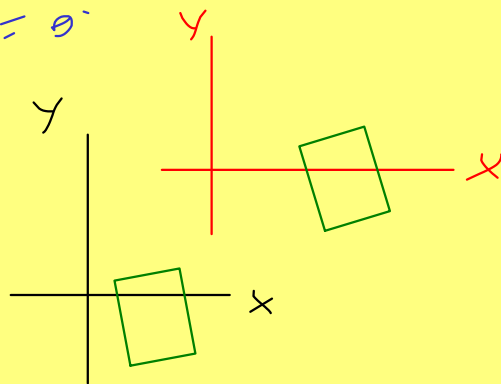
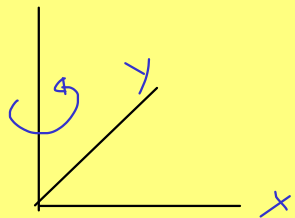
Esto muestra que normal no implica autoadjunto.

o) T_λ isométrica.

$$\langle T_\lambda(z), T_\lambda(w) \rangle = \langle z, w \rangle$$

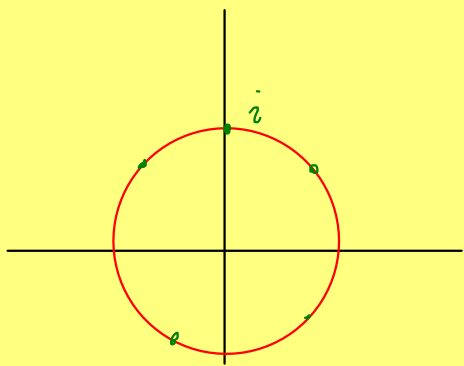


$$\begin{aligned} \|T(v)\| &= \|v\| \\ \|T(w)\| &= \|w\| \\ \theta &= \theta' \end{aligned}$$



$$\begin{aligned} \langle T_\lambda(z), T_\lambda(w) \rangle &= \langle \lambda z, \lambda w \rangle = \lambda \bar{\lambda} \langle z, w \rangle \\ &= |\lambda|^2 \langle z, w \rangle \end{aligned}$$

Entonces para que T_λ sea isométrica, $\lambda \bar{\lambda} = 1$

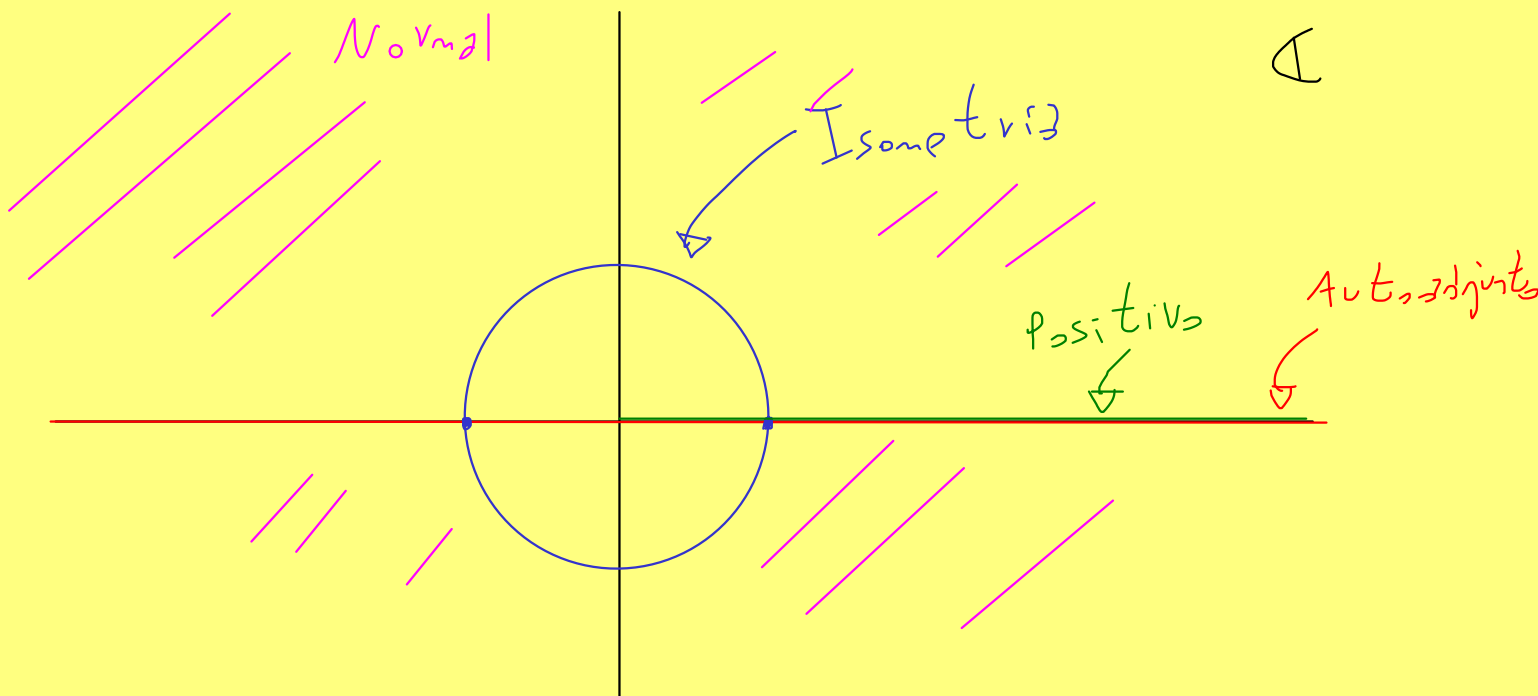


$$\lambda = \pm 1$$

$$\lambda = i$$

$$\bar{\lambda} = -i$$

$$\lambda \bar{\lambda} = -i^2 = -(-1) = 1$$



G.3.6)

$K = \mathbb{C}$, T autoadjunto

$$\| \underbrace{T \pm i \text{Id}}(v) \|^2 = \|T(v)\|^2 + \|v\|^2$$

$$T(v) \pm i v.$$

6.4) S, T autoadjuntos $\Leftrightarrow S, T$ normales.

S : $K = \mathbb{R} \rightarrow S, T$ autoadjuntos $\Leftrightarrow S, T$ diag.

$K = \mathbb{C} \rightarrow S, T$ normal $\Leftrightarrow S, T$ diag.

por hipótesis $S \circ T = T \circ S$, entonces
por un ejercicio del práctico $\exists \checkmark$

$$\langle u, v \rangle = \|u\| \|v\| \cos \theta$$

$$\langle u, v \rangle' = \langle u, v \rangle$$

$$\langle u, v_0 \rangle = \|u\| \|v_0\| \cos \alpha$$

$$\uparrow \|u\|' = \sqrt{\langle u, u \rangle'}$$

